AFCAC/ICAO Joint Workshop on PBN Implementation

Performance Based Navigation (PBN) in Europe

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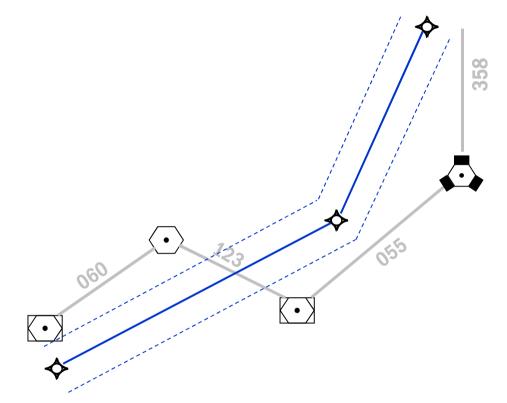
The European Organisation for the Safety of Air Navigation



- Area Navigation
- PBN Concept
- Linking PBN & the rest: Benefits
- European PBN developments
- Implementation Considerations
- Questions



- Is a method of navigation which permits aircraft operation on any desired flight path:
 - within the coverage of stationreferenced NAVAIDS, or
 - within the limits of the capability of self-contained systems, or
 - a combination of these capabilities



Blue line shows ATS route designed using area navigation techniques: without constraints of groundbased NAVAIDs

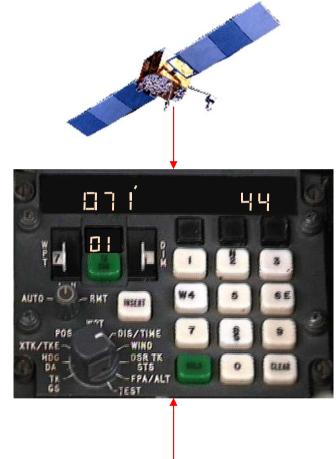
Area navigation is flown using a navigation computer

area navigation is the key enabler for PBN



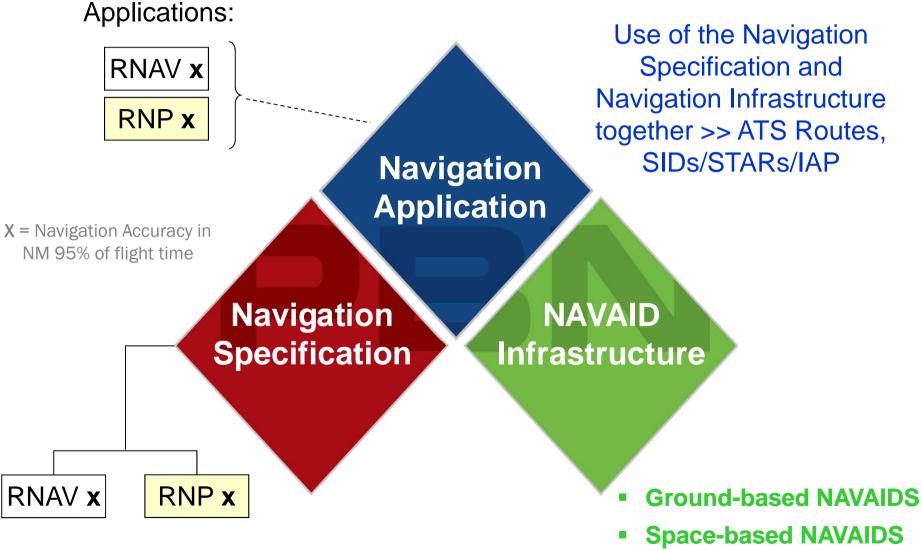
How is Area Navigation Enabled?

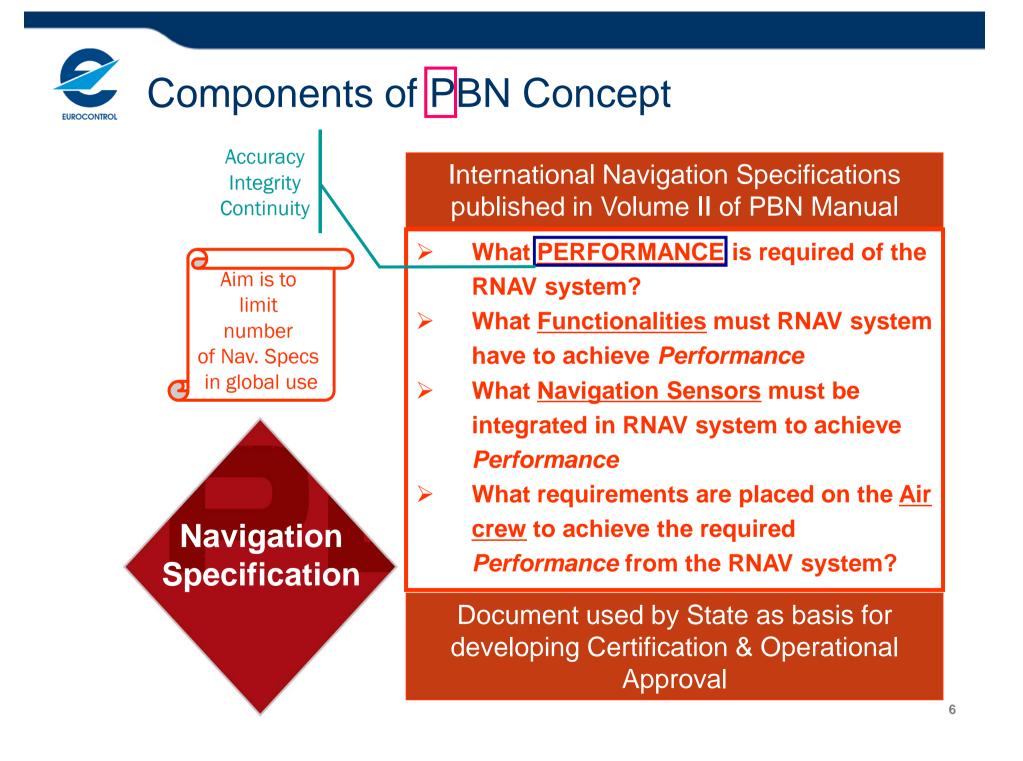
- Through the use of a navigation computer
- Waypoints (co-ordinates) are input into computer
 - Manual entry permitted but limits capabilities
 - Automatically with an integrated database
- Pilot creates route (series of waypoints) i.a.w. flight plan
- Computer estimates position using navigation sensors fitted and compares estimation to defined route
- Deviation between the position and defined path will create guidance information





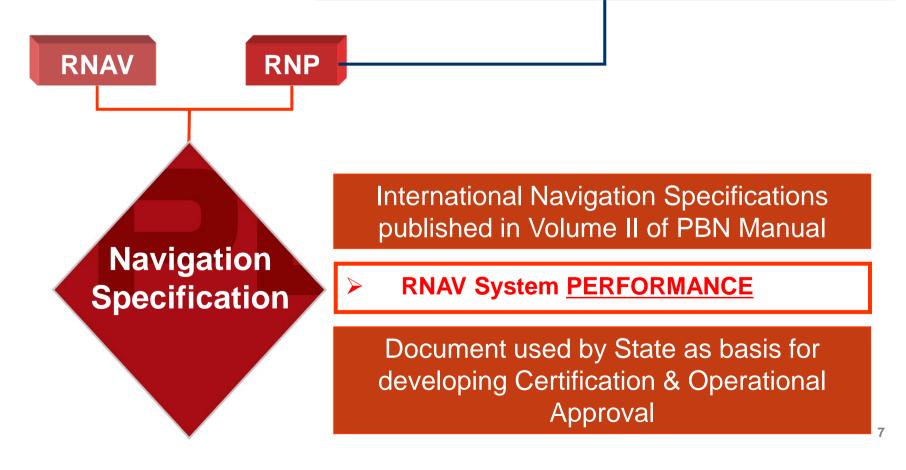






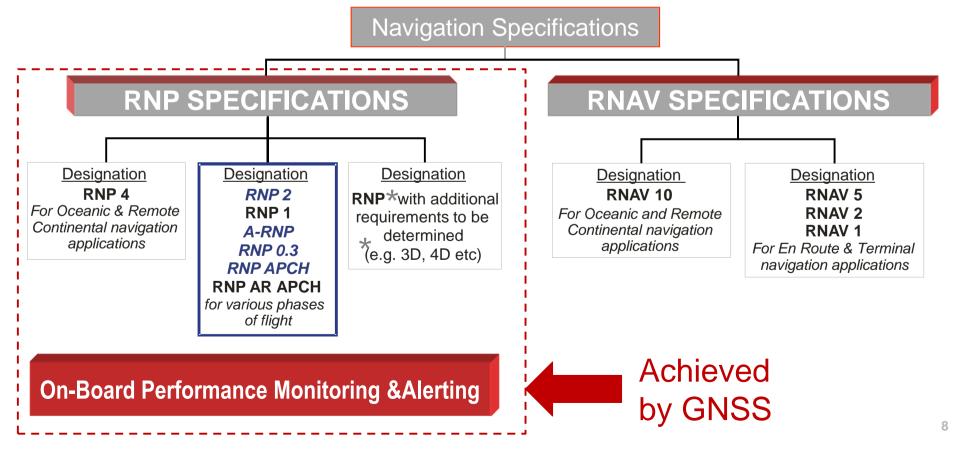








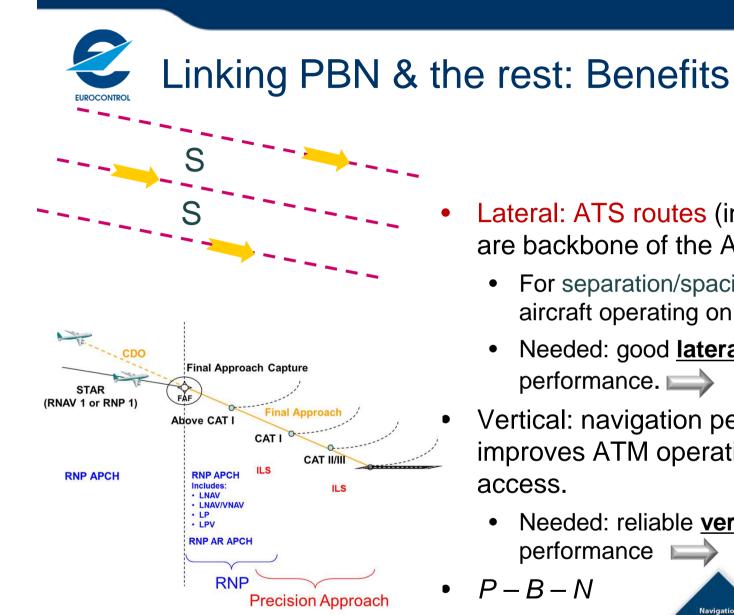
The name of RNAV or RNP specifications for en route and terminal mostly indicates the lateral accuracy requirements 95% of the flight time. E.g. RNAV 1 (1nm either side of track 95% flight time).





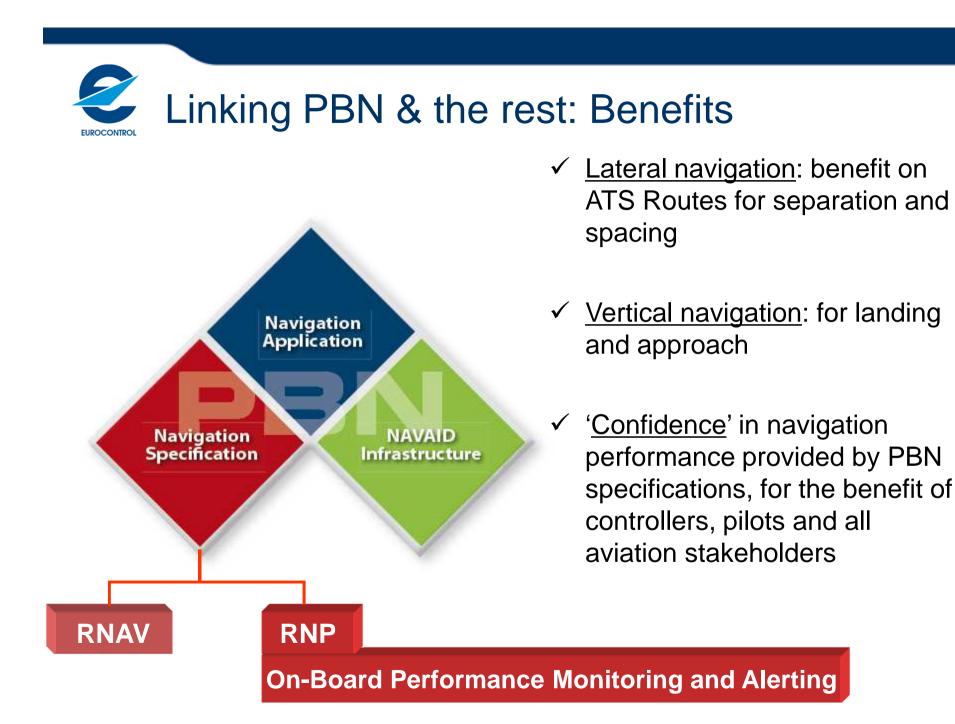
KEY MESSAGE!

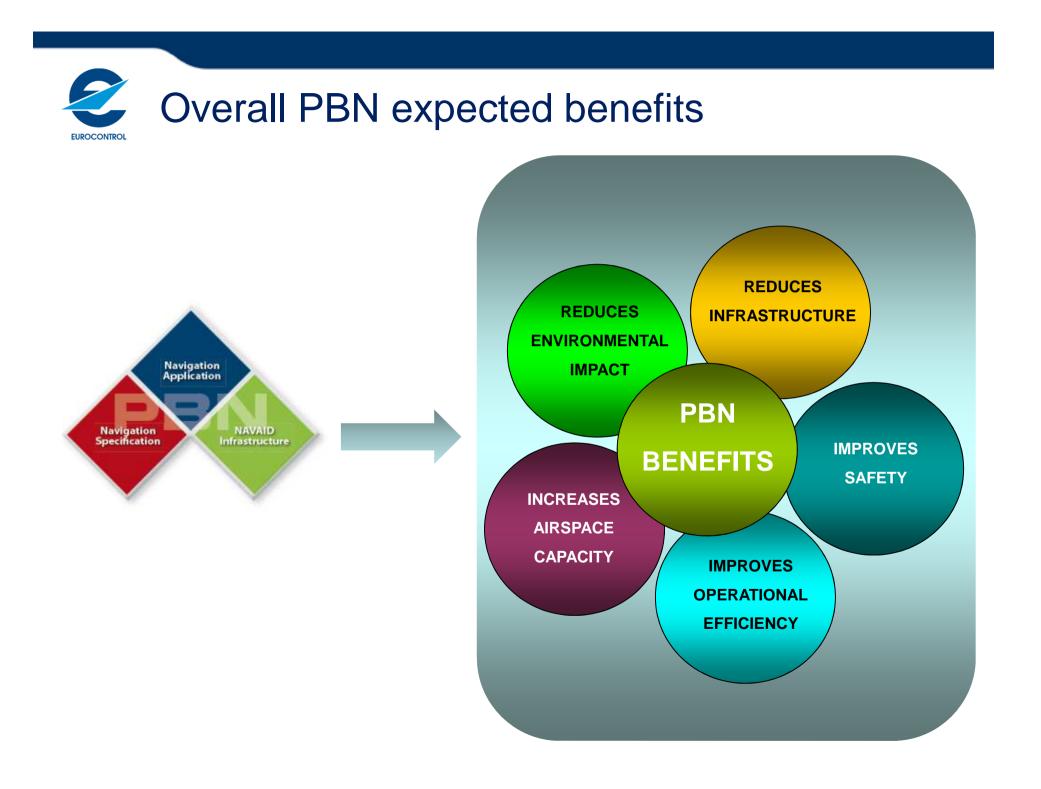
- PBN is a move from sensor to performance based navigation.
- Although PBN uses technology e.g. area navigation system, and navigation sensors e.g. GPS – the concept is **PERFORMANCE** based.
- PBN uses technology to achieve this **PERFORMANCE**.

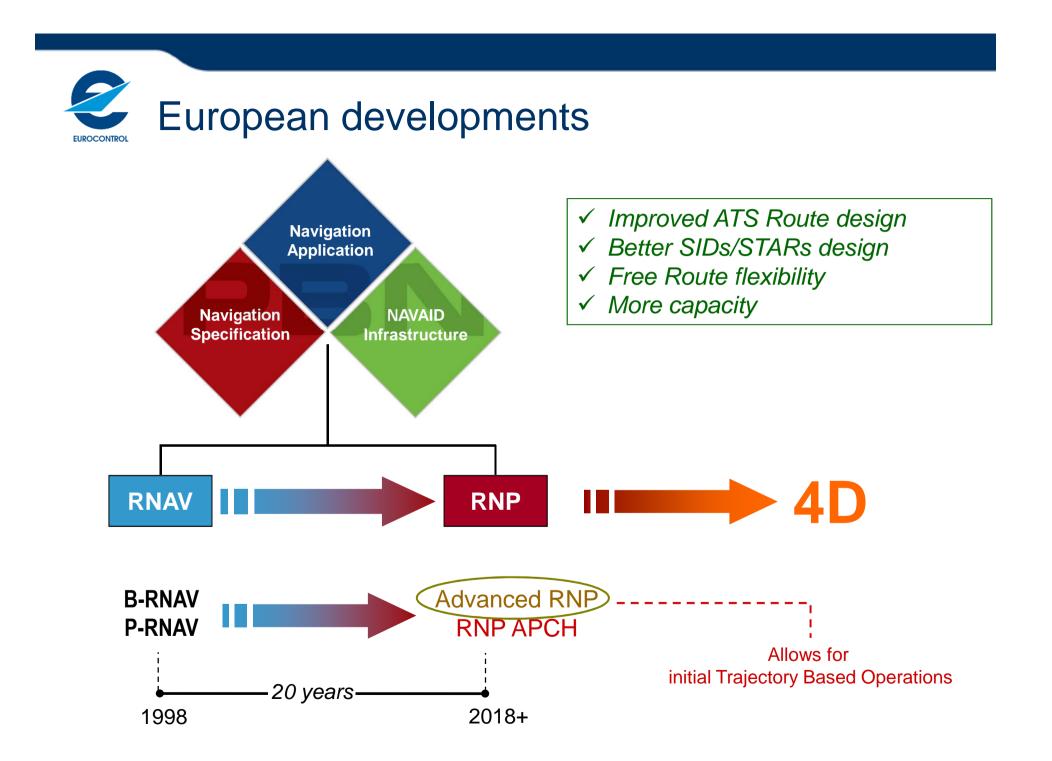


- Lateral: ATS routes (incl. SIDs/STARs) are backbone of the ATM System
 - For separation/spacing, ATC wants aircraft operating on the route centreline.
 - Needed: good *lateral* aircraft navigation performance.
- Vertical: navigation performance also improves ATM operations and airport
 - Needed: reliable vertical navigation









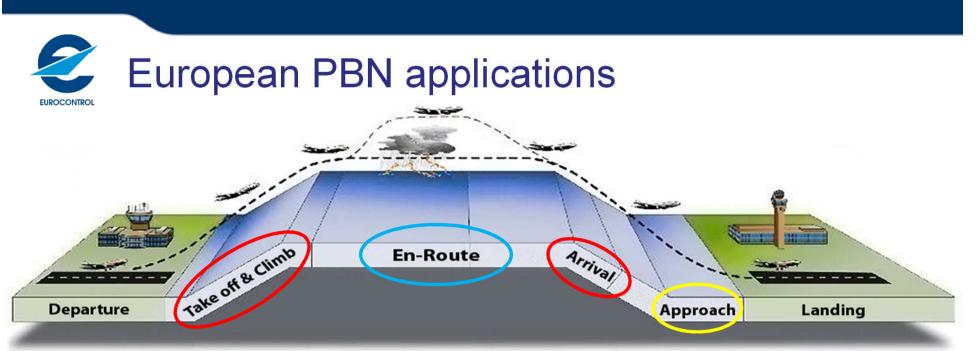


EUROPE'S HIGH-LEVEL AIRSPACE CONCEPT

At a very generic level, Europe's current airspace concept, which extends well beyond PBN, can be said to have the following characteristics:

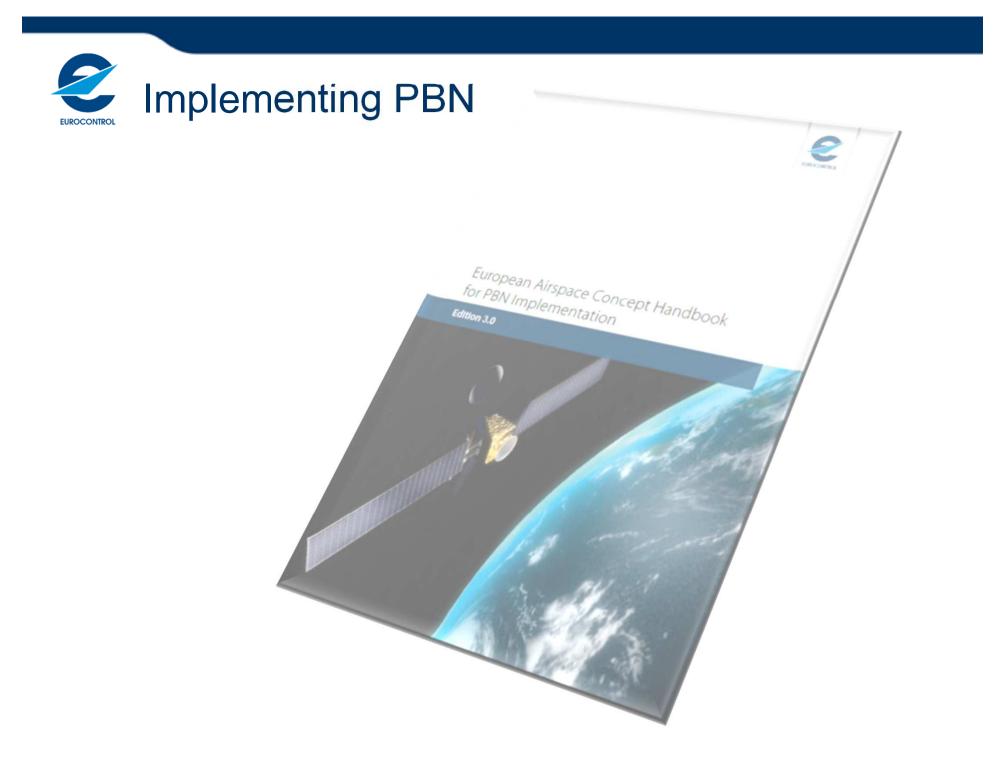
- A parallel network of ATS routes, based on B-RNAV, across the continent;
- A system of feeder or link routes based mainly on B-RNAV which connect to P-RNAV or Conventional SIDs and STARs starting at the nominal TMA boundary
- An organised track system (OTS) in the North Atlantic based on MNPS (this is due to change to RNP 2 or RNAV 10).
- The use of Reduced Vertical Separation Minima (RVSM) between FLs 290 and 410.
- Airspace Classification Class C above FL195.
- Extensive use of the "Flexible Use of Airspace" concept;
- Some use of "Free Routes"
- Evolution from State managed upper airspace to Functional Airspace Blocks (FABs).

Europe's Airspace Concept is evolving to include the use of **Advanced RNP** in en-route and terminal operations, and **RNP APCH** on the Approach.



| Flight Phase | Application | Target Date | Target Date Current Situation Required | | Enabling Systems | |
|--------------------|----------------------------|------------------------------|--|--|------------------------|--|
| En-Route | RNAV 5 (B-RNAV) | 1998 | Mandatory | +/- 5NM (95%) | VOR/DME/ GPS*/ INS* | |
| Arrival/Departure | RNAV 1 (≈ P-RNAV) | 2006+ | Implementation | +/- 1NM (95%) | DME/GPS | |
| | RNP APCH (LNAV) | 2006 | Implementation | +/- 0.3NM (95%) | GPS | |
| Approach (Londing | APV Baro (LNAV/VNAV) | 2008 | Implementation | +/- 0.3NM (95%) | GPS/Baro VNAV | |
| Approach / Landing | APV SBAS (LP/LPV) | 2010 | Implementation | HAL +/- 40m (10 ⁻⁷) VAL +/- 50m (10 ⁻⁷) | GPS + SBAS (EGNOS) | |
| | RNP AR APCH (LNAV/VNAV) | Individual Implementation | Implementation | Depends on required accuracy <0.3NM (95%) | GPS | |

* Not part of PBN

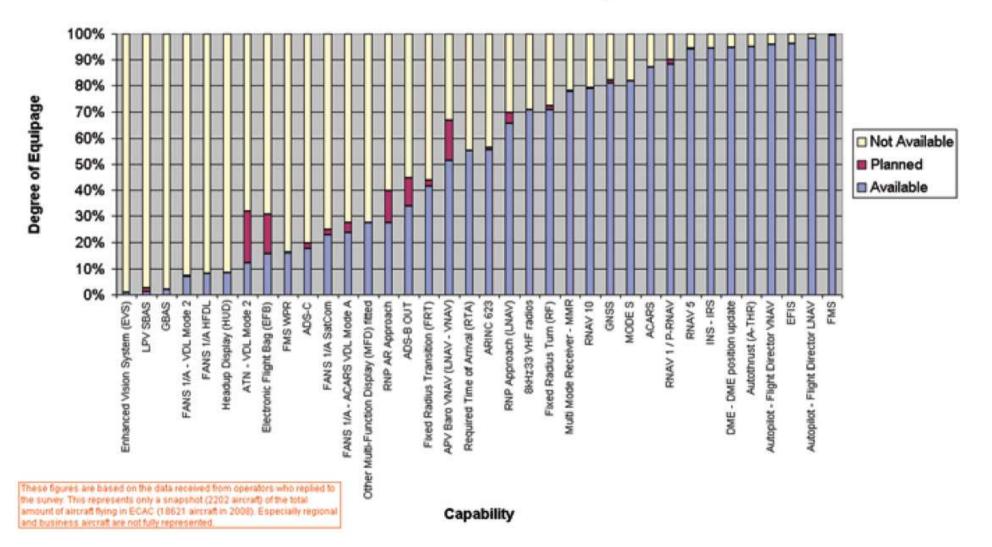




SSA



IATA-EUROCONTROL Avionic Survey Results









LOCAL IMPLEMENTATION ASSESSMENT



<u>Key</u> Assessment Scope Portion of Assessment to be completed at more detailed level (below).



- Why doing it ?
- What to validate?
 - Validate Airspace concept and resulting Procedures
 - Assess if ATM objectives are achieved
 - Confirm flyability of Instrument Flight Procedures
 - Identify possible problems and develop mitigations
 - Provide evidence design is safe
 - Validation is an ongoing process

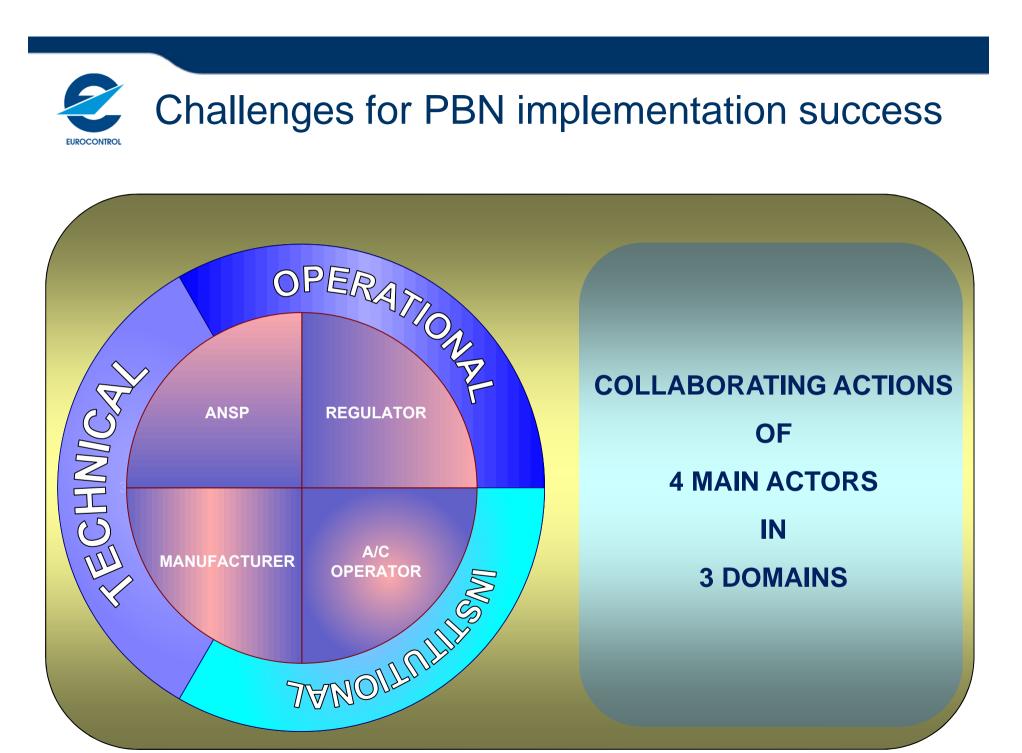
Act. 13a-13b: Procedure Validation

- Ground Validation
 - Obstacle clearance
 - Charting
 - Coding
 - Flyability
- Flight Validation
 - Obstacle verification (optional)
 - Flyability (workload, charting, manoeuvring)
 - Infrastructure
- Database Validation

Act. 15: Awareness and Training

- Success relies on good understanding
- Must address all involved stakeholders
- Nav Specs provide training requirements for:
 - Flight Crew
 - ATCos
- Must be timely but not rushed
- Use Implementation team as 'champions'





Challenges for PBN implementation success

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| → regulation settlement | → costs |
|-----------------------------------|---------|
| → consultation | |
| → timeline | |
| Coordination & overall monitoring | |
| → human factors | |

- \rightarrow PBN enablers availability
- $\stackrel{\bigcirc}{\mapsto}$ \rightarrow readiness for development and deployment
- ▶ synchronisation between actors (A/C operators / manufacturers / ANSPs / regulator)
- $\stackrel{\square}{\cong}$ \rightarrow clear statements on conventional Navaids continuation / discontinuation
- + technical solutions for all the community (GA / BA / Airlines / State Aircraft / RPAS ?)
- 0 \rightarrow procedures P → aircraft equipage R \rightarrow training T \rightarrow air space design 0 → anticipation A





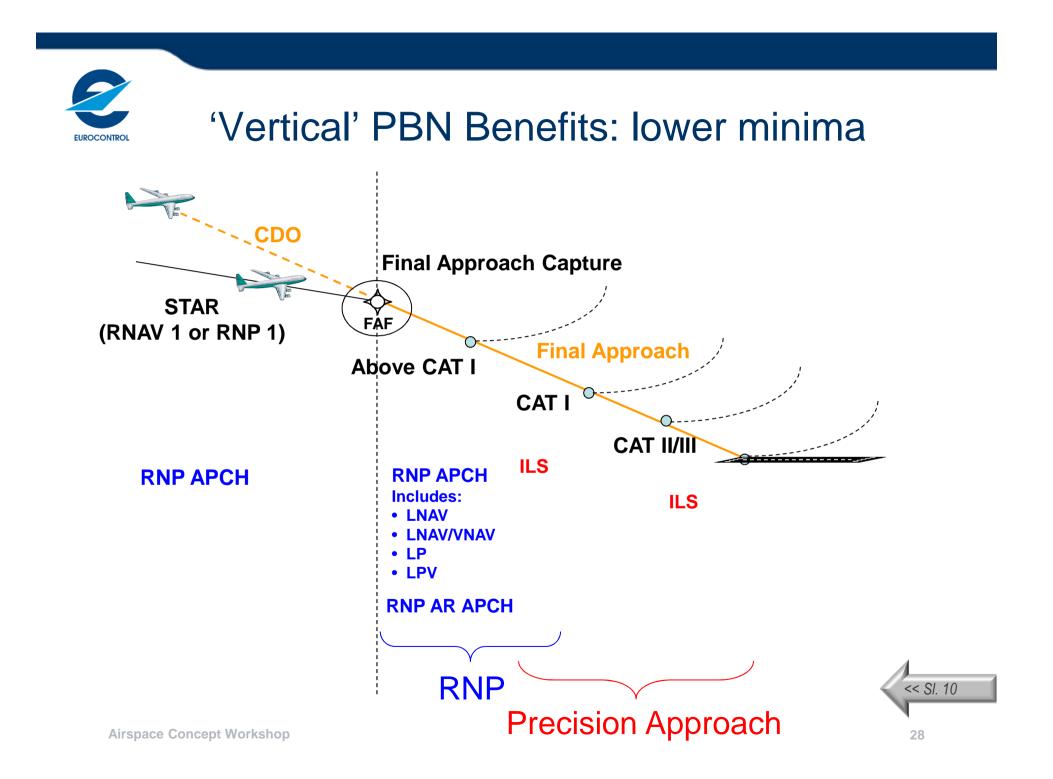


EXTRA SLIDES

Potential capacity benefit of PBN

| | Advanced RNP | | P-RNAV | | B-RNAV |
|--------------------------------|---|----------|----------------------------------|----------|---|
| | En-route | Terminal | En-route | Terminal | En-route |
| Same Direction | | 7 NM | 9 NM | 8 NM | 16.5 NM |
| Opposite Direction | 7 NM | | | | 18 NM |
| Other | | | | | 10-15 NM with increased ATC intervention rates |
| Spacing on turning segments | As above using FRT en-route and RF for SIDs/STARs | | Larger than above because no FRT | | Much larger than above because no automatic leg change. |

How is the air traffic affected if there is an area outage of GPS?
 e.g. Unplanned outage due to jamming, space weather?



APV – APproaches with Vertical Guidance

- There are various ways to complete the final approach phase of flight
 - ILS
 - MLS
 - GLS (GBAS) • RNP

APV is here

- Each kind of approach has different minima
 - How low can you go? ...DH/MDH...
- In this phase of flight effort aims to ensure <u>sufficient</u> <u>confidence</u> in space/air/ground systems to improve safety and permit the *lowest* minima for the *worst* metconditions.

APV – APproaches with Vertical Guidance

 RNP APCH **GPS** Lateral Lateral + Vertical SBAS Lateral Lateral + Vertical RNP AR

Lateral + Vertical (+ curved)



EUROCONTROL

APV – APproaches with Vertical Guidance

- RNP APCH
 - GPS
 - Lateral LNAV
 - Lateral Vertical LNAV/VNAV
 - SBAS
 - Lateral LP
 - Lateral Vertical LPV
- RNP AR (Required)
 - Lateral Vertical



