





FDA Limits - Content

- 1 How Data is recorded?
- 2 Which parameters to record?
- 3 What does recorded Data look like?
- 4 How to make it readable in an FDA software?





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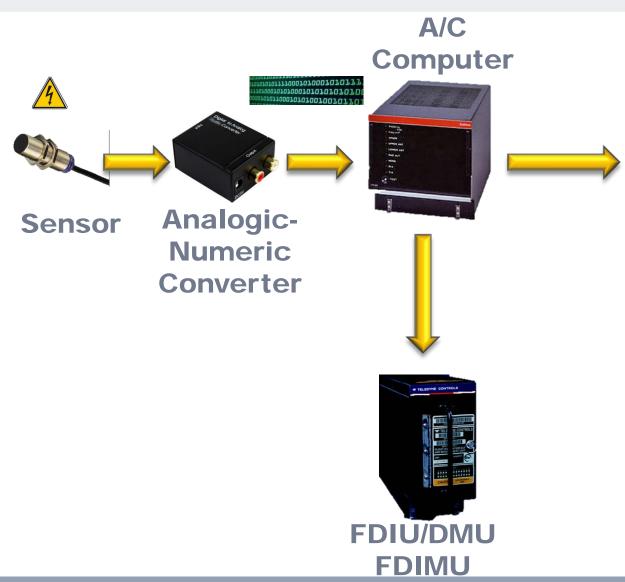
Flight Data Recorders (FDR) or Digital Flight Data Recorders (DFDR) are dedicated to accident investigation.

Flight Data Analysis programs extract data from easily accessible Quick Access Recorders (QAR).









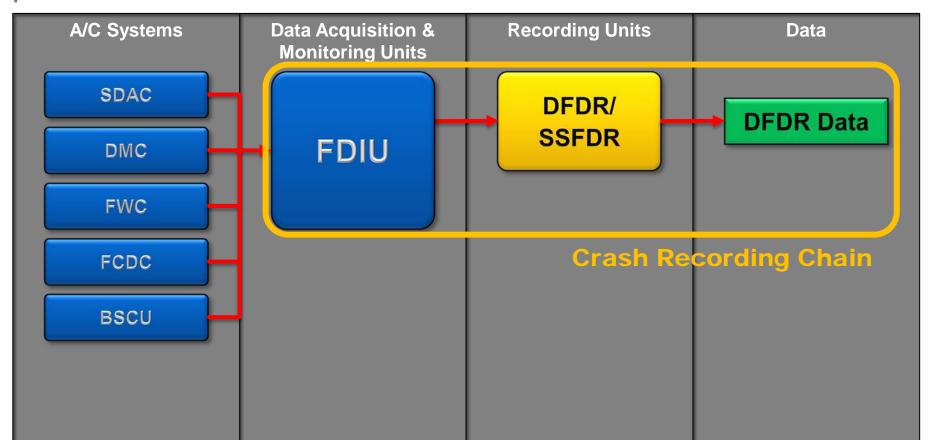


A/C Systems





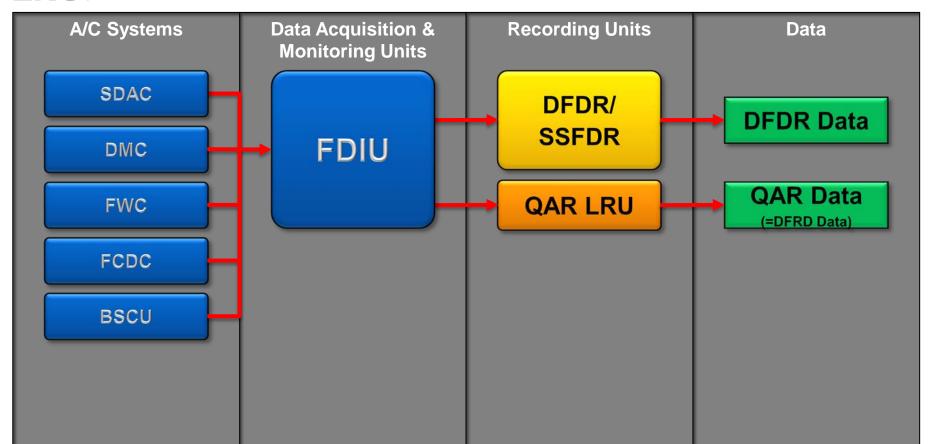
The **FDIU** (Flight Data Interface Unit) is in charge of picking parameters on the **A/C ARINC network**.







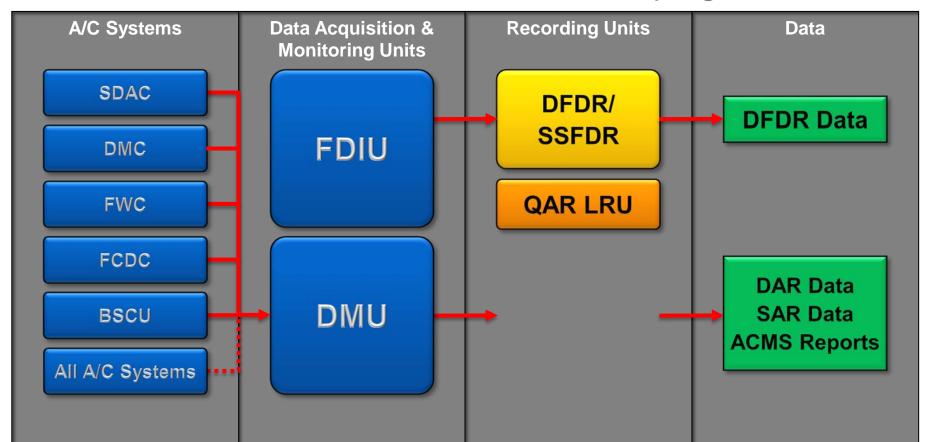
The FDIU provides the **same** Data to the **DFDR** and to a **QAR LRU**.







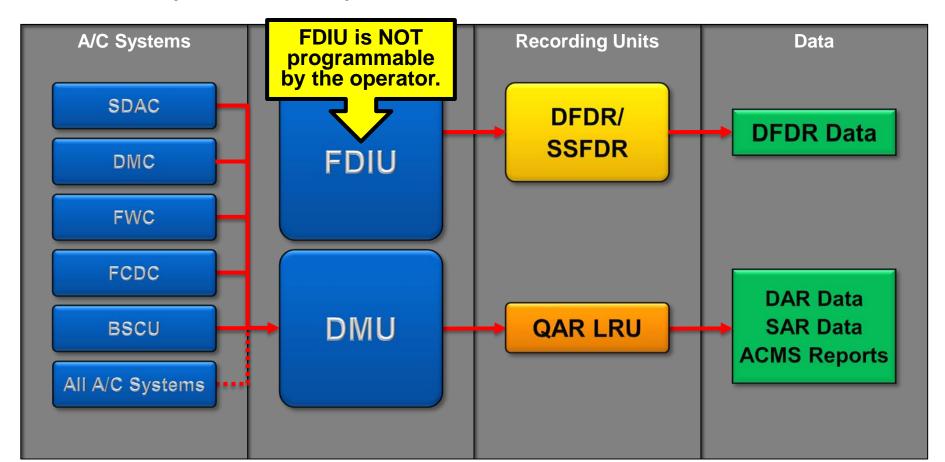
DAR Data stands for **D**igital **A**CMS **R**ecorder Data **DAR** Data and **QAR** Data are used for FDA program.







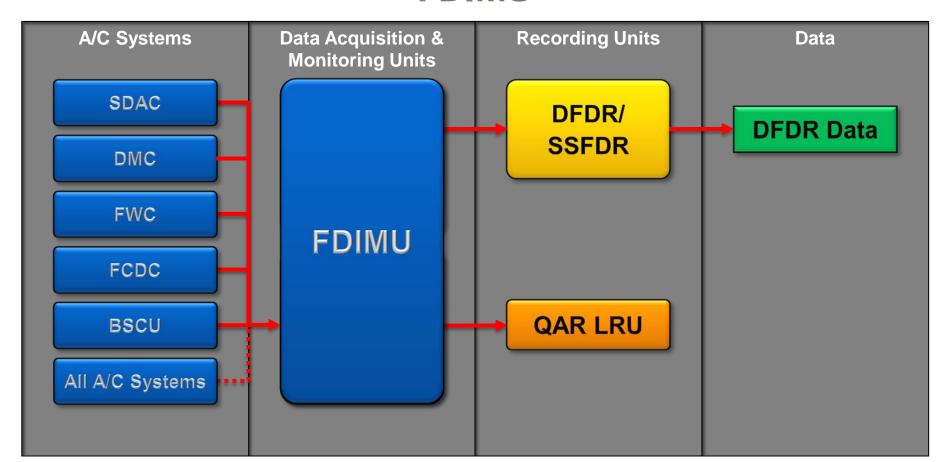
DMU can be programmed by an operator to record any convenient parameters provided available on the ARINC network.





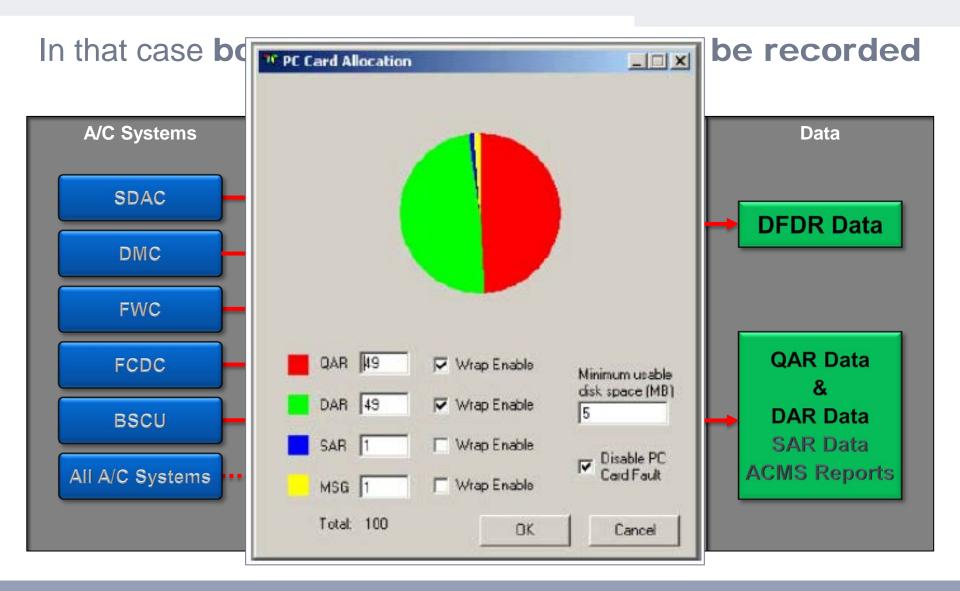


FDIU and DMU are often combined into a single equipment: FDIMU











Different Recording Systems

- ➤ Different Data Files
 - ➤ Different decoding programs

Different Parameter Sources

➤ Different raw parameter gross values

Homogeneity Issue



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FDA Limits -

Regulation



Table A8-1. Parameter Guidance for Crash Protected Flight Data Recorders

Serial number	Parameter	Measurement range	Maximum sampling and recording interval (seconds)	Accuracy limits (sensor input compared to FDR read-out)	Recording resolution
1	Time (UTC when available, otherwise relative time count or GPS time sync)	24 hours	4	±0.125% per hour	l second
2	Pressure-altitude	-300 m (-1 000 ft) to maximum certificated altitude of aircraft +1 500 m (+5 000 ft)	1	$\pm 30 \text{ m to } \pm 200 \text{ m}$ ($\pm 100 \text{ ft to } \pm 700 \text{ ft}$)	1.5 m (5 ft)
3	Indicated airspeed or calibrated airspeed	95 km/h (50 kt) to max V _{So} (Note 1) V _{So} to 1.2 V _D (Note 2)	1	±5% ±3%	l kt (0.5 kt recommended)
4	Heading (primary flight crew reference)	360°	1	±2°	0.5°
5	Normal acceleration (Note 3)	-3 g to +6 g	0.125	±1% of maximum range excluding datum error of ±5%	0.004 g
6	Pitch attitude	±75° or usable range whichever is greater	0.25	±2°	0.5°
7	Roll attitude	±180°	0.25	±2°	0.5°
8	Radio transmission keying	On-off (one discrete)	1		
9	Power on each engine (Note 4)	Full range	l (per engine)	±2%	0.2% of full range or the resolution required to operate the aircraft
10*	Trailing edge flap and cockpit control selection	Full range or each discrete position	2	±5% or as pilot's indicator	0.5% of full range or the resolution required to operate the aircraft
11*	Leading edge flap and cockpit control selection	Full range or each discrete position	2	±5% or as pilot's indicator	0.5% of full range or the resolution required to operate the aircraft
12*	Thrust reverser position	Stowed, in transit, and reverse	l (per engine)		
13*	Ground spoiler/speed brake selection (selection and position)	Full range or each discrete position	1	±2% unless higher accuracy uniquely required	0.2% of full range
14	Outside air temperature	Sensor range	2	±2°C	0.3°C
15*	Autopilot/auto throttle/AFCS mode and engagement status	A suitable combination of discretes	1		
16	Longitudinal acceleration (Note 3)	±l g	0.25	±0.015 g excluding a datum error of ±0.05 g	0.004 g
Note.—	The preceding 16 parameters satisfy	the requirements for a Type	II FDR.		
17	Lateral acceleration (Note 3)	±l g	0.25	±0.015 g excluding a datum error of ±0.05 g	0.004 g

n the DFDR



14/11/13 No. 37-A

Regulations on paramaters only concern the DFDR

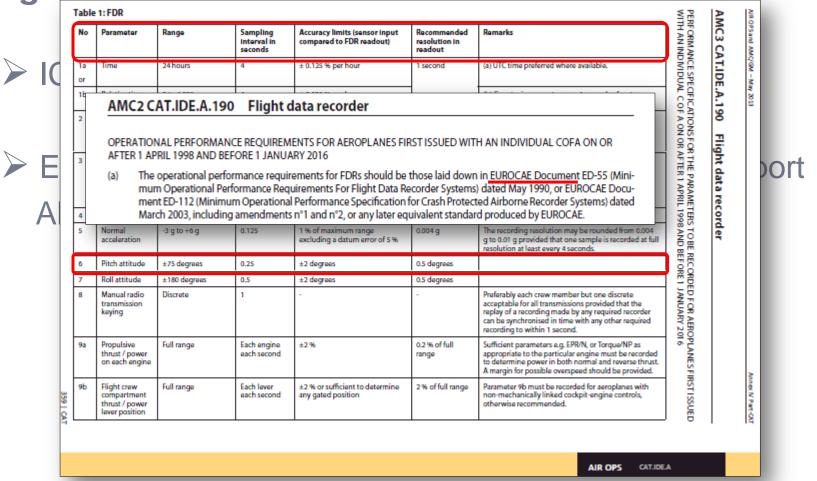






TABLE II-A.1:	PARAMETERS	TO BE RECORDED	- AEROPLANES

N°	Parameter	Minimum Recording Range (refer to para II-A.7)	Maximum recording interval in seconds (refer to para II-A.8)	Recording Accuracy (refer to para II-A.9)	Recording Resolution (refer to para II-A.11)	Remarks
1a	Time	24 hours	4	± 0.125% per hour	1 second	(a) UTC time preferred where available.
or						
1b	Relative Time Count	0 to 4095	4	± 0.125% per hour		(b) Counter increments each 4 seconds of system operation.
1c	GPS Time Sync	Discrete	4			(c) To establish whether the aircraft clocks are synchronised to GPS time
2	Pressure Altitude	- 1 000 ft to	1	±100 ft to ±700 ft	5 ft	Refer to paragraph II-A.6.1
		maximum certificated altitude of aircraft + 5 000 ft		Refer to Table II-A.3		
3	Indicated Airspeed or Calibrated Airspeed	50 kt or minimum value from installed pitot static system to Max V _{S0}	1	±5%	1 kt (0.5 kt recommended)	Refer to paragraph II-A.6.1
		Max V _{so} to 1.2 V _D		± 3%		
4	Heading (Primary flight crew reference)	0 - 360 degrees and discrete 'true' or 'mag'	1	± 2 degrees	0.5 degrees	When true or magnetic heading can be selected, the primary heading reference, a discrete indicating selection shall be recorded.
5	Normal Acceleration	- 3 g to + 6 g	0.125	± 0.09 g excluding a datum error of ±0.45 g	0.004 g	
6	Pitch Attitude	± 90 degrees	0.25	± 2 degrees	0.5 degree	Accuracy will be apply only within ± 75° range
7	Roll Attitude	± 180 degrees	0.5	± 2 degrees	0.5 degree	For a new aircraft type, an analysis should be performed by the aircraft manufacturer in order to assess if a shorter sampling interval is necessary to capture quick attitude variations in a dynamic sequence.
8	Manual Radio Transmission Keying and CVR/FDR synchronization reference	Discrete(s)	1	-	-	Preferably each crew member but one discrete acceptable for all transmissions provided the CVR/FDR system complies with paragraph 2-1.11 of Section 2 (including ATC/SATCOM communications)



Regulations on paramaters only concern the DFDR

- ➤ ICAO Annex 6 Part I Aereoplanes Chapter 6 Para 6.3 - Appendix 8
- ➤ EASA AIR OPERATIONS Commercial Air Transport AMC CAT.IDE.A.190 Flight Data Recorder
- EUROCAE ED-55 / ED-112 / ED-112 A
 MOPS for Crash Protected Airborne Recorder Systems
- FAR 121.334 Digital Flight Data Recorders

 Appendix M to Part 121 Airplane Flight Recorder Specifications





Airbus adds to these lists, parameters also required by Airbus Flight Safety and Airbus Handling Quality. All these parameters are **mandatory** parameters identified by an **M**.

M06a = Pitch Attitude

On the DFDR data frame there are also parameters recorded on request of Airbus internal stakeholders. They are called **documentary** parameters identified by a **D**.

D09 = Vertical Speed





For the DAR Data Frame there is no regulatory requirement but most of the previous parameters (Mandatory and Documentary) are recorded.

Standard DAR Data Frames exist but they are fully customizable by the operator.

These modifications will obviously affect the final picture of a flight into an FDA software.





More than 100 standards exist (QAR & DAR)

Homogeneity Issue

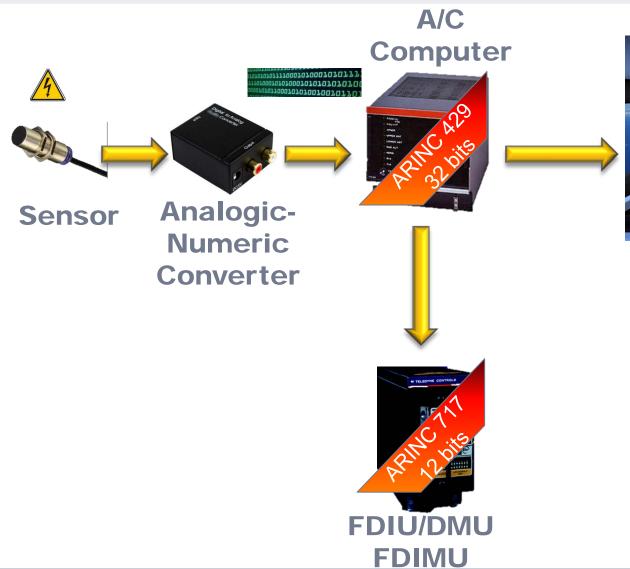


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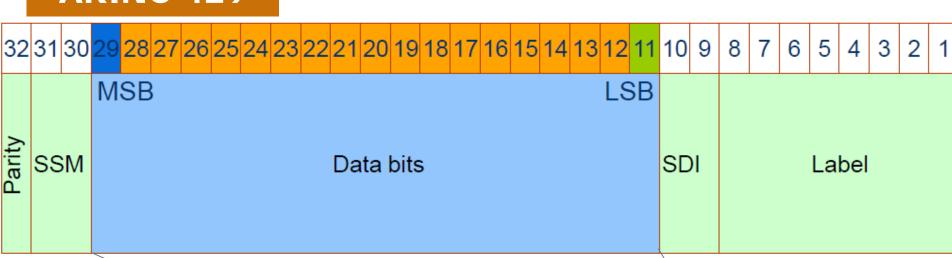


A/C Systems

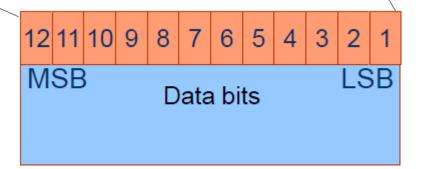




ARINC 429



ARINC 717

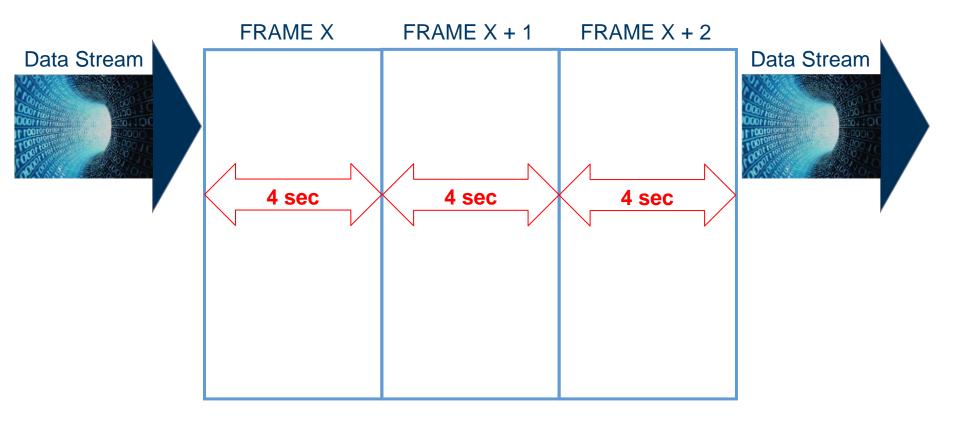






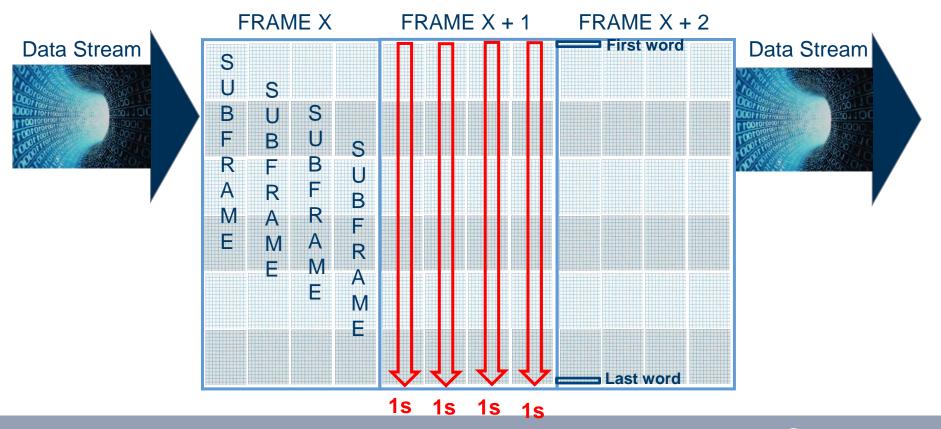
Either the FDIU or the DMU sends continuous Data Blocks containing 4 seconds of flight Parameters.

One block is called a **frame**.





Each Frame is divided into 4 **Subframes**Each subframe lasts 1 second and contains a number of **words**Words are numbered from the beginning to the end of the SF

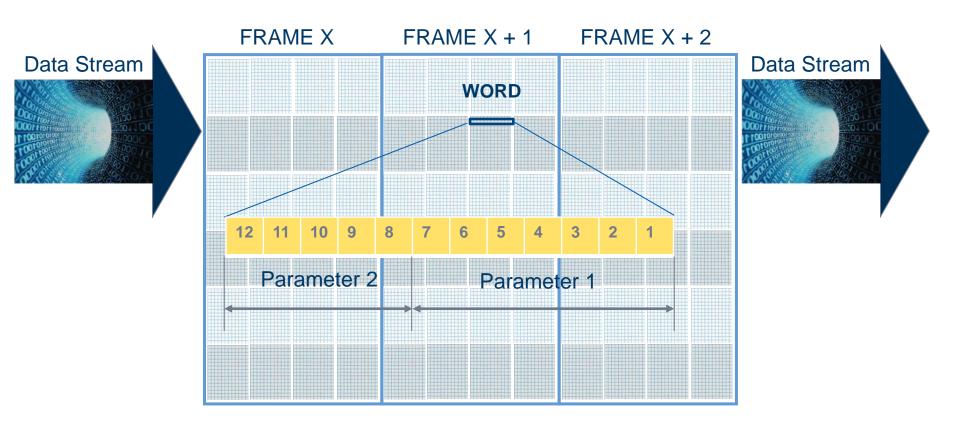






Each word is made of 12 bits.

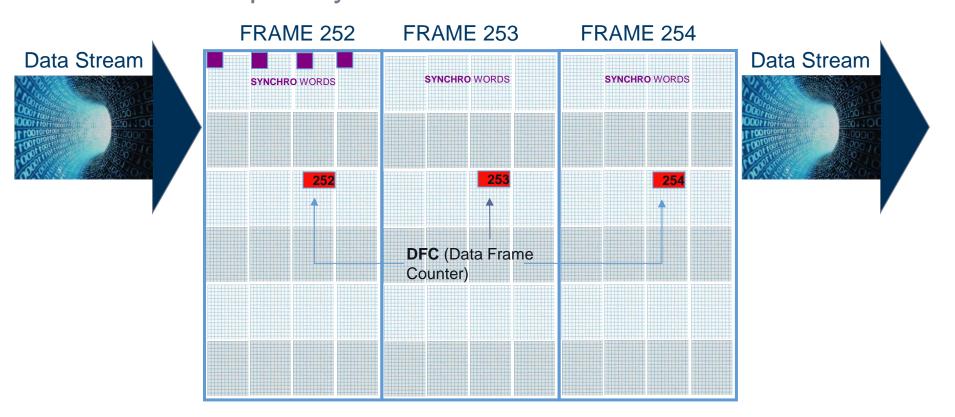
These bits contain the active **parameter data**One word can contain several parameters







The stream is managed by **synchronisation words** and a **data frame counter** which provide the continuous assessment capability on the stream.

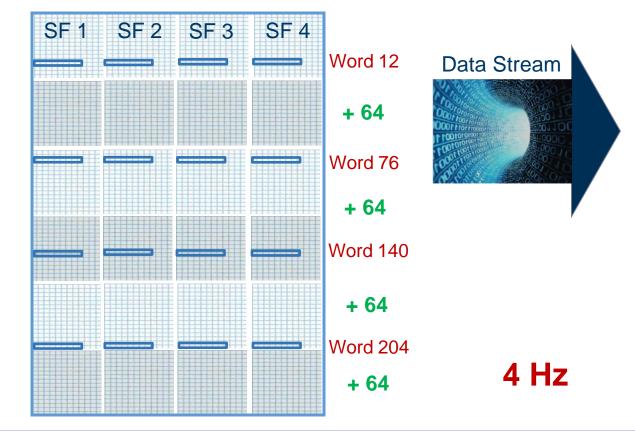




According to its **refreshing rate** parameter can be stored several times in one frame. Done at a **constant pace**.

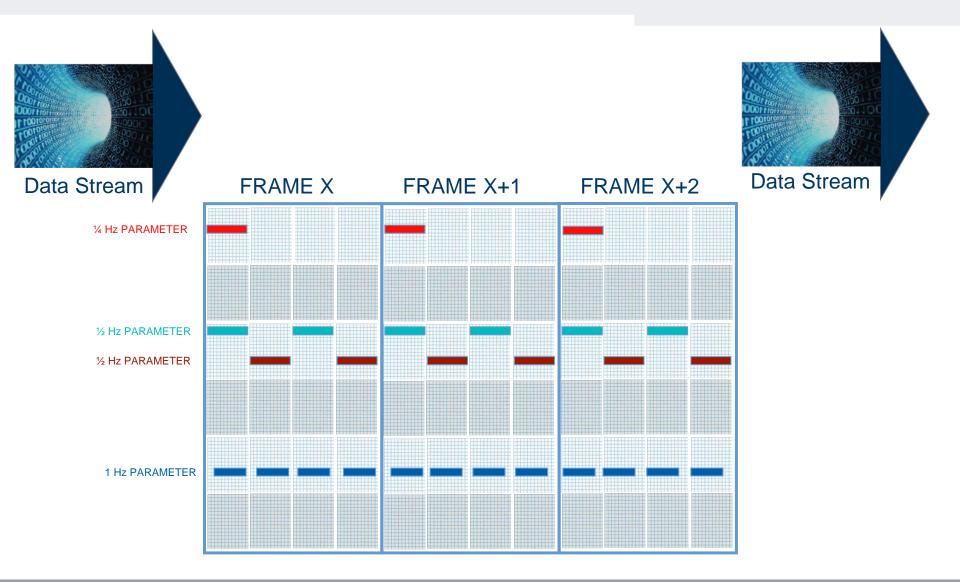


Example : FRAME **256 WPS**













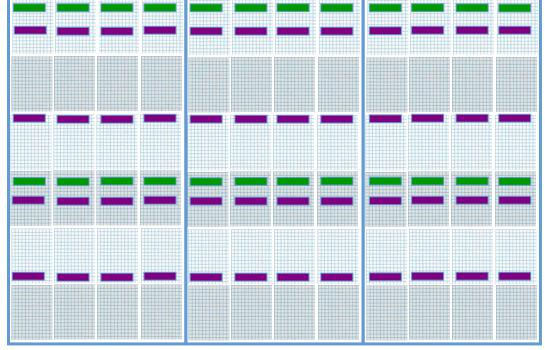


FRAME X FRAME X+1 FRAME X+2

Data Stream

2 Hz PARAMETER

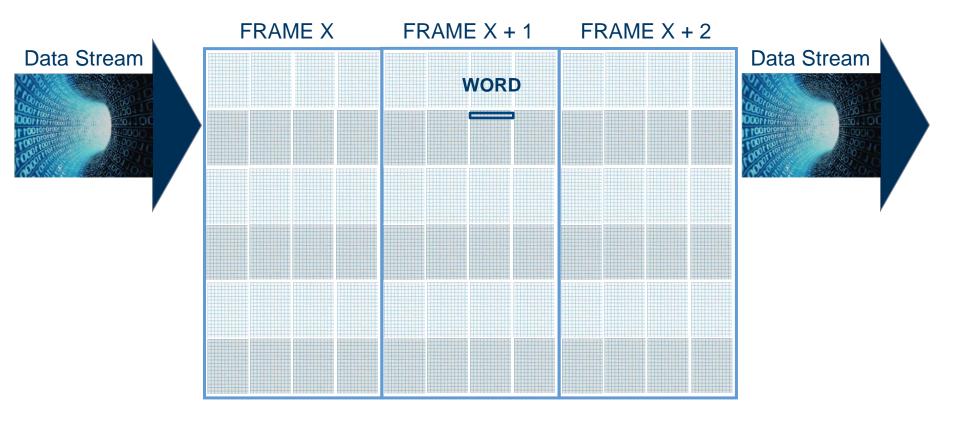
4 Hz PARAMETER



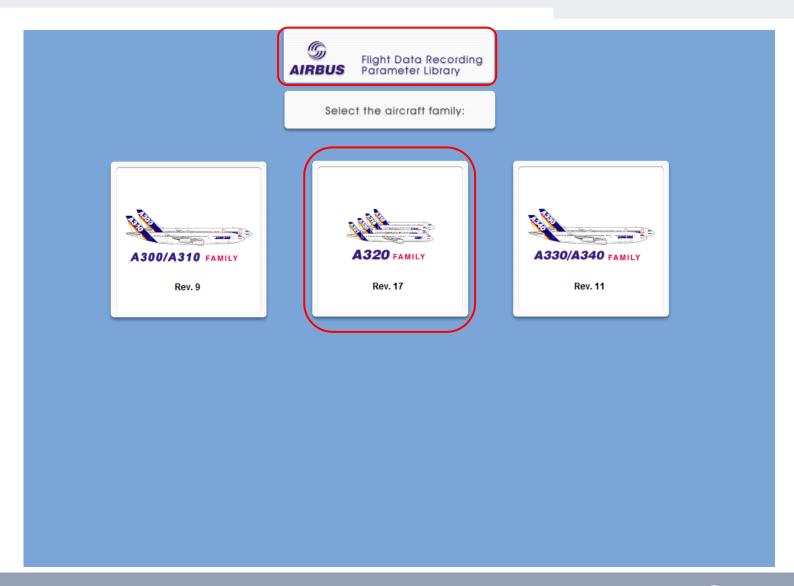


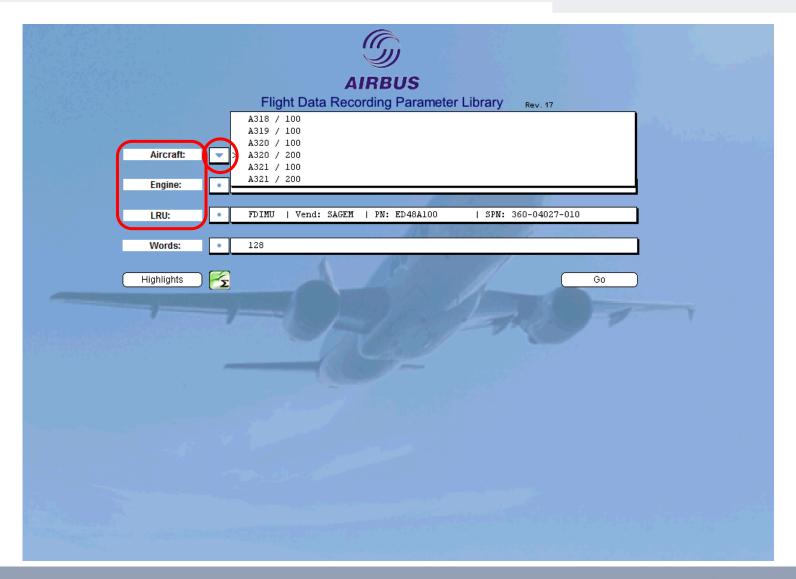


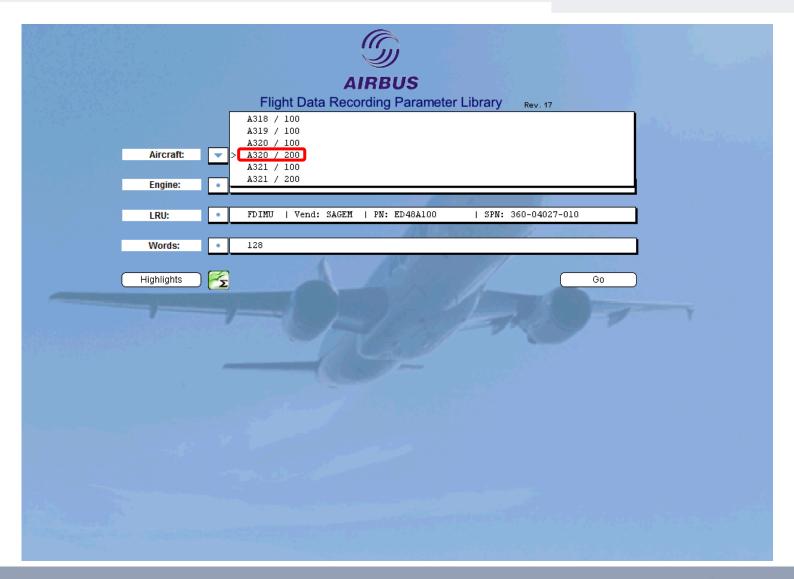
Some words do not need to be recorded on each Frame. They are therefore recorded every **Superframe**.

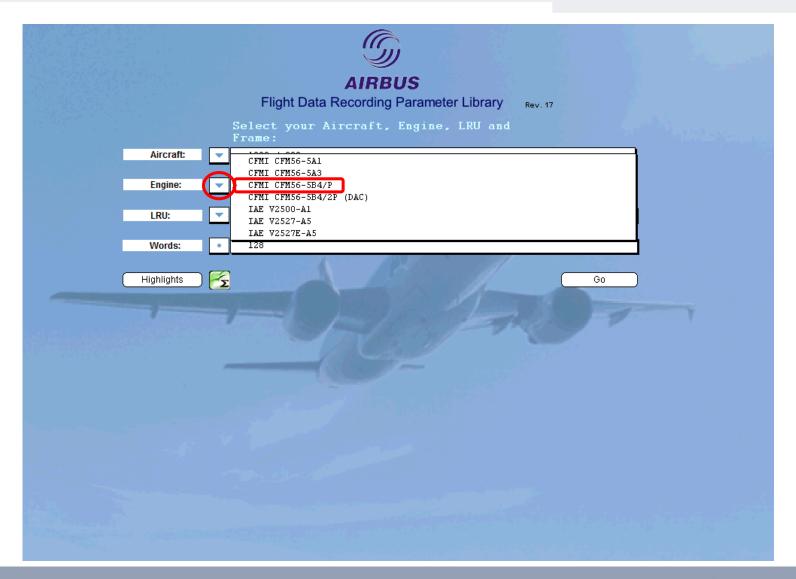


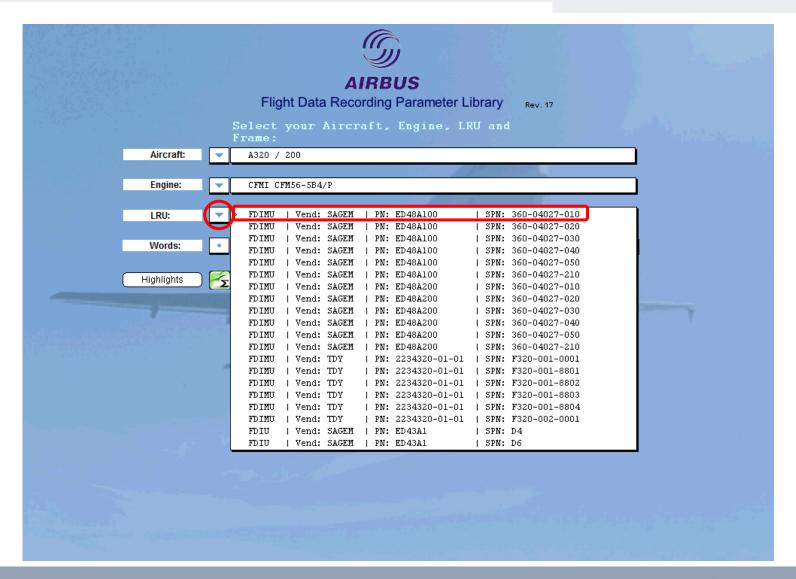


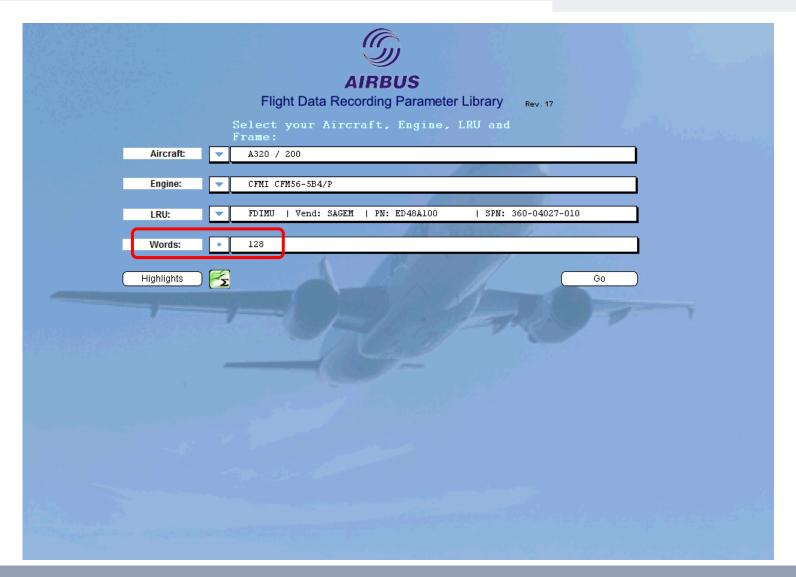




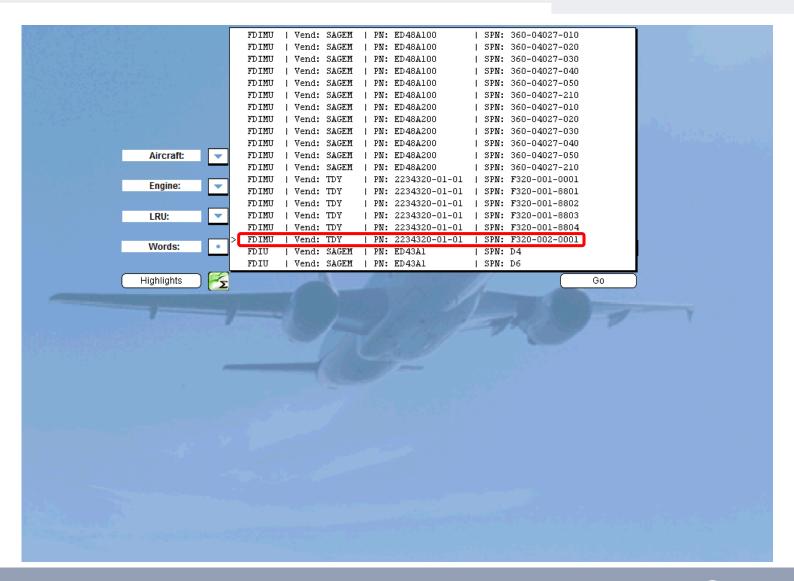




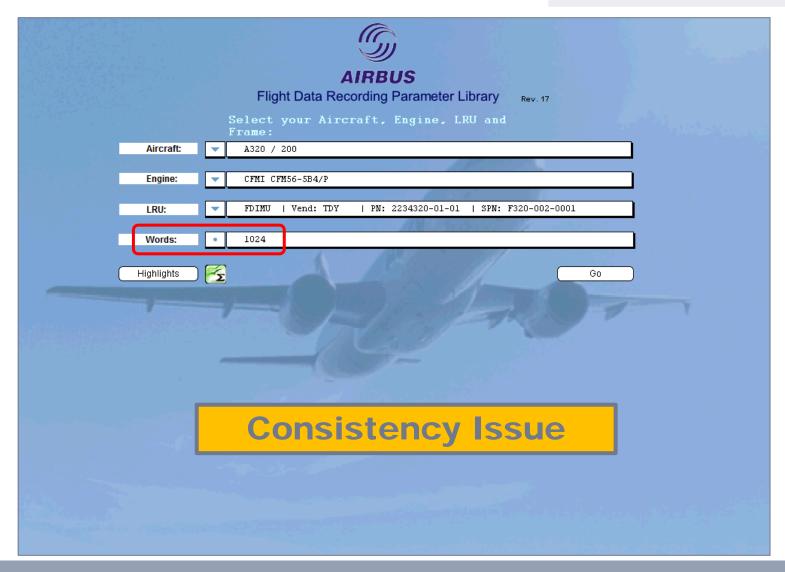




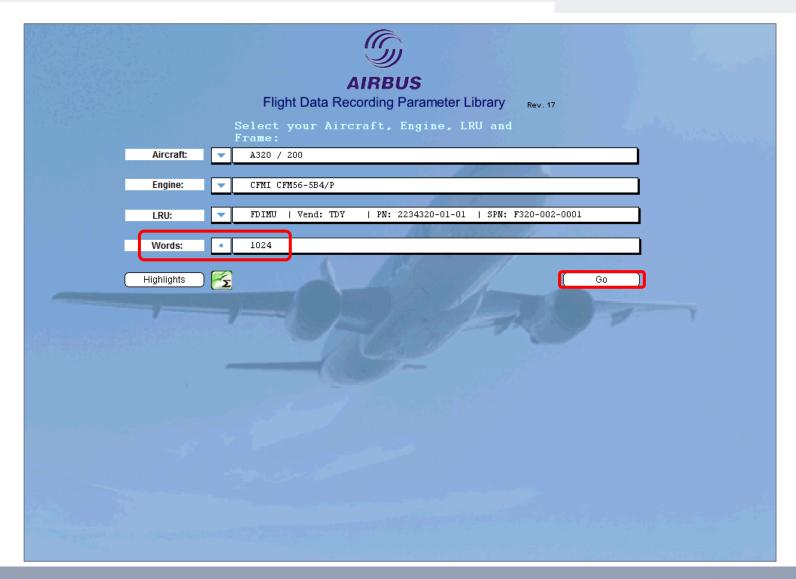


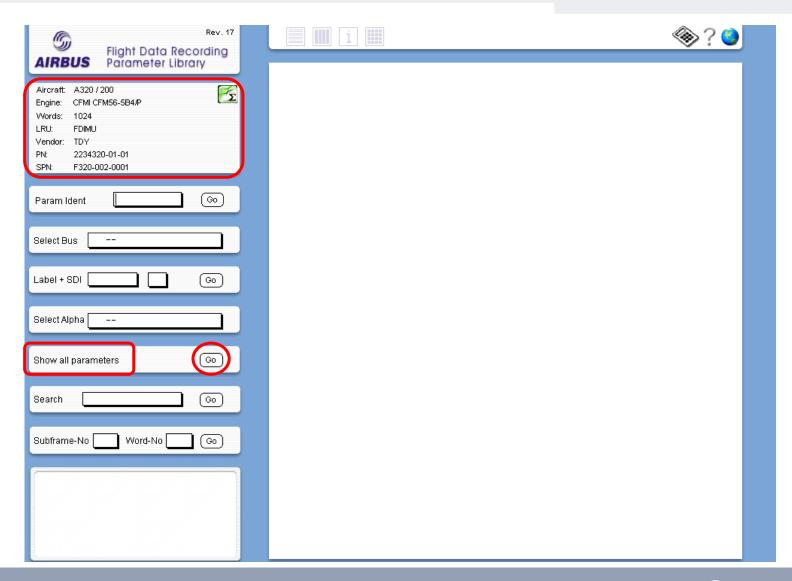




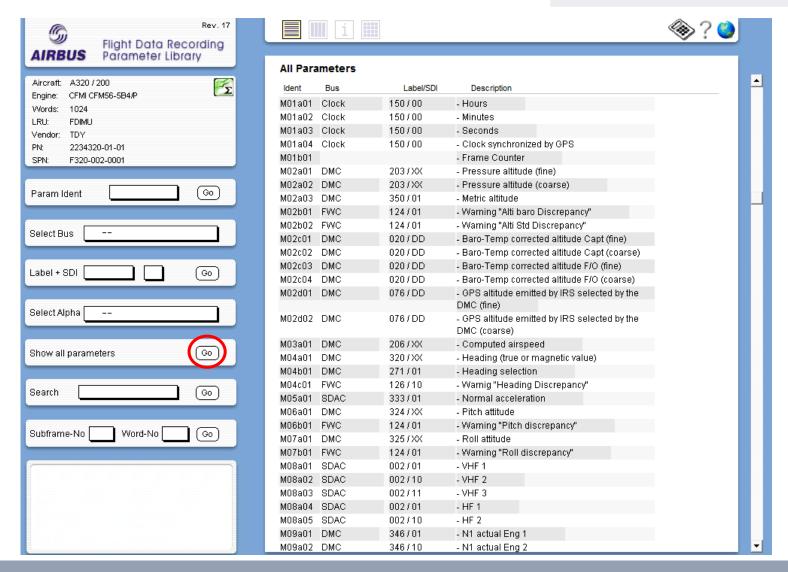




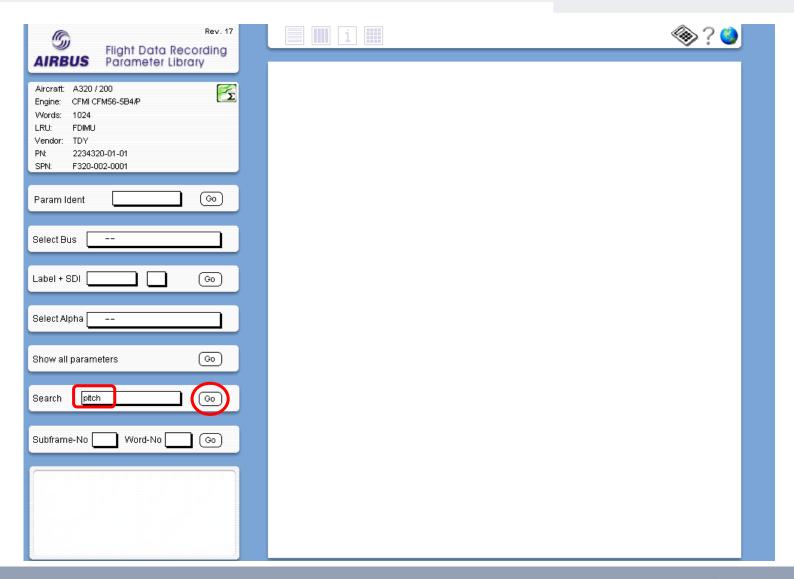


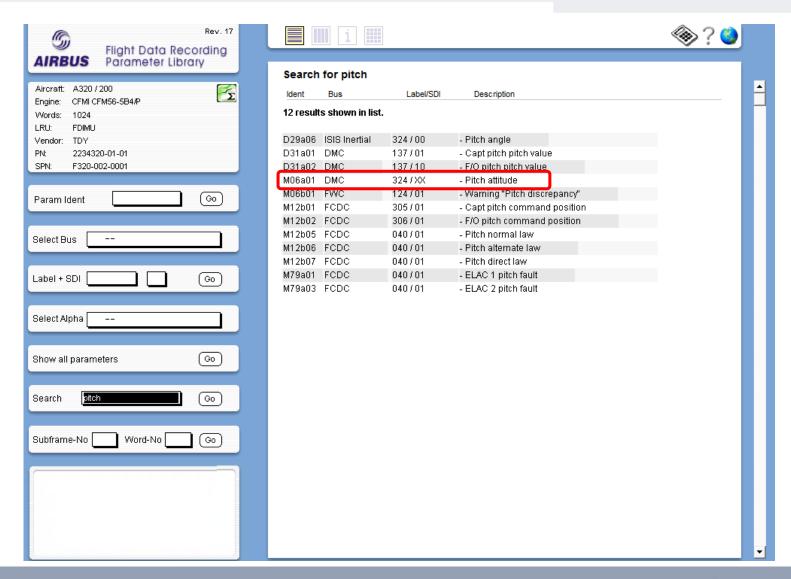




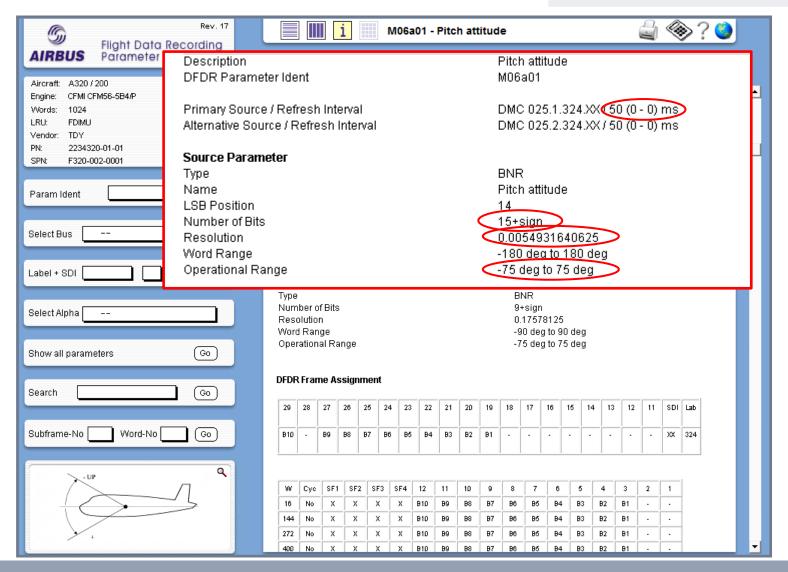






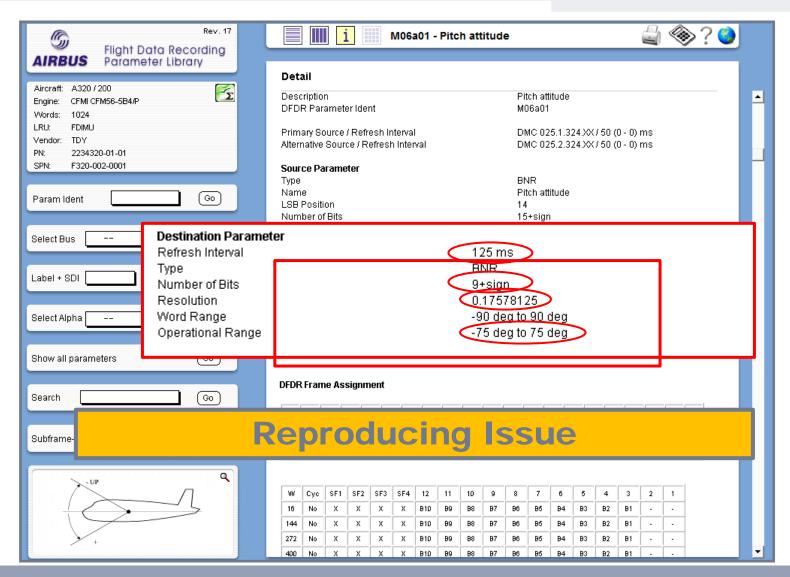














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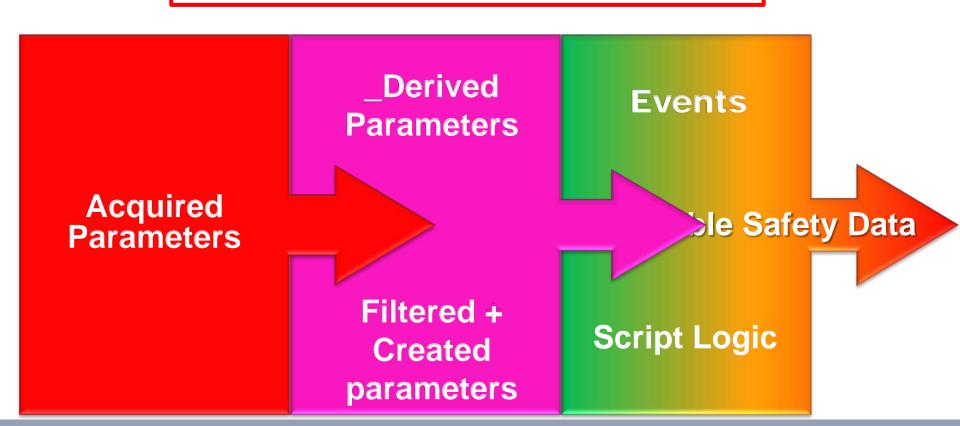
4 How to make it readable in an FDA software?





The Purpose of FDA Tool is to

Identify Non-Desired flight conditions



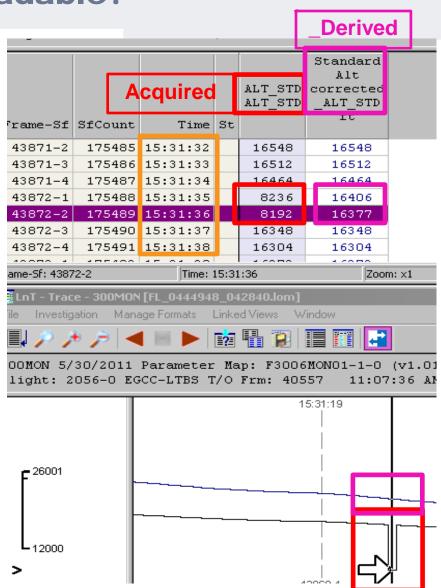




Acquired Parameters must be _Derived to become exploitable

This derivation allows:

Automatic wrong parameter filtering

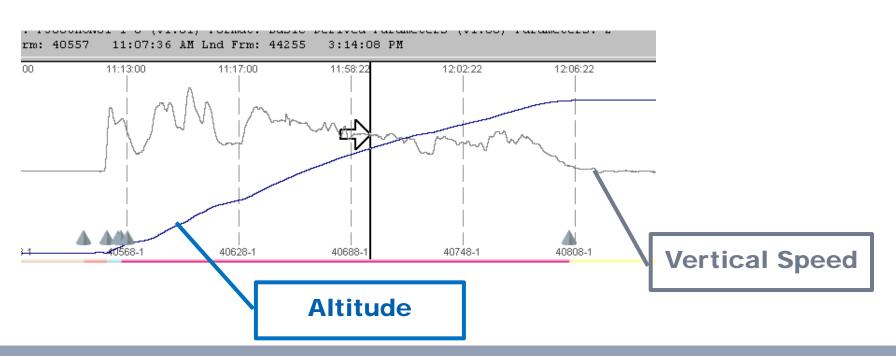






Derivation also allows new parameter development

<u>example</u>: vertical speed derived from altitude







Parameters can be derived rather simply

Boolean Example



0 = FALSE



1 = TRUE

_Derived Parameter = Acquired Parameter



Parameters can be more complex

Binary Example



__Derived Parameter
=
Acquired Parameter x Coefficient
+
Offset

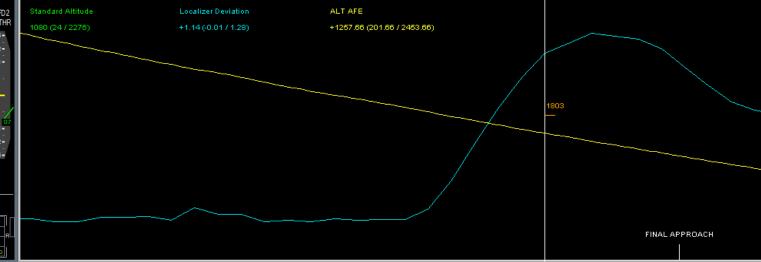




Ex: Deviation from Localizer

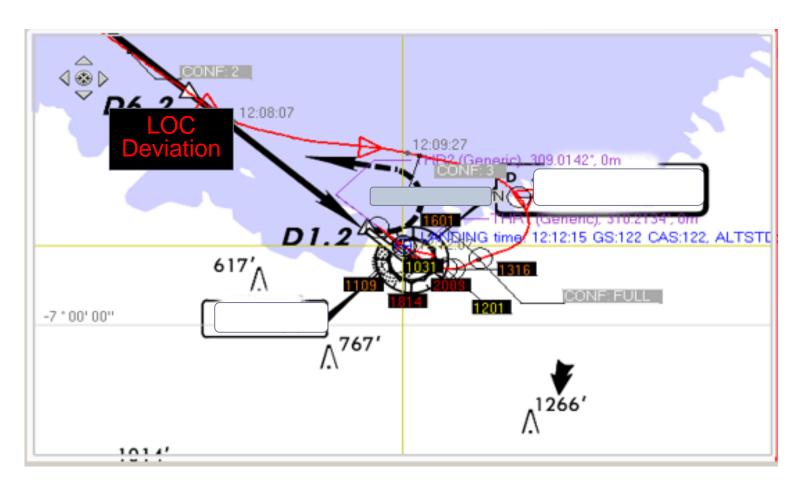
	LOCC >: TOL >= 3s		
A/C Type	LOW	MEDIUM	HIGH
A300-600	0.5 dot	1.0 dot	1.5 dot
A310	0.5 dot	1.0 dot	1.5 dot
A 2 1 0	0.5.4-4	1.0.4-4	1.5.4-4

















Limitation

- Parameter reliability
- Script logic revelency

Solution

- Engineering cleaning
- Operational cleaning

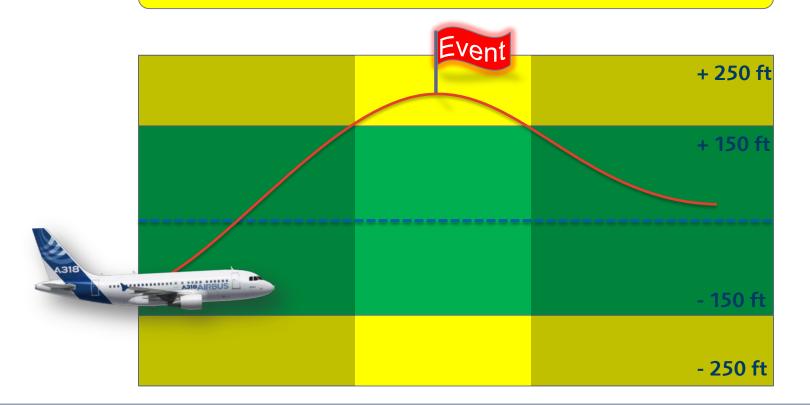
An FDA software is partially DUMB





Ex: Level Bust

Event raised when entering and escaping the zone







Limitation

➤ Inside and Outside Voice messages not available

Solution

> To create a close Link with the reporting system

An FDA software is partially DEAF









Limitation

> No Environmental/Situational Information

Solution

➤ To use any available data, including the reporting system

An FDA software is partially BLIND



FDA Limits - Conclusion

The **FDA tool** is very **powerful**,

Even if it has some limits

It will tell you

WHAT happened,

but not WHY it happened...

An FDA tool needs Human Expertise



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