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Capacity Planning and Assessment

Additional considerations

Air Traffic Services System Capacity Seminar/Workshop
Nairobi, Kenya, 8 – 10 June 2016

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EUROCONTROL Operations Planning



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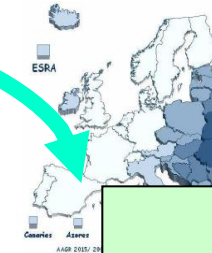
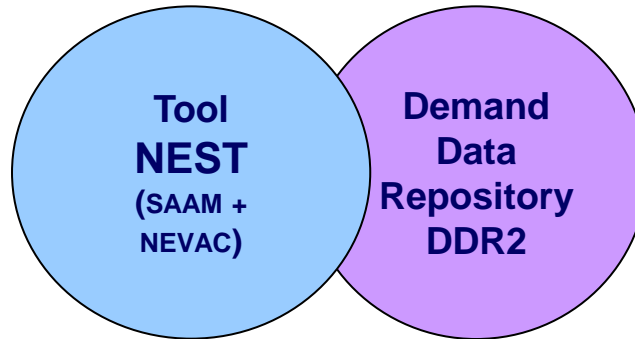


Summary

Capacity Planning

Winter

Annual Performance Analysis - Network Operations Report –(the NOR)
 Consolidation of Plans - Network Operations Plan (the NOP)



Spring

Traffic Forecast
 Network Delay Forecast
 Update NOP


Autumn

Traffic Forecast update
 Traffic Demand and Distribution
 Capacity Requirements and Delay
 Interactive Capacity Planning meetings with ANSPs
 ANSP Plans



Summer

Evaluation of Summer performance
 ACC Capacity Baselines



Assessing sector capacity through controller workload

- Several approaches to workload modelling

Workload self-assessment

Task time models

Traffic/sector complexity models

- Different workload vs.capacity relationships

→ Workload thresholds

- Different assessment process

Numerical Estimates

Fast-time Simulations

Real Time Simulations



Several valid methodologies available

CAPAN



Simulation
Methodology

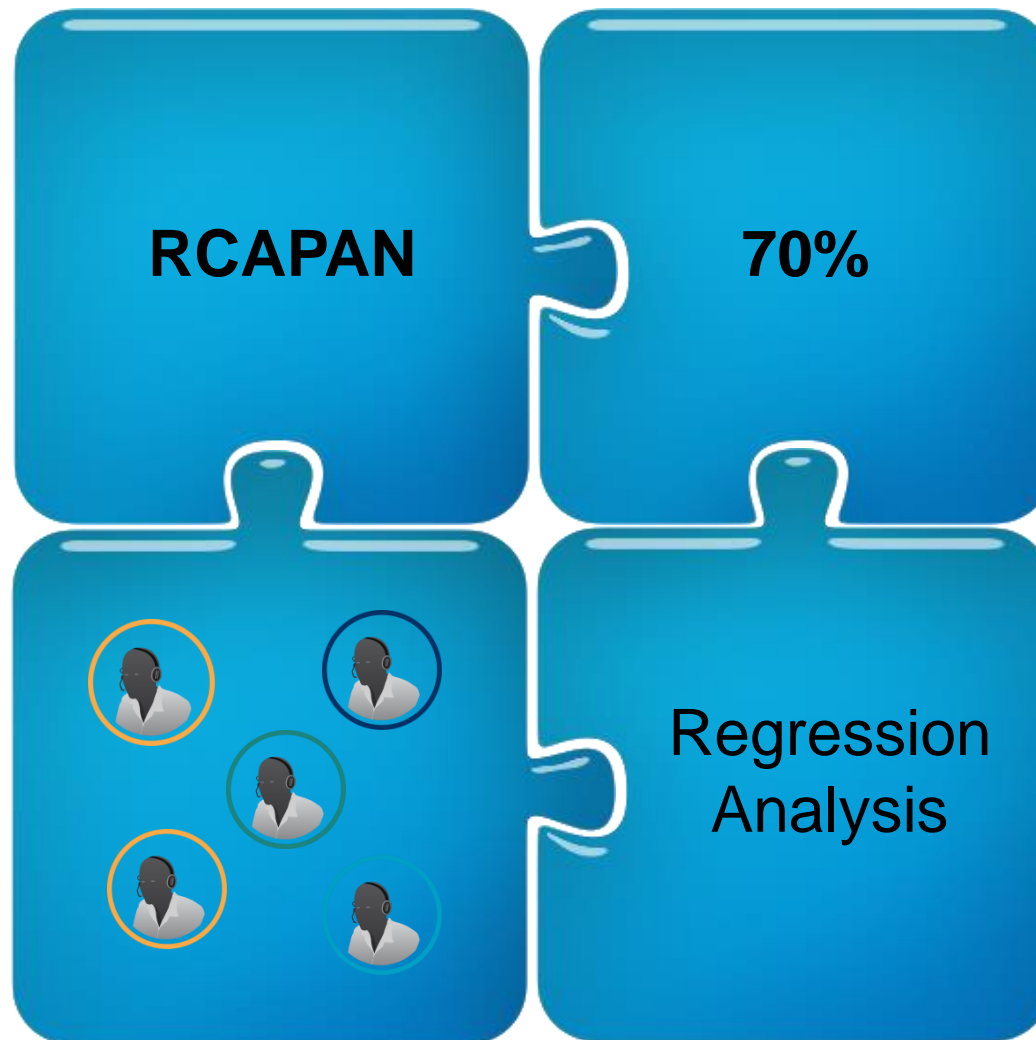
Sector Capacity

Controller Workload

Fast Time Simulation in ATM



CAPAN



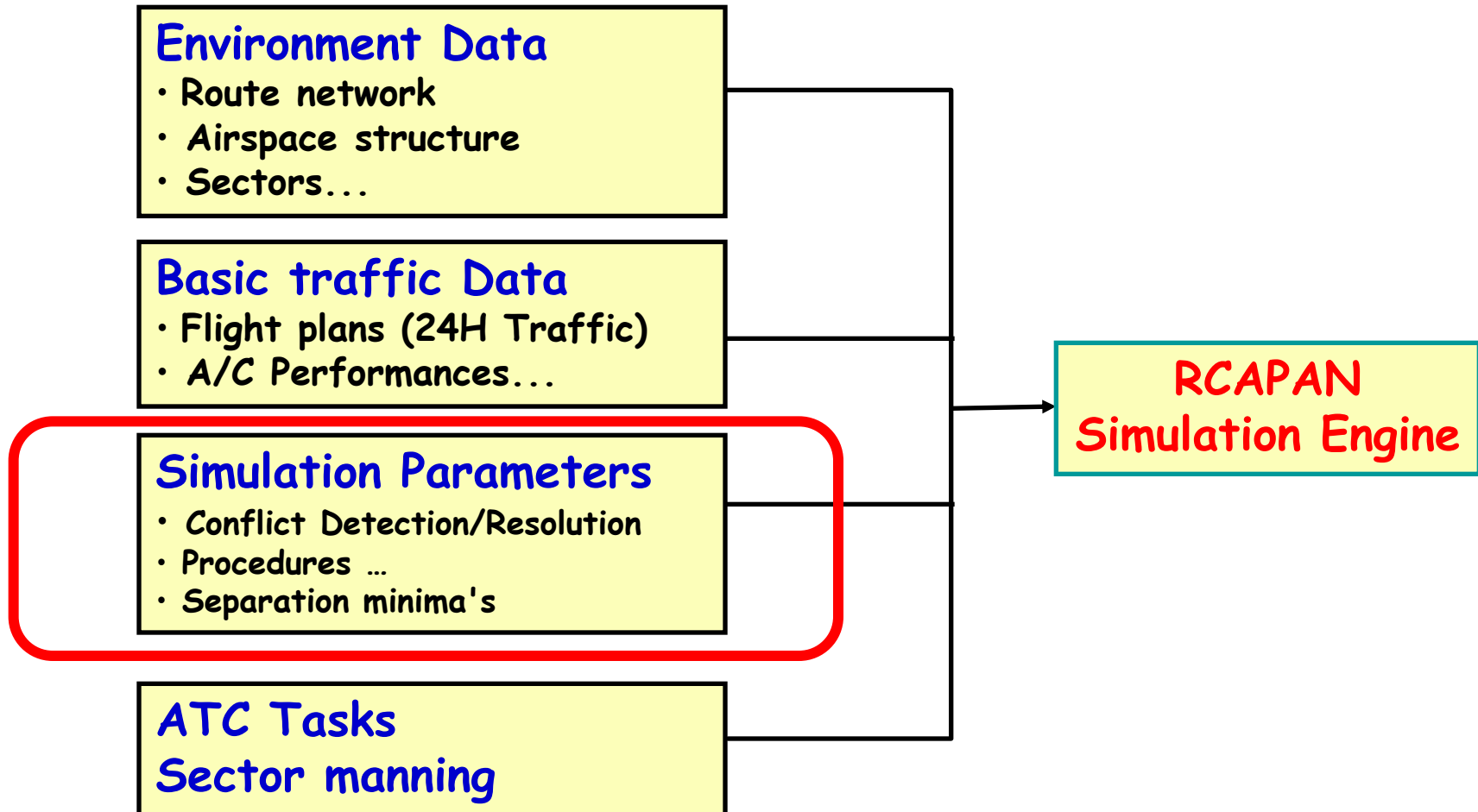


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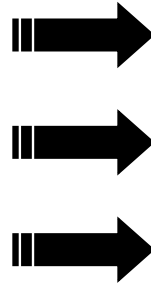
Conflict Detection & Resolution

Input Data



Conflict Detection & Resolution

A conflict is detected if time and/or distance separation between two flights is infringed at any time while crossing the portion of airspace under control



An action is taken to solve the conflict depending on:

- Type of conflicts
- Conflict evolution
- System capabilities

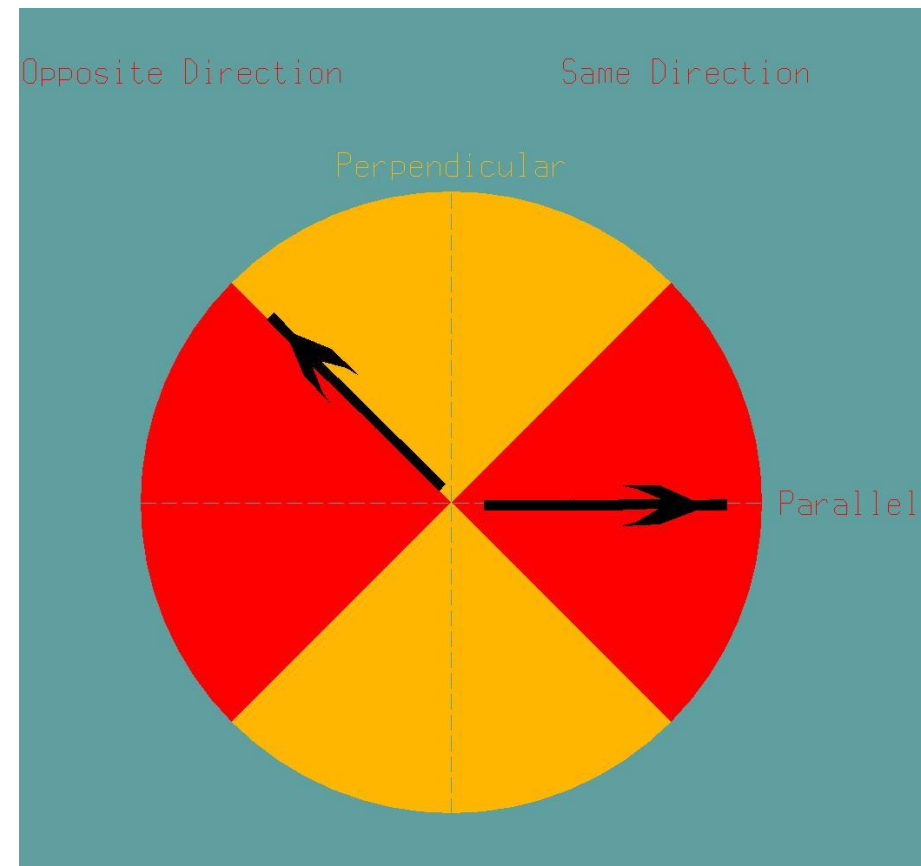
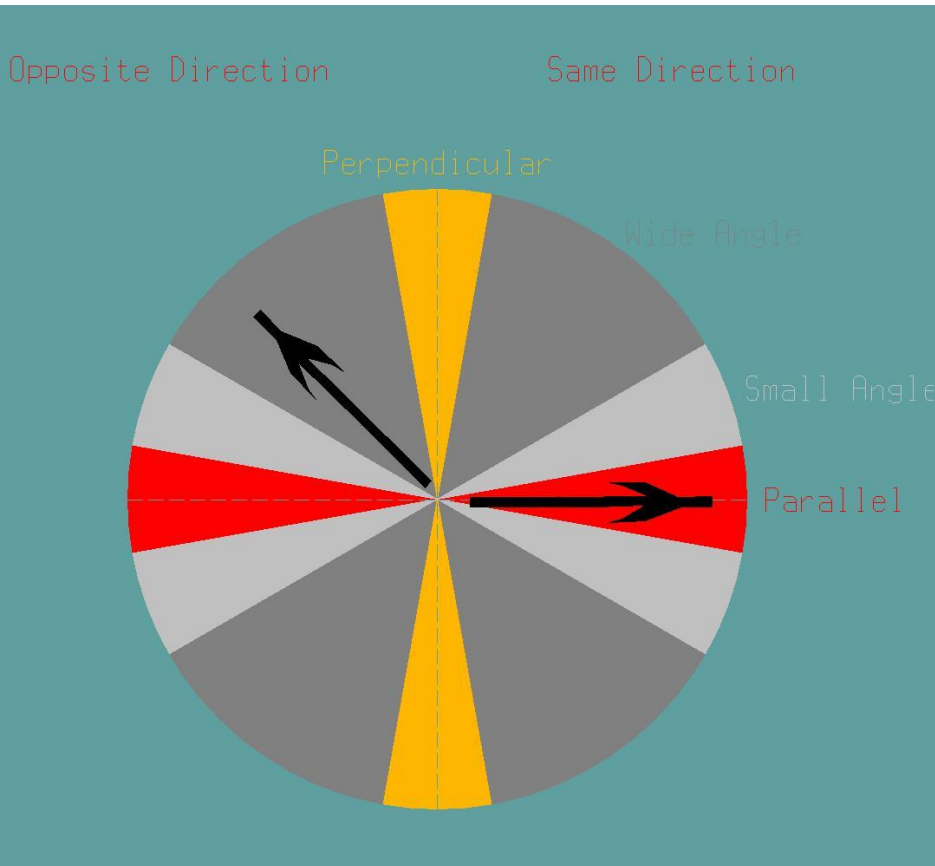


Define time and/or distance thresholds for separation infringement



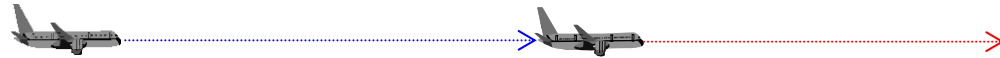
Define controller conflict resolution logic

Conflict Geometry Horizontal Plane

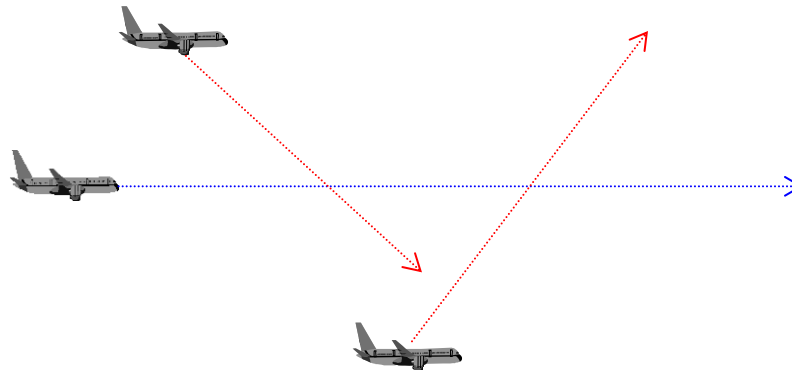


Conflict Attitude Vertical Plane

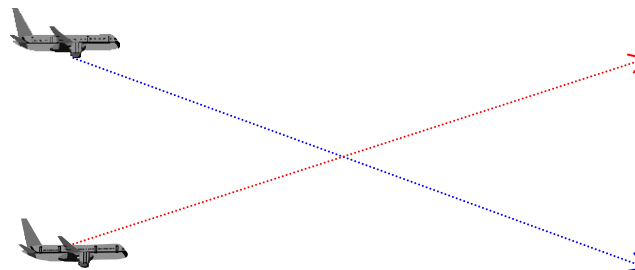
1. Both aircraft at the same level in cruise



2. One aircraft in cruise, one aircraft in climb or descent



3. Both aircraft either in climb or descent

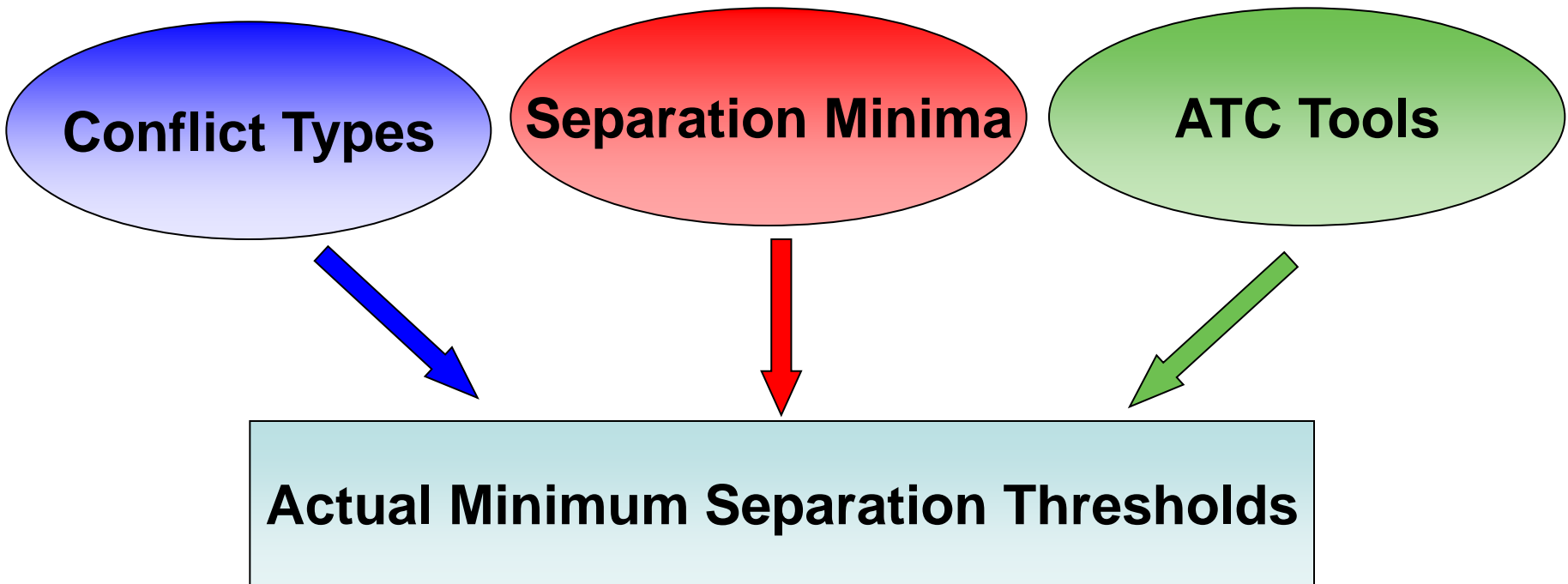


Conflict Types

A minimum of 9 types of conflicts

RADAR Conflict Number	Description
Type 1	Two aircraft on the same track at the same flight level in cruise.
Type 2	Two aircraft on the same track, one of which is in climb or descent
Type 3	Two aircraft on the same track, both of which are in climb or descent
Type 4	Two aircraft on crossing tracks, both in cruise at the same flight level
Type 5	Two aircraft on crossing tracks, one of which is in climb or descent
Type 6	Two aircraft on crossing tracks, both of which are in climb or descent
Type 7	Two aircraft on opposite tracks, both of which are in cruise at the same flight level.
Type 8	Two aircraft on opposite tracks, one of which is in climb or descent.
Type 9	Two aircraft on opposite tracks both of which are in climb or descent.

Conflict Detection



Separation Minimum distances need to be defined for all types of conflicts

These figures are used to detect and discriminate conflicts for all simulated flight profiles

Controller Separation Thresholds

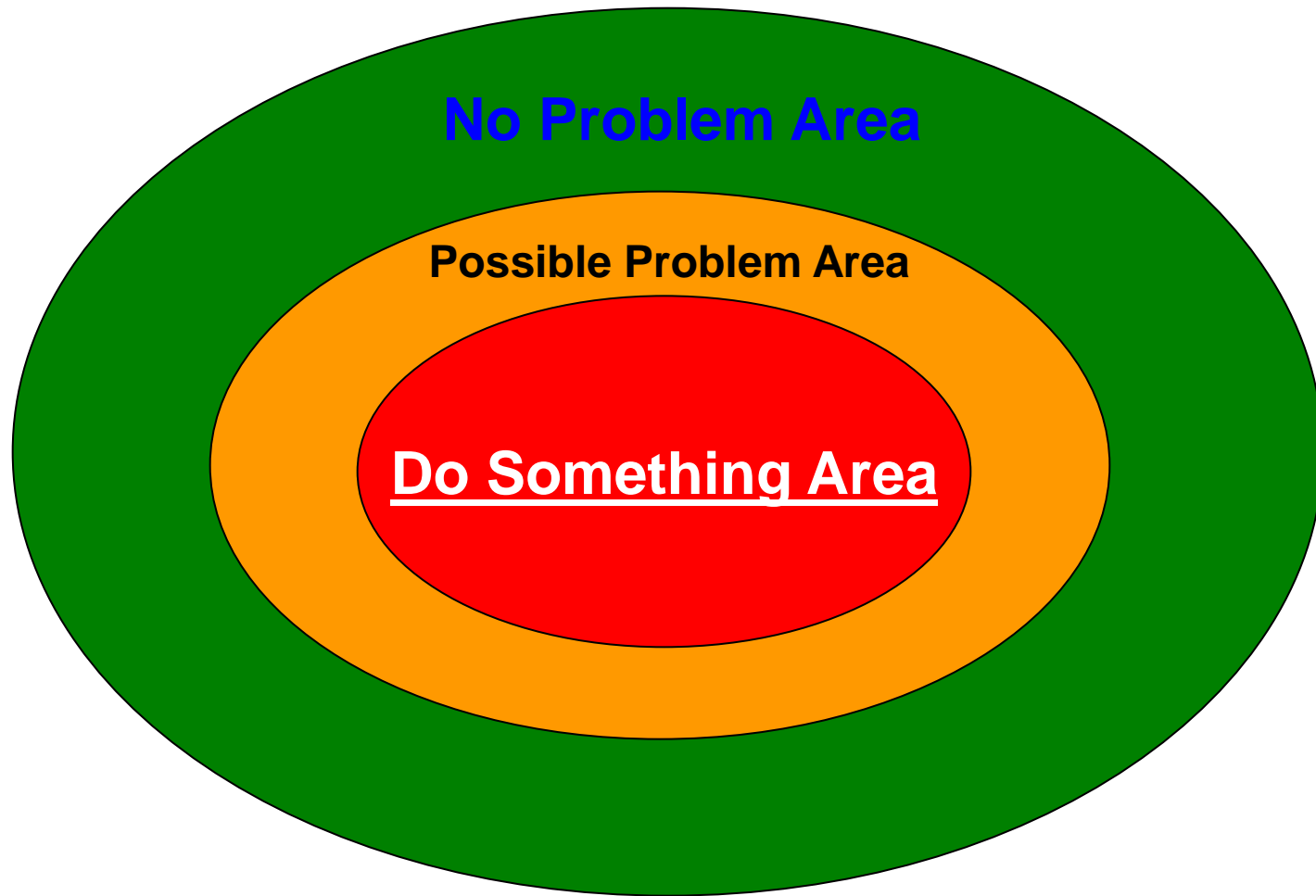
→ Monitoring Threshold:

- Controller will monitor closely the situation
- Controller will not modify the flight trajectory

→ Intervention Threshold:

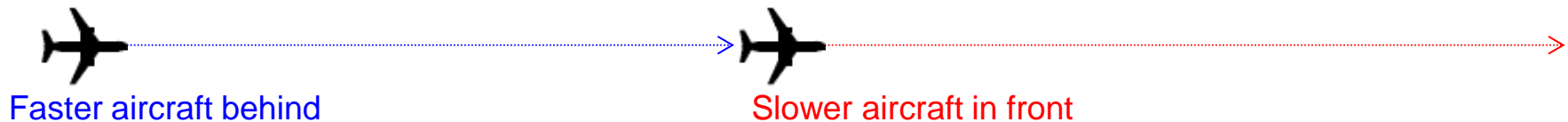
- Controller will modify the flight trajectory to ensure safe (and comfortable) distance between the involved flights

Controller Separation Thresholds



Conflict Detection Thresholds: An Example

- Applicable Separation Minima: 5nm
- Conflict Type 1: Parallel Same Direction, Same Level
- ATC Tools: CPA calculation between two flights based on present heading and speed
- Detection starting as soon as flights are within controller window



Case 1

- a. Controller assesses CPA to be 6 nm
- b. Even though $CPA > Sep.Min.$ controller takes an action

Case 2

- a. Controller assesses CPA to be 10 nm
- b. Controller does not intervene
- c. Controller might monitor the evolution of the conflict



A possible threshold for conflicts Type 1 could be 10 nm

Conflict Resolution

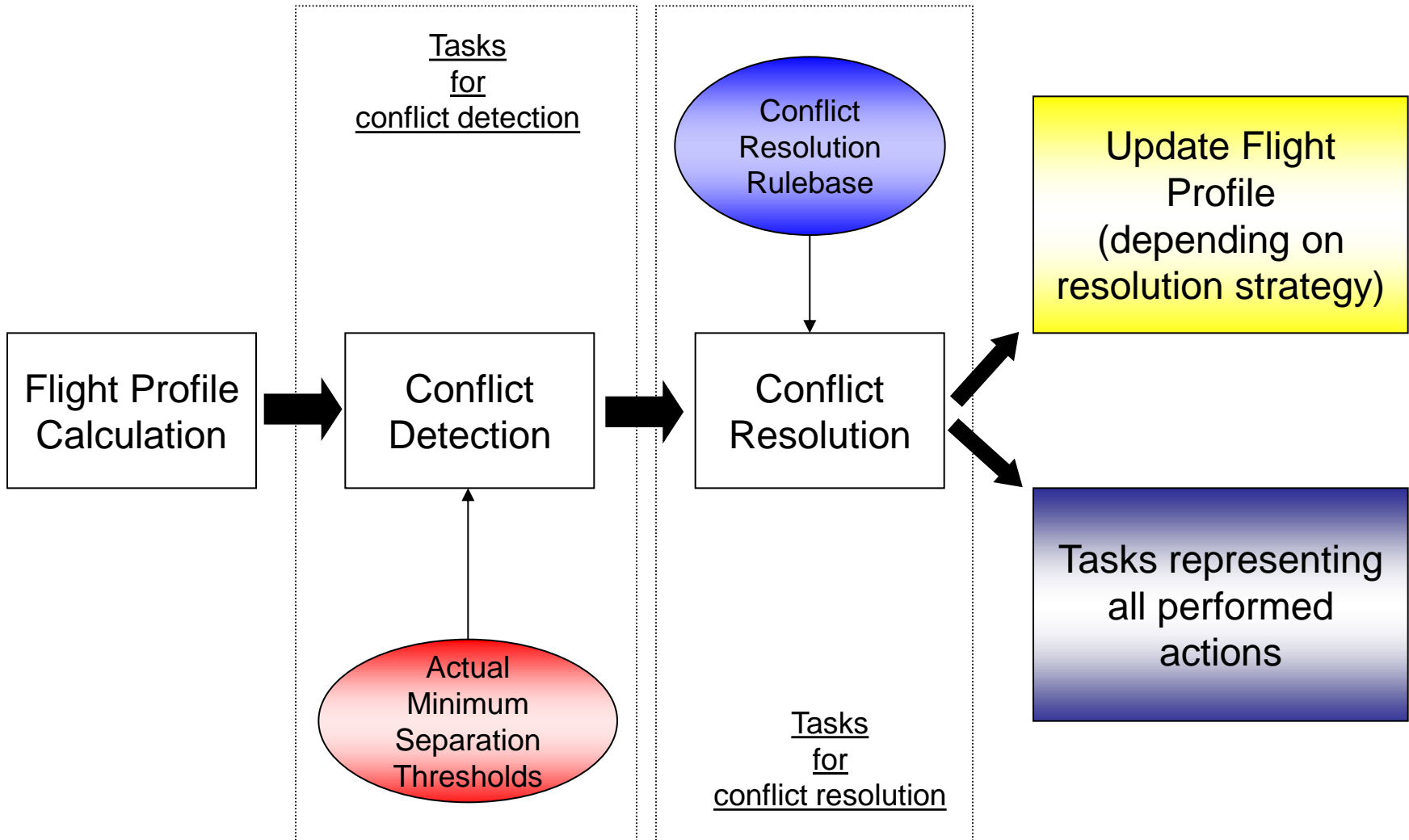
A conflict can be solved in many different ways, for example:

- Level Change
- Speed control
- Vectoring
- Direct-To

Workload assessment needs to be able to take this into account either by simulating it realistically or by reproducing the proper load for the controller → *resolution strategy*

A **set of rules** has to be defined to choose the right resolution according to actual conflict evolution, local procedures and modus operandi

Conflicts and Tasks



Input Data

Environment Data

- Route network
- Airspace structure
- Sectors...

Basic traffic Data

- Flight plans (24H Traffic)
- A/C Performances...

Simulation Parameters

- Conflict Detection/Resolution
- Procedures ...
- Separation minima's

ATC Tasks

Sector manning

RCAPAN
Simulation Engine

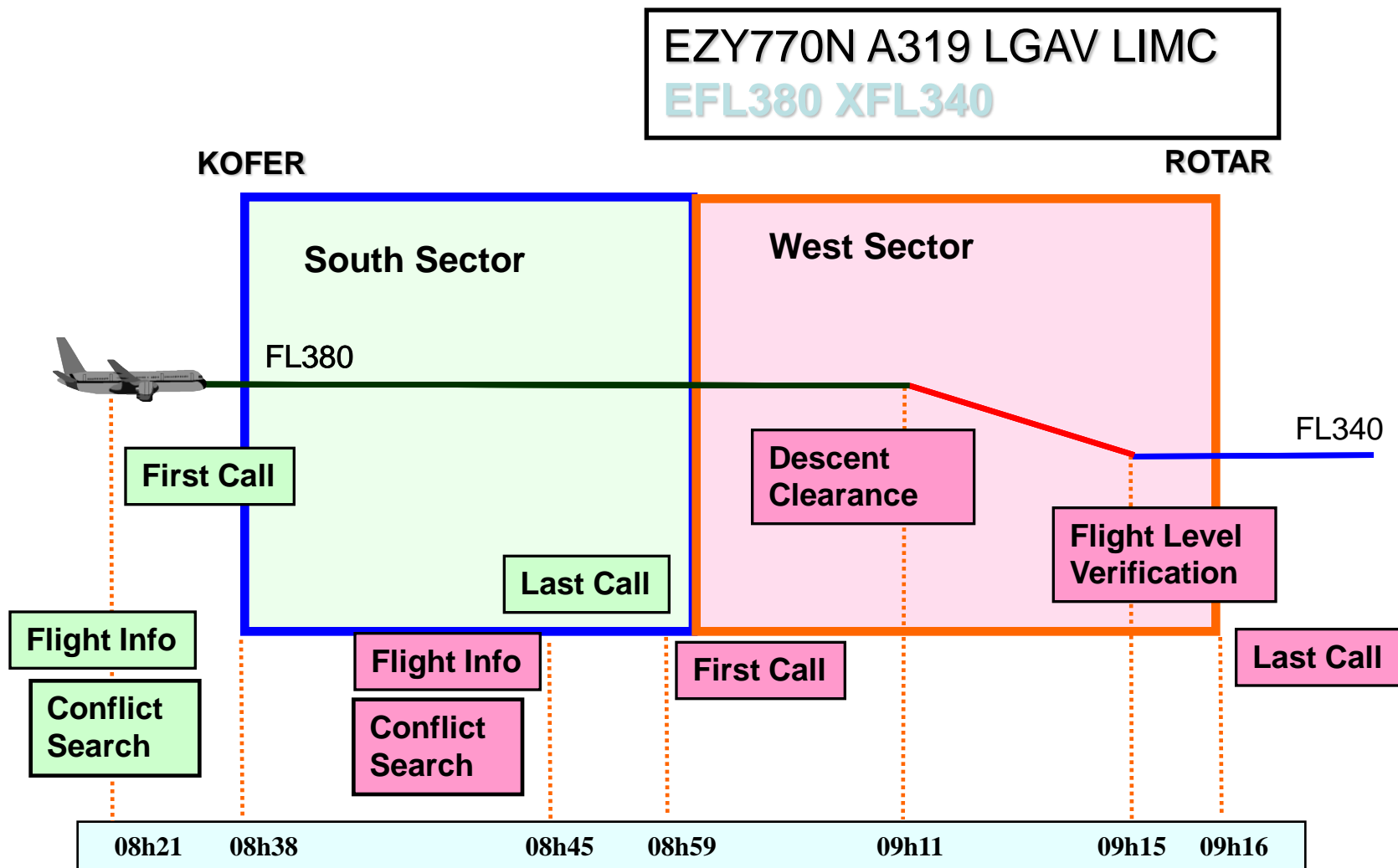


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Tasks and Task Categories

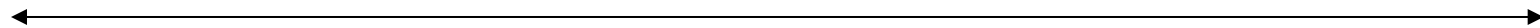
Events and Tasks



Task Definition

- Tasks reproduce controller actions
- Tasks are triggered by discrete ATC events
e.g. entry into a sector, entry into controller window, start of descent, etc.
- Tasks can be associated to specific conditions
e.g. airport, route, flight level, flight attitude
- Tasks can be grouped/chained to represent a set of connected actions

→ One Task = Many Actions vs. Many Tasks = One Action



Low Granularity

High Granularity

Task Categories

Tasks categories are chosen:

- To cover all discrete actions a controller can perform
- To reflect work organisation
- To address analysis interest

Categories and Sub-Categories can be defined as appropriate

Example:

Main Category - Radar

It covers all actions to detect and solve conflicts

Sub-category for each action

- e.g. Vector ~ Sub-cat.: TX Vector
- Monitor vector ~ Sub-cat.: Radar
- Monitoring
- Passing traffic information ~ Sub-cat.:
- TX traffic info

Sub-Category for groups of actions

- e.g. Vectors
 - + Monitor
 - + Passing Traffic
 - Info
- } ~ Radar
~ Conflict
Resolution

Controller Tasks & Categories

Eurocontrol CAPAN

- Standard model for controller tasks for both ACC and TMA environment
- Totally Customisable depending on system capabilities, specific procedures, separation minima, etc
- Divided into 5 main task categories:
 1. Flight Data Management
 2. Conflict Search
 3. Coordination
 4. Standard Radio Telephony
 5. Radar
- Applicable to single/double man operations, multi-sector planner, etc.





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Sector Capacity Assessment

General conclusions

Sector Capacity Assessment

Sector Capacity is driven by controller workload

A capacity assessment methodology should define:

- task categories and tasks
- conflict detection and resolution mechanisms
- a set of rules to mimic controller reasoning
- a threshold for average theoretical working time corresponding to sector capacity
- a technique to establish the relation between workload and capacity indicator

Sector Capacity Assessment

Assessment as a standardized process

A capacity assessment methodology should:

- Use a simulation engine which allows reproducing the ATC environment
- Follow a reiterative process of validation for every assessment case
- **INVOLVE active ATC staff** throughout the full process
- Encourage transparency and teamwork at all stages
- Use expert staff to guarantee that input data and simulation are properly carried out

→ **WRONG INPUT ~ WRONG OUTPUT**

Sector Capacity Assessment

Usability of results

A capacity assessment methodology should:

- Establish a comprehensive and possibly standardized set of results
- Define capacity related KPIs

Useful Links

- EUROCONTROL: www.eurocontrol.int
- Network Manager: <http://www.eurocontrol.int/network-manager>
- Operations Planning: <http://www.eurocontrol.int/operations-planning>
- ATFCM: <http://www.eurocontrol.int/articles/air-traffic-flow-and-capacity-management>
- Fatigue Risk Management: <http://www.eurocontrol.int/news/too-tired-be-safe-fatigue-risk-management-systems>