


Development and Validation of Procedures

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Overview

From Procedure design to Database -The steps needed to ensure RNAV/RNP systems follow the procedure correctly


Learning Objectives

- The translation of procedure from origination into a data base
- Taking account of RNAV/RNP limitations if the procedure is to be followed correctly
- The validation of procedures

Note: The term RNAV is used throughout to mean both RNAV and RNP Systems

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RNAV Procedure Description

- Instrument Flight Procedures
 - Published in AIP
 - Defined as textual descriptions supported by charts
 - The charts are used by the pilots and ATC
 - Database providers require clear and unambiguous procedure descriptions and use the charts to validate/check

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Coding the Procedure

Procedure coding

- Translates textual description of route or a terminal procedure into a format useable in RNAV systems.


Two steps:

- Translation from AIP text/chart into ARINC 424 alphanumeric code
- Translation from ARINC 424 into avionic specific binary code (known as 'packing')

Successful translation into ARINC 424 depends upon a clear and unambiguous description of the route/procedure.

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ARINC 424


- Industry standard for the transmission of data
- Navigation element uniquely defined and stored
- Can be accessed for any intended navigation purpose
- Developed to allow RNAV to be used on conventional procedures
- ICAO PANS-OPS references ARINC 424 rules and methodologies

Note: ARINC 424 not developed for design of flight procedures,

BUT: understanding of ARINC 424 enables procedure designers to perform their tasks so that misinterpretations and errors are significantly reduced

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ARINC 424 Records

<ul style="list-style-type: none"> VHF Nav aids NDB Nav aids Waypoints Holding Airports SID/STAR/APP Localiser and Glide Slope/MLS/GLS Company Route Localiser Marker Path Points 	<ul style="list-style-type: none"> Airport Communications MSA Airways Marker Cruising Tables FIR/UIR GRID MORA En-route Airways En-route Airways Restrictive En-route Communications Preferred Routes Controlled Airspace
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En-Route Coding

- Individual airway legs defined by waypoint and altitude constraints
- En-route holds not associated with any aerodrome and identified as 'ENRT'

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Terminal Coding

- Procedure identified as SID, STAR or APCH
- Only one STAR allowed per route
- ENRT Transitions used to link STARs to APCHs.
- RWY Transitions used to link RWYs to SIDs
- Individual legs defined by heading, waypoint, waypoint transition, path terminator, speed constraint, altitude constraint as appropriate

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Waypoint Transitions

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Track Distances Between Turns

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RNAV – Path Terminator Leg Type

Path	Letter	Terminator
Constant DME arc	A	A Altitude
Course to	C	C Distance
Direct Track	D	D DME distance
Course from a fix to	F	F Fix
Holding pattern	H	H Next leg
Initial	I	I Manual termination
Constant radius	R	R Radial termination
Track between	T	
Heading to	V	

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Path Terminators 14 RNAV Types

- Course to an Altitude - CA
- Course to a Fix - CF
- Direct to a Fix - DF
- Fix to an Altitude - FA
- Fix to a Manual Termination - FM
- Racetrack Course Reversal (Alt Term) - HA
- Racetrack (Single Circuit - Fix Term) - HF
- Racetrack (Manual Termination) - HM
- Initial Fix - IF
- Track to a Fix - TF
- Constant Radius Arc - RF
- Heading to an Altitude - VA
- Heading to an Intercept - VI
- Heading to a Manual Termination - VM

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Course to an Altitude

Course is flown making adjustment for wind

Unspecified Position

090°
CA Leg

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Course to Fix

Course is flown making adjustment for wind

080°
CF Leg

A

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Direct to Fix

Unspecified position

Direct
DF Leg

A

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Fix to Altitude

FA leg is flown making adjustment for wind

080°
FA Leg

Unspecified Position

8000'

A

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From a Fix to a Manual Termination

FM leg is flown making adjustment for wind

80°
FM Leg

Radar Vectors

A

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Racetrack

HA - Terminates at an altitude
HF - Terminates at the fix after one orbit
HM - Manually terminated

Next Segment

340°

Previous Segment

A

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Initial Fix

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Radius to Fix

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Track to a Fix

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Heading to an Altitude

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Heading to Manual Termination

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Use Of Path Terminators

- Available Path Terminators are defined in PBN Manual Nav Specifications
 - If the RNAV system does not have leg type demanded by procedure, the data packers have to select one (or combination of) available leg types to give best approximation
 - Risk incorrect execution!

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Aircraft Types you cater for

- Local fast regionals 
- Occasional older visitors – lack of functionality 
- Heavy slow long-hauls 

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RNAV Procedure Description

- RNAV procedures defined by:
 - Sequence of waypoints
 - Identifier
 - Co-ordinates
 - Fly-over/fly-by/fix radius
 - Path Terminators - ARINC 424
 - Altitude restrictions
 - Speed restrictions
 - Direction of turn
 - Required navaid

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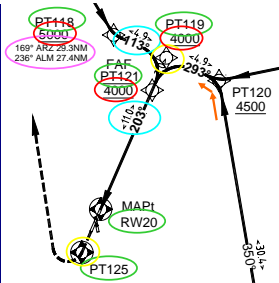
What Pilots Need to Know

- Waypoint names and sequence
- Fly-over/fly-by/fix radius
- Turn direction
- Speed restrictions
- Altitude restrictions
- Required navaid
- Leg distance and magnetic track for error checks
- Fixes at certain waypoints for gross error checks

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Procedure Description for Pilots

- Waypoint sequence
- Fly-over/fly-by/fix radius
- Speed/Altitude Restrictions
- Leg distance & magnetic track
- Fix information
- Turn direction



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Speed and Altitude Constraints

- Speed constraints allow tighter turns and can assist airspace design and operation
- Altitude constraints can provide separation from obstacles and other traffic - minimum climb gradients must still be published

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Procedure Description for Database Providers

- Textual description provide formal statement of procedure
 - Often open to interpretation
- RNAV procedures require more specific details including path terminators
 - Can result in lengthy descriptions
 - Alternative descriptive methods have been developed by IFPP (OCP) and adopted by ICAO
 - Tabular layout
 - Formalised textual description
 - Formalised short-hand description

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Tabular Description

RNAV Approach

Path Terminator	Waypoint Name	Fly Over	Course/Track/Heading 'M' ('T)	Turn Direction	Altitude Constraint	Speed Constraint	Required Navaid	Bearing/Range to Navaid	YPA/TCH
IF	SUSER	-	-	-	+5000	250	-	LOM 262/29	-
TF	CV023	-	-	-	4000	-	-	-	-
CF	CV024	-	348° (347.8°)	-	2680	150	OKE	-	-
TF	RW3SL	Y	-	-	370	-	-	-	-3750
EA	RW3SL	-	348° (347.8°)	-	770	-	OKE	-	-
DF	SUSER	Y	-	-	5000	-	-	-	-

RNAV SID

Path Terminator	Waypoint Name	Fly Over	Course/Track/Heading 'M' ('T)	Turn Direction	Altitude Constraint	Speed Constraint	Required Navaid	Bearing/Range to Navaid	Vertical Path Angle
EA	RW20	-	201° (203.3°)	R	400	-	-	-	-
DF	FOKSI	-	-	-	-	250	-	-	-
TF	PF213	Y	345° (346.8°)	-	+5000	250	-	OKE 330/30	-

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Formalised Description

Climb on track 047° M, at or above 800ft, turn right	[A800+; M047; R]-	FA
Direct to ARDAG at 3000ft	→ARDAG[A3000]-	DF
To PF035 at or below 5000ft, turn left	-PF035[A5000;-L]-	TF (Fly-over)
To OTR on course 090°M at 210kts	-OTR[M090; K210]-	CF
From STQ at or above FL100, turn left direct to WW039 at or above FL070, to WW038 at 5000ft	STQ[F100+; L]- →WW039[F070+]- WW038[A5000]	TF (Fly-over) DF TF

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Waypoint Identification

- Significant points
 - Identified by co-located navaid or by unique five-letter pronounceable “name-code” (5LNC)
- Some waypoints in the terminal area used for vectoring for sequencing and must be easy to enter in an RNAV system
 - 5LNCs not appropriate for this
 - Proceed direct ALECS (or ALEKX, ALECS, ALECX, ALLEX, ALIKS, ALIKX, ALICX, ALLIX, ALYKS, ALYKX, ALYCS, ALYCX, ALLYX)
- Concept of strategic and tactical waypoints

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Charting Altitude Restrictions

An altitude window : FL220
10,000

An “at or above” altitude: 7000

A “hard” altitude : 3000

An “at or below” altitude : 5000

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Where Are We?

Having designed an RNAV procedure to meet operational requirements we have:

- Considered the need to translate to a Nav DB
- Reviewed the ARINC 424 leg types
- Introduced means for describing the procedure in an unambiguous manner

Now:

- How to ensure that the procedure is correct and will be flown correctly

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Validation Activities

- Ground Validation
 - Obstacle clearance
 - Charting
 - Coding
 - Flyability
- Flight Validation
 - Obstacle verification (optional)
 - Flyability (workload, charting, manoeuvring)
 - Infrastructure
- Database Validation

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Ground Validation

- Obstacle clearance
 - Independent review by procedure designer
- Charting
 - Independent review – can be part of same organisation
- Coding
 - Software tool (e.g. Smiths PDT) or
 - Expert review
- Flyability – software tools (from PC-based to full flight simulator)
 - Not necessarily an issue with standard procedures (e.g. 'T' approaches), but critical for some aircraft types
 - Range of aircraft and meteo conditions

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Validate the Procedure Flyability

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Validate Again with Different Conditions

B737-300 18.5k
ISA +40
Wind 300/20

B737-300 22k
ISA -20
Wind 250/20

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Different Aircraft and Different Conditions

CA 500ft agl; DF LL001; TF FARKS; TF...
No wind

B737/400
B747/400
A340/300

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Wind Effect

CA 500ft agl; DF LL001; TF FARKS; TF...
ICAO wind from 045°

B737/400
B747/400
A340/300

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Countered by Speed Restriction

CA 500ft agl; DF LL001; TF FARKS; TF...
[210kts]; TF...
ICAO wind from 045°

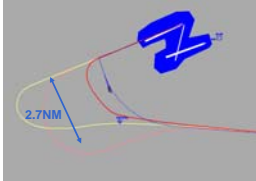
B737/400
B747/400
A340/300

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Leg Length Too Short



CA 2000ft agl; DF BRW02


No wind

ATR42

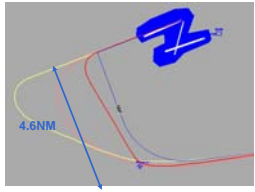
B 747-400

A340-300

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Leg Length Acceptable



CA 2000ft agl; DF BRW02


No wind

ATR42

B 747-400

A340-300


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Flight Validation

- Obstacle verification
 - Necessary where full obstacle survey cannot be assured
- Flyability
 - Detailed workload and charting assessments, but
 - High level qualitative assessment of manoeuvring only (rely mainly on Ground Validation)
- Infrastructure assessment
 - Runway markings, lighting, communications, navigation etc


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Flight Inspection

- Flight Inspection addresses:
 - **Navaid performance** for DME/DME RNAV
 - **Unintentional interference** for GNSS


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DME Tasks

- Need to confirm valid DME pairs
 - Expected coverage and field strength
 - If gaps are present, need to know exact area
 - Range accuracy within Annex 10
- Need to identify DME's that degrade the navigation solution
 - Propagation distortions
 - Either effect can be removed (small local reflector) or
 - Pilot needs to deselect

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RNAV DME Flight Inspection Planning


Infrastructure Assessment preparation to make inspection efficient

Identify:

- Candidate DME pairs and associated coverage
 - Including expected gaps in coverage, if any
- Candidates for exclusion:
 - Propagation path near horizon or significant terrain
 - Second DME on same channel within line of sight
 - ILS/DME facilities (offset bias?)
- Minimum/maximum height profile for Nav aid coverage validation

PANS-OPS, ATC Operations, Engineering and Flight Inspection Organization jointly plan inspection flight

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Database Validation

- RNAV procedures coded using ARINC 424 path terminators to define specific nominal tracks
- Coded procedures not available in operational databases until effective date
 - Recommend implementation date 3 to 10 days after effective date
- Test databases may be provided for flight validation
- Flight does not validate integrity of procedure subsequently coded in operational database
- State must find other means of validating the operational database

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Data Origination

ICAO Documents
Annex 15 SARPS
Doc 8071 *Flight Inspection Manual*


EUROCONTROL Guidance Material
Integrity of Aeronautical Information
- *Aeronautical Data Origination*
AFN/NAV/DAT/ORG/DOC001-150404
Survey and procedure Design Requirements
Navigation Infrastructure assessment Document

FAA Guidance Material

- FAA Specification 405 *Standards for Aeronautical Surveys and Related Products*
- FAA Order 8260.19 *Flight Procedures and Airspace*

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Requirements Addressed in Documents

- Survey –WGS84
- Training for designers
- Software Tool Qualification
- Data management
- Quality Assurance
- Verification of Procedure Designs
- Publication
- Validation tests
 - Flyability – under range of wind conditions for appropriate aircraft types
 - Navigation aid coverage

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Summary

- Waypoint transitions
- ARINC 424 Path terminators
- Procedure Coding
- Charting Issues
- Validation:
 - Flyability
 - Flight Inspection

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Audience Response System Questions

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