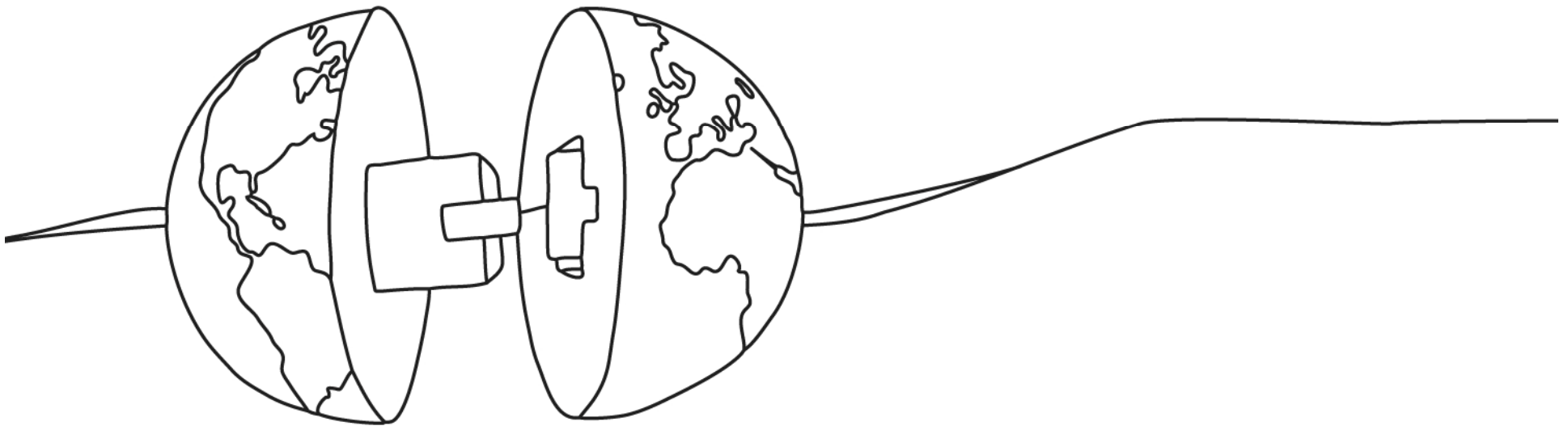


Seminar on ATM Automation-CAR/SAM

Rio de Janeiro, 11-13 Jun2008

Integration case of ADS-B/ADS-C/Radar data



Adriana Mattos

ATM Business Development
Latin America and Caribbean

SITA

Communication services

Agenda

- Overview on Australian ATM system
- ADS-B Upper Airspace Project
- Changes to ATC system
- Human-Machine Interface overview:
 - The track presentation
 - Track source
 - Accuracy
 - The best data presented to the controller
 - The ability to separate source data
- Air situation display show
- Conclusion

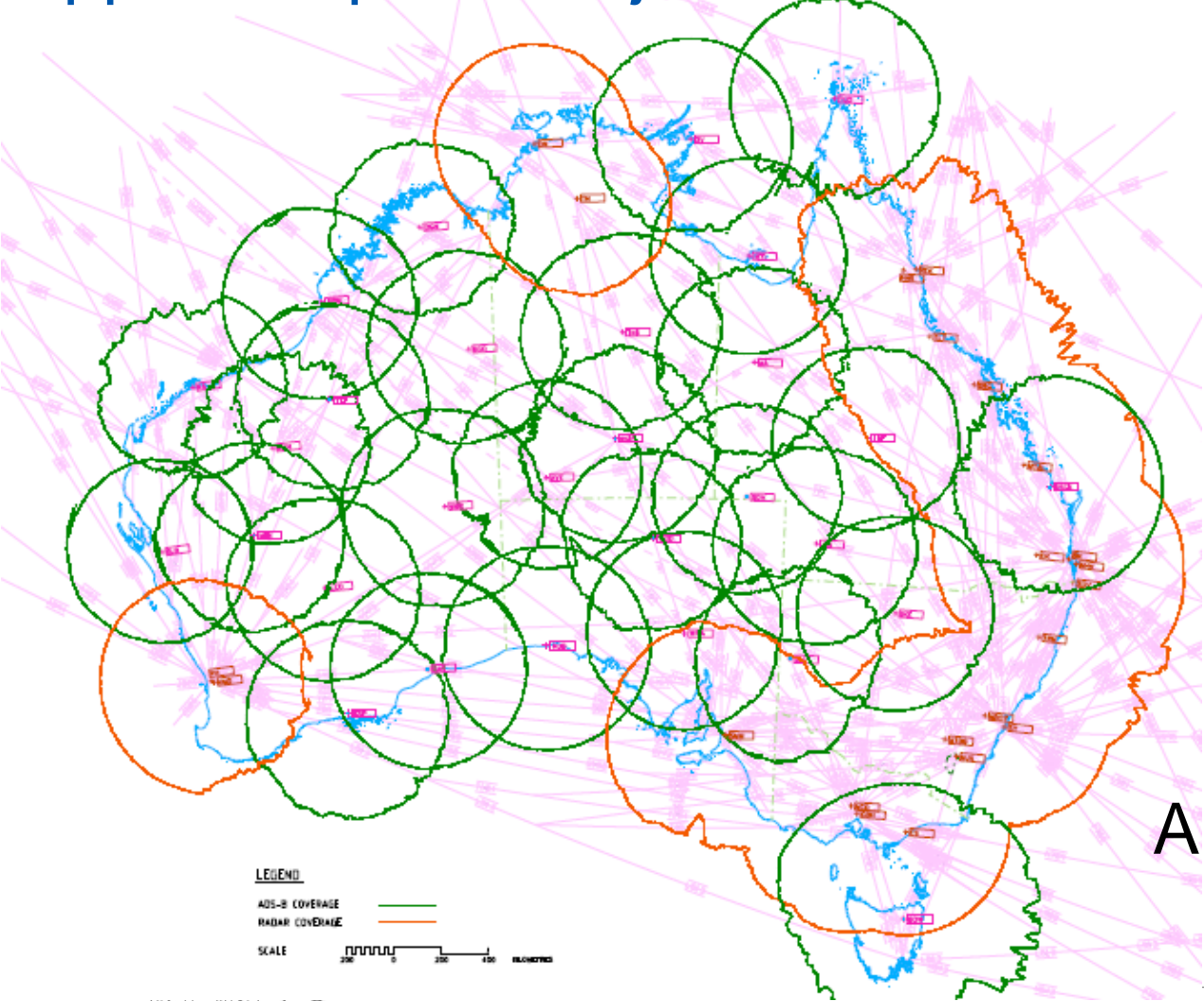


Overview on Australian Air Traffic Management System

- 2 Area Control Centers: Melbourne and Brisbane
- All ATC units use Thales Eurocat System
- Around 150 consoles: no paper strip is used
- No analogue radar displayed to the controllers
- All centres use same console type
- ADS-B, ADS-C, Radar and Flight Plan tracks are displayed
- Above FL100, VHF voice coverage is fully available



Upper Airspace Project



GROUND STATIONS ARE BEING INSTALLED

ADS-B Coverage at 30,000 feet

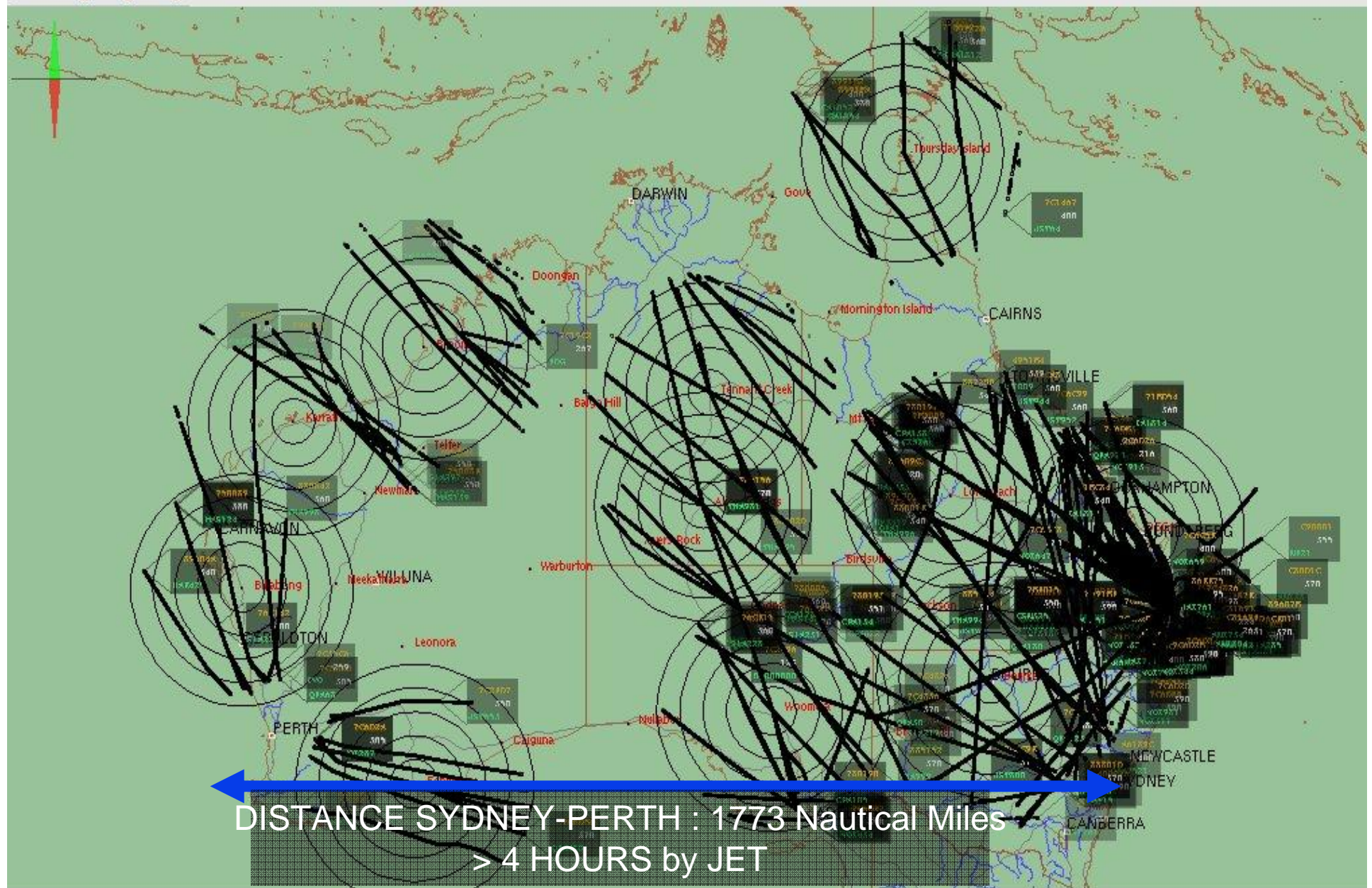


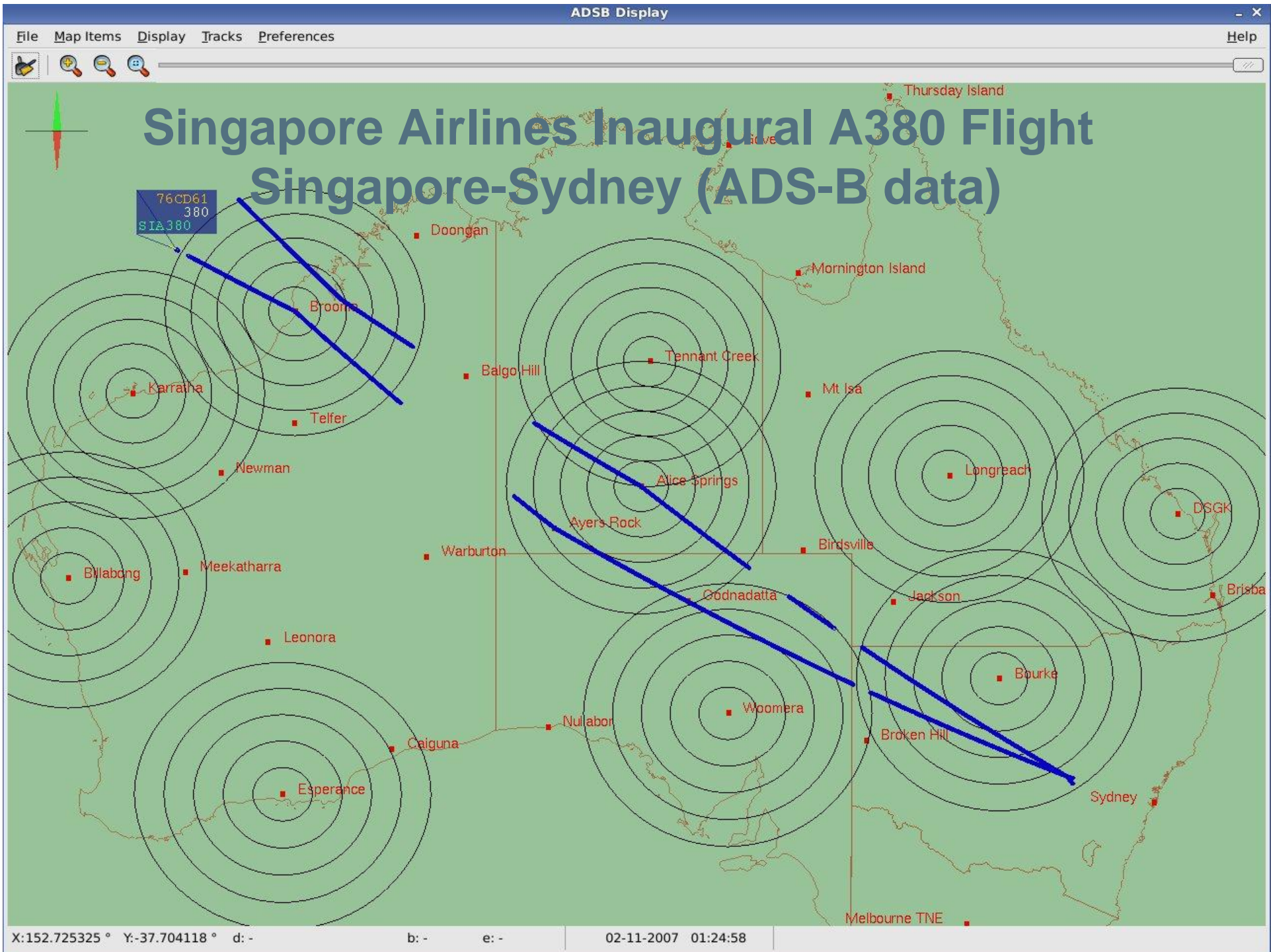
- 11 ADS-B Ground stations operational delivering service
- Increase in approved aircraft ~ 660
 - 55% of scheduled international aircraft now approved & receiving services
- 19% of scheduled domestic flights
 - Regionals coming on line (Rex – SAABs)
- Thursday is commissioned
 - ADS-B coverage across the FIR boundary – data sharing opportunity
- Work started on Lord Howe Island – ADS-B in the Ocean



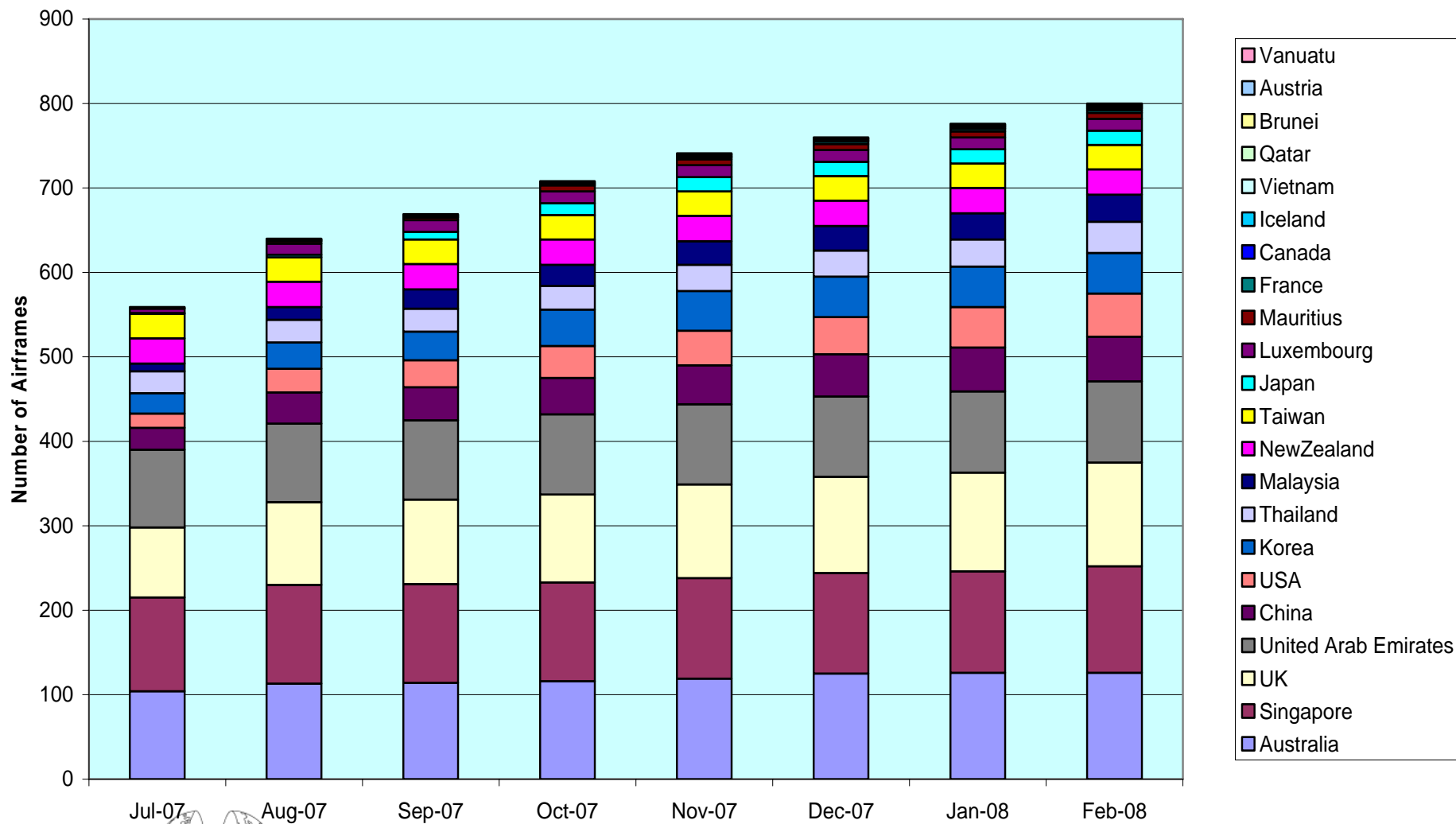


Thursday Island





1090 MHz ADS-B Equipped Aircraft broadcasting position with NUC>=5 by State of Registry (as seen by 11 ADS-B Ground Stations in Australia)





- About to commission supplementary “windows” to follow selected pairs of aircraft
- Contract signed
 - Multi-sensor fusion tracker for enroute/terminal for radar, ADS-B, DAPS, multilateration
 - Support & display of DAPS (Mode S radar & ADS-B)
 - Integration of MLAT & ASMGCS ADS-B
 - ADS-B in TMAs



The track presentation

- Display of source of track
- Display of accuracy of track
- Integrated track:
 - One track per aircraft
 - Full alert functionality regardless of source of data
 - The best available data presented to the controller
- Ability to separate and identify the source of data (supervisor)



Track source

Visibility of the source of the track

- Combined ADS-B and radar track
- ADS-B track
- Radar track
- ADS-C track
- Flight plan track

Combined ADS-B and radar track



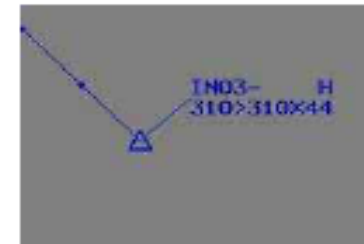
ADS-B tracks



Radar tracks



ADS-C tracks



Flight plan tracks



Accuracy

- ADS-B track with high quality (quality is based on FOM and Ground Station reliability)
- ADS-B track with low quality
- Primary radar track
- Secondary radar track

ADS-B track with high Quality



Primary radar track



ADS-B track with low Quality



Secondary radar track



One track per aircraft

Integrated track – one track per aircraft

- Comprised of
 - Position data
 - Velocity data
 - Alert data
- Important to reduce clutter on screen
- Tolerances for coupling of track need to be configurable
 - Need to show operator two tracks if position data different
 - Need to show worst case emergency data



Alert functionality regardless source of data

- All alerts to be available on all tracks
 - RAM, DAIW, TDAW, STCA, MSAW, CLAM
- Important for controller to have the same alerts regardless of source of data
- Parameters need to be configurable
 - Tolerances should be configurable for all alerts (e.g. RAM tolerance)
 - Different tolerances should be able to be used for different source's of data (RAM tolerance different between ADS-B and radar)
- Controller should not have to interpret which source has produced alert



The best available data presented to the controller

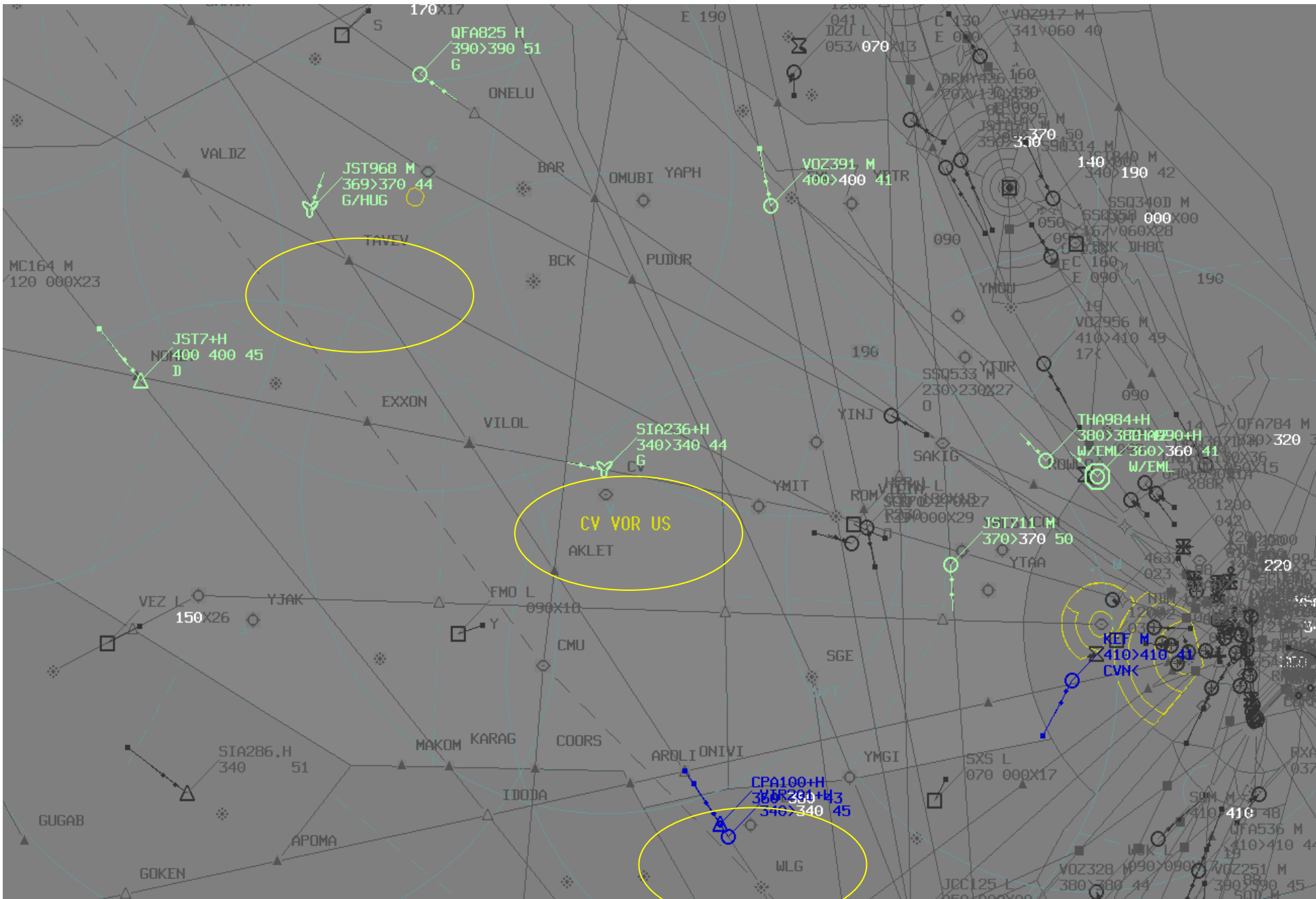
- The best available data may not be from one source. E.g.
 - Position data from radar
 - Velocity data from ADS-B
 - Combined position data from ADS-B and multiple radars
- Should data be combined to provide the controller with the most accurate data? Implications for separation standards.
- Need to have complex, configurable data fusion
 - Different priorities for different data (e.g. velocity/position data may have different priorities between sources)
 - Different methods (Priority, Multi Sensor Track Fusion)

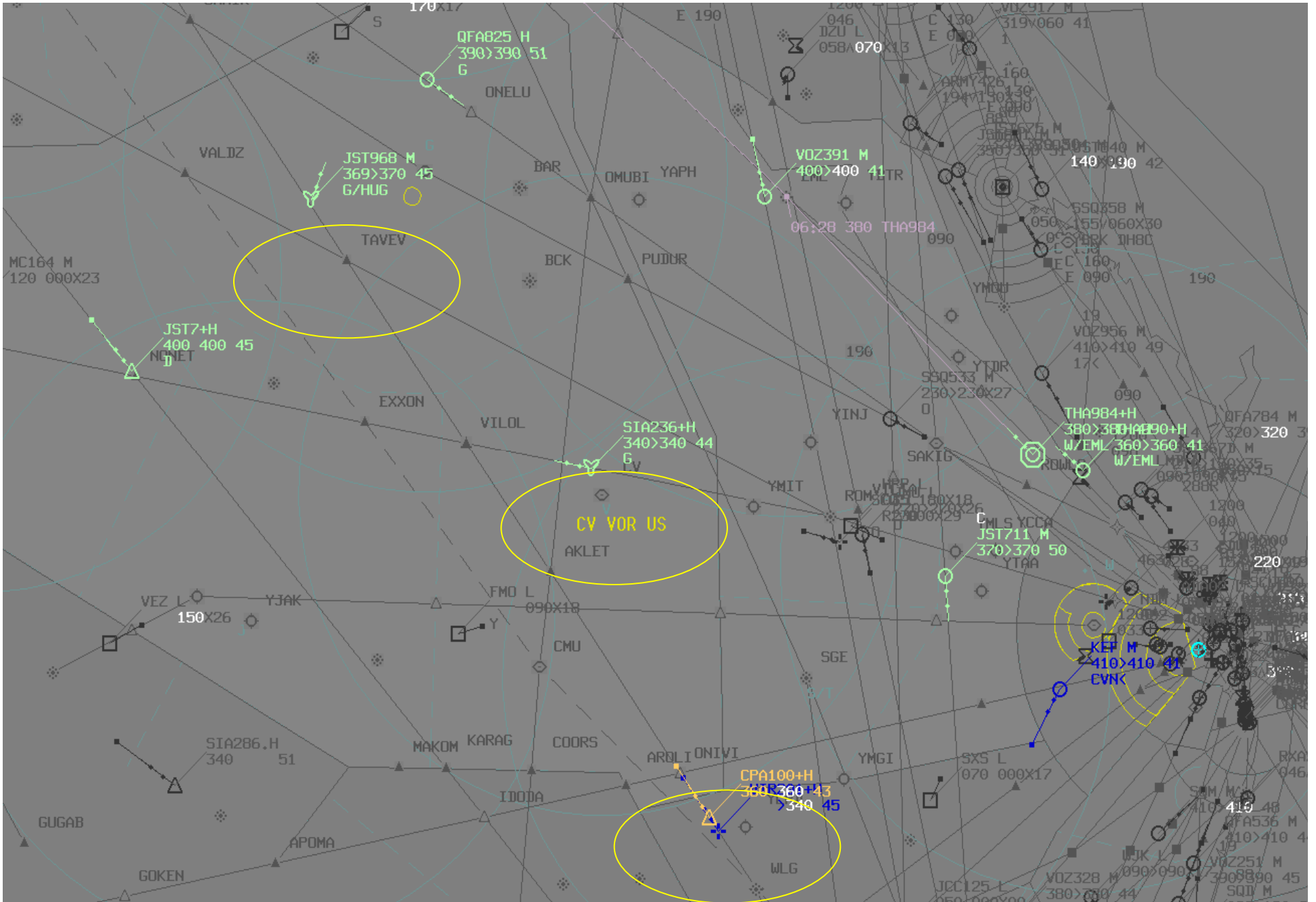
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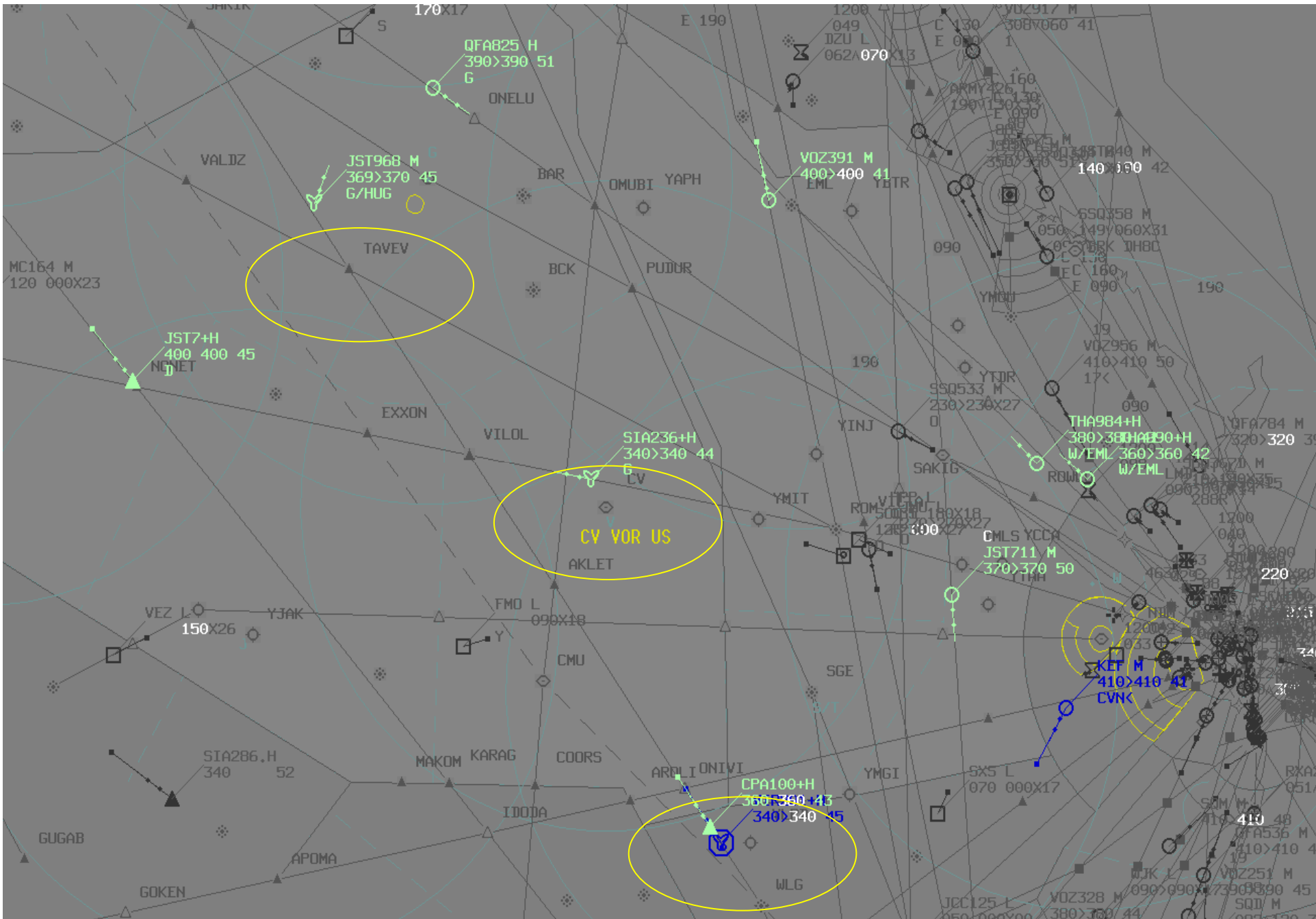
The ability to separate and view source data

- The supervisor needs the ability to see what data is contributing to the combined track, but also needs to be able to view the data separately
 - Required in order to check accuracy
 - Needs to be able to verify data consistency
- The supervisor needs to be able to diagnose problems with track data
 - Is ADS-B data incorrect?
 - Possible aircraft position problem
 - Possible aircraft velocity problem
 - Is radar data incorrect?
 - Possible radar problem
 - Data from a radar should be removed from the system



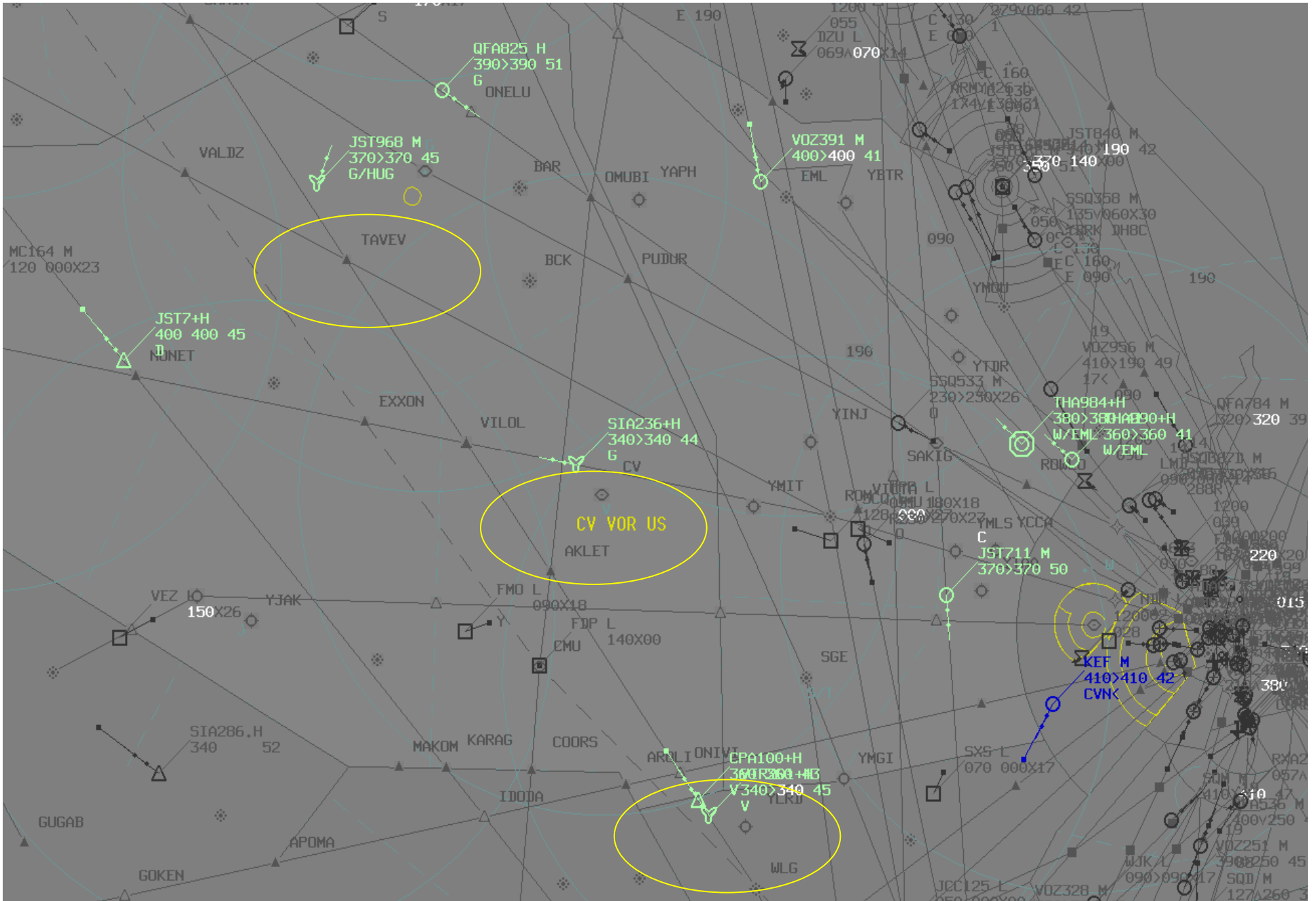


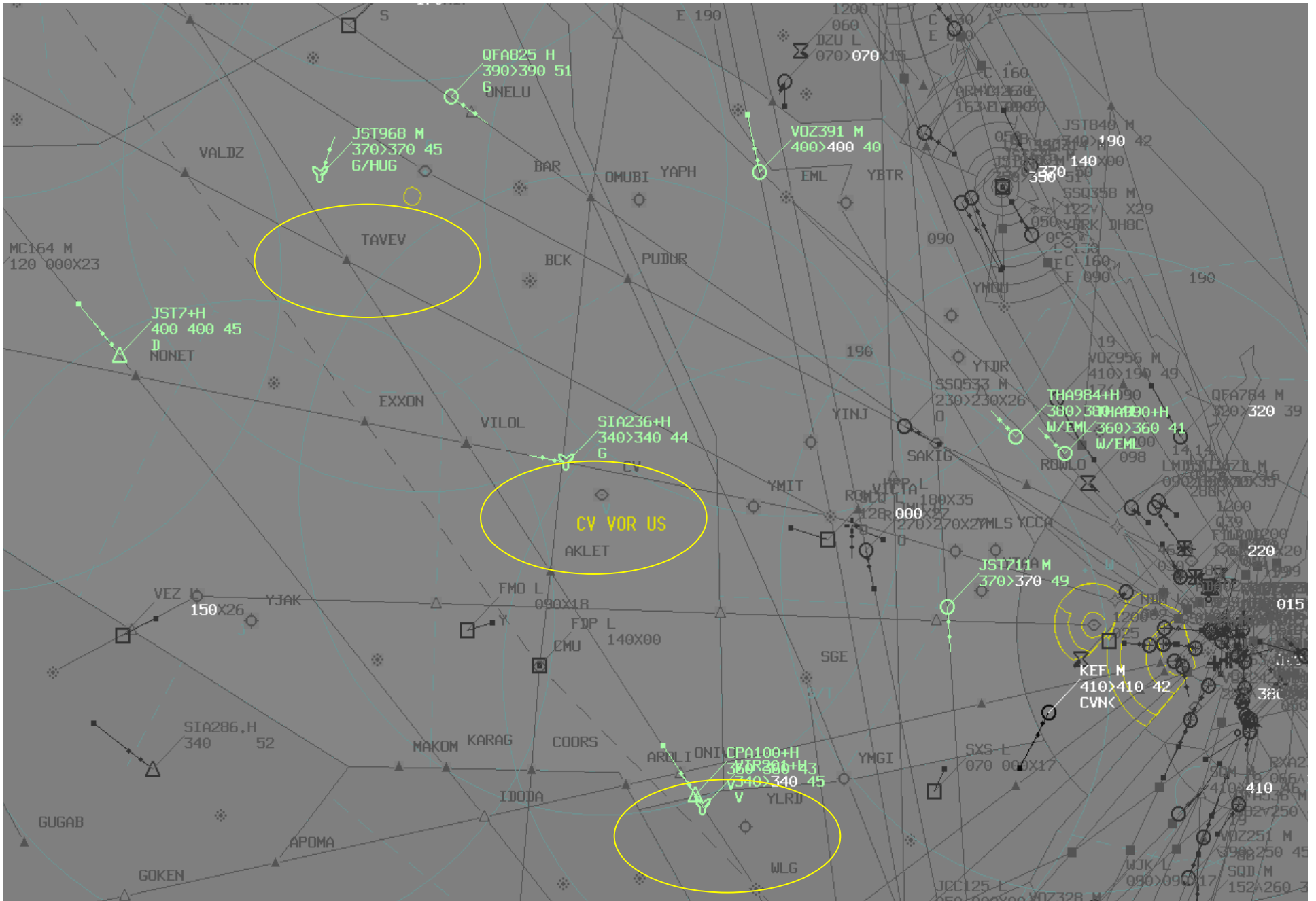


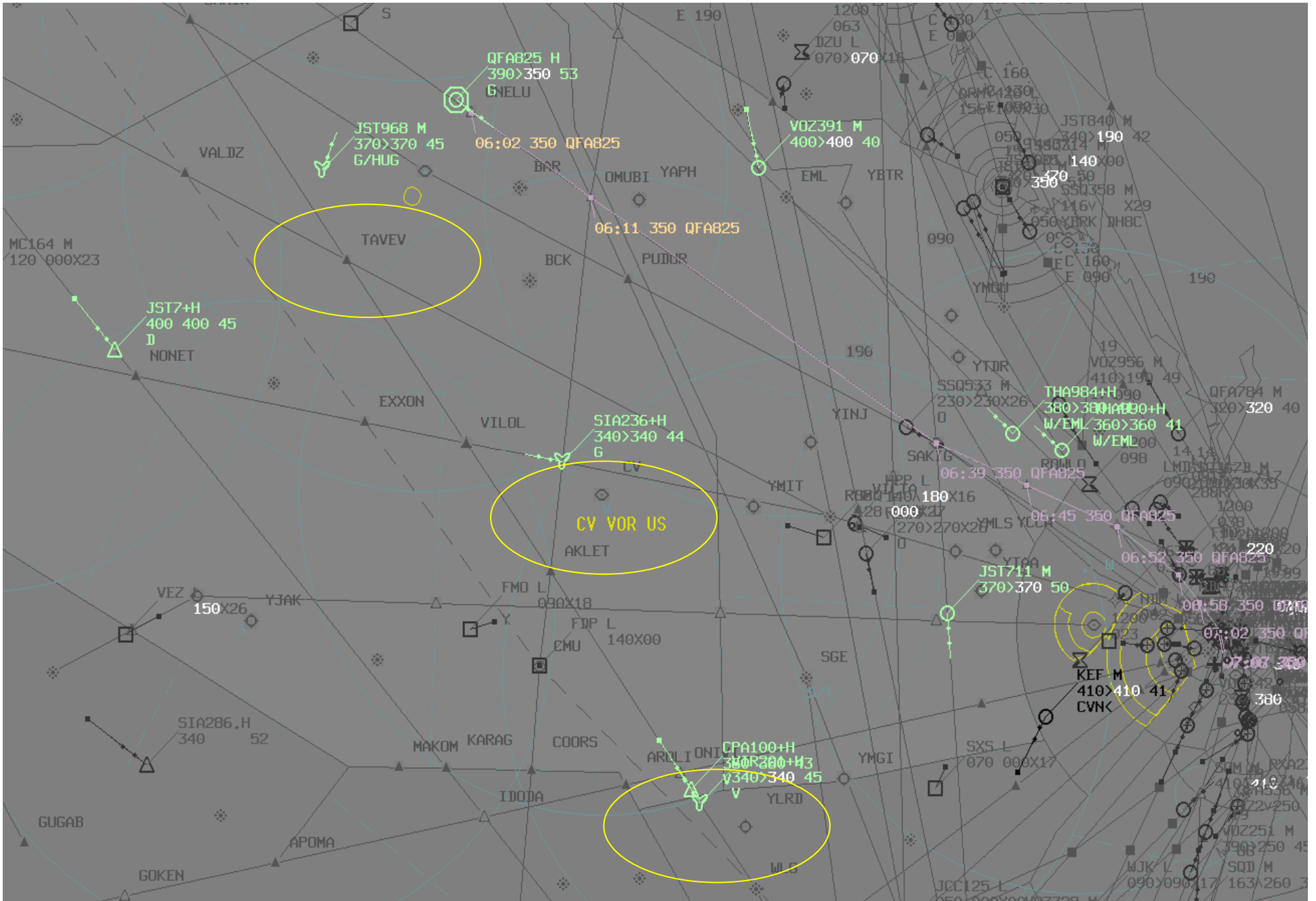


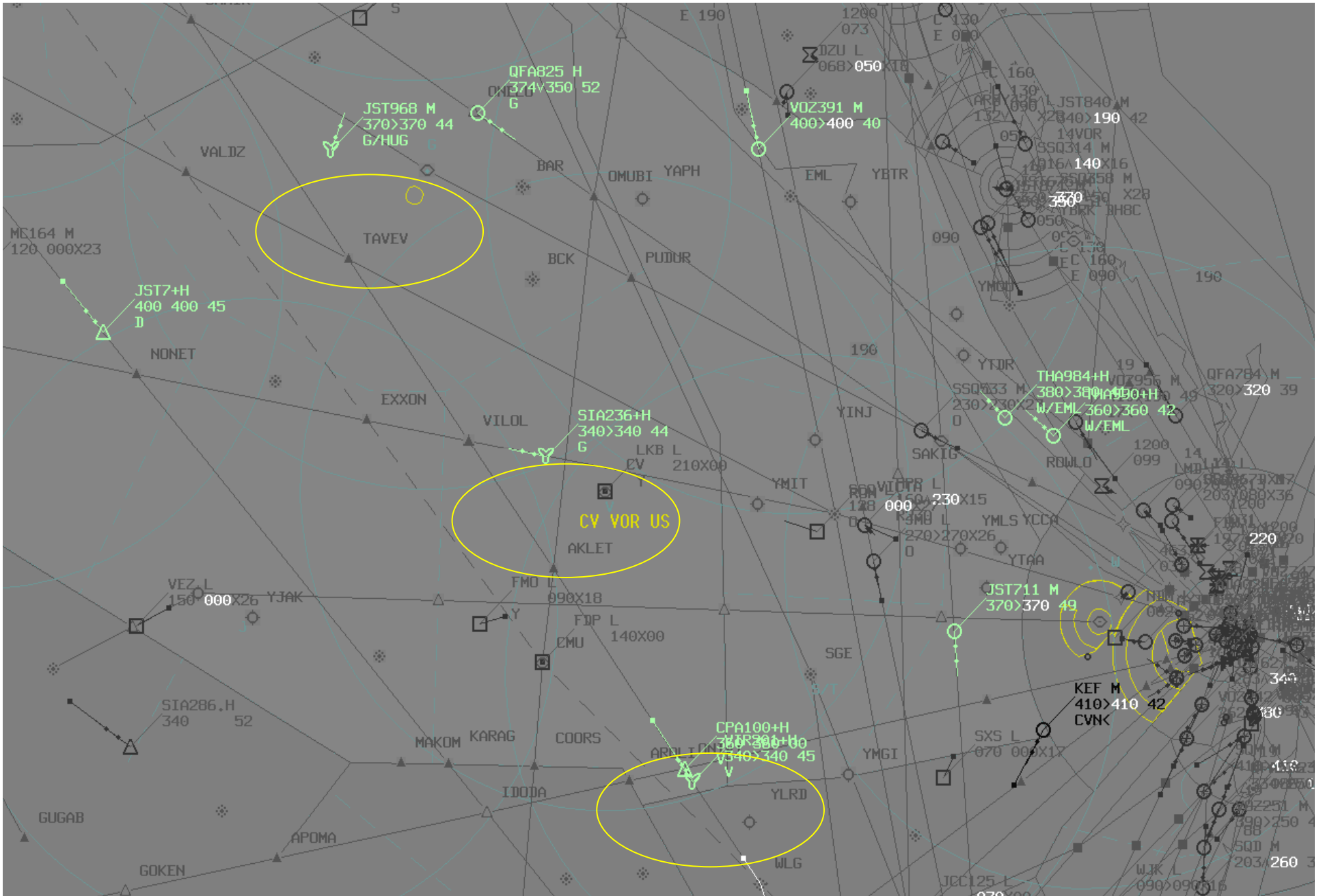
Integration case of ADS-B/ADS-C/Radar data | 12 Jun2008 | 24 | ©SITA Confidential

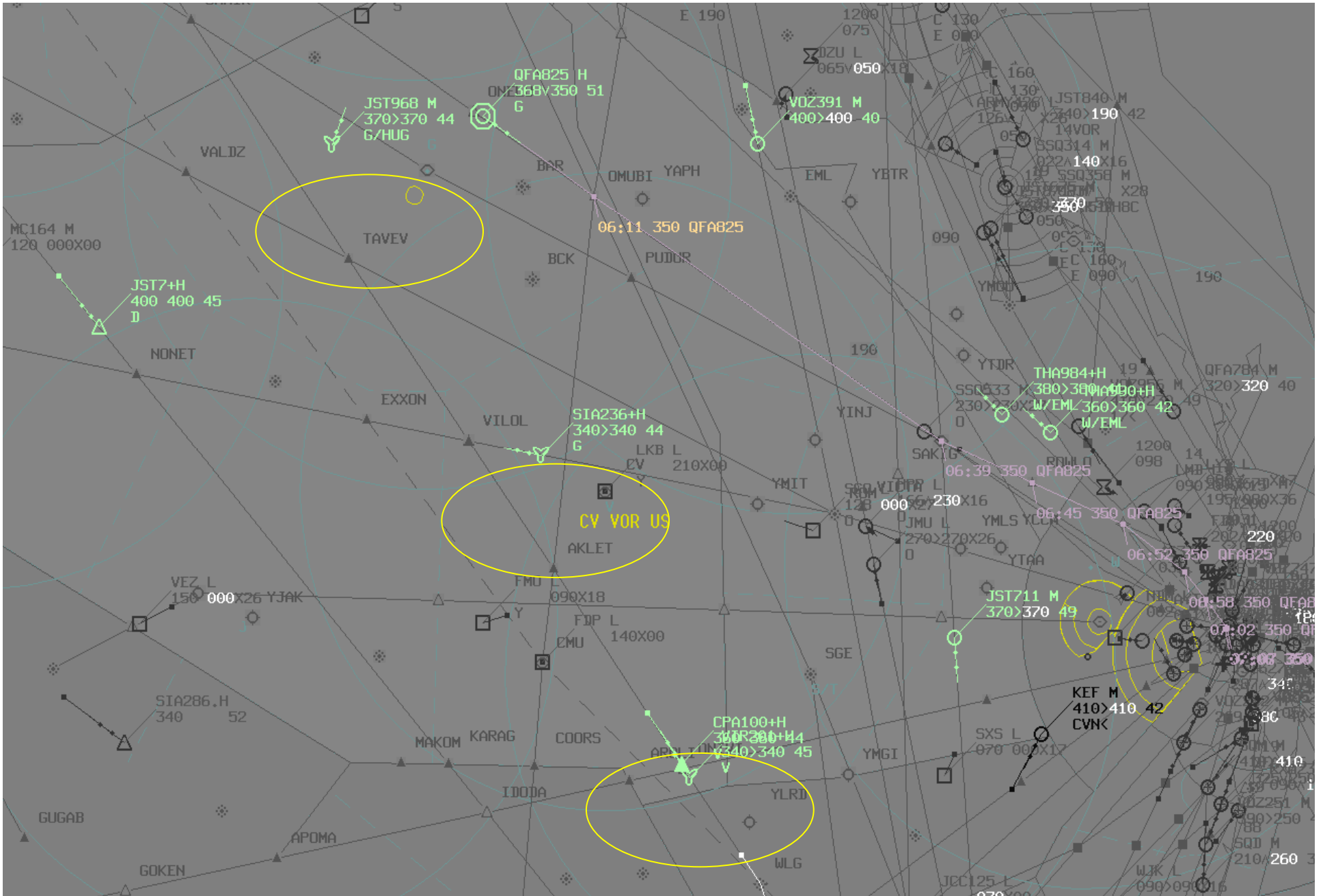


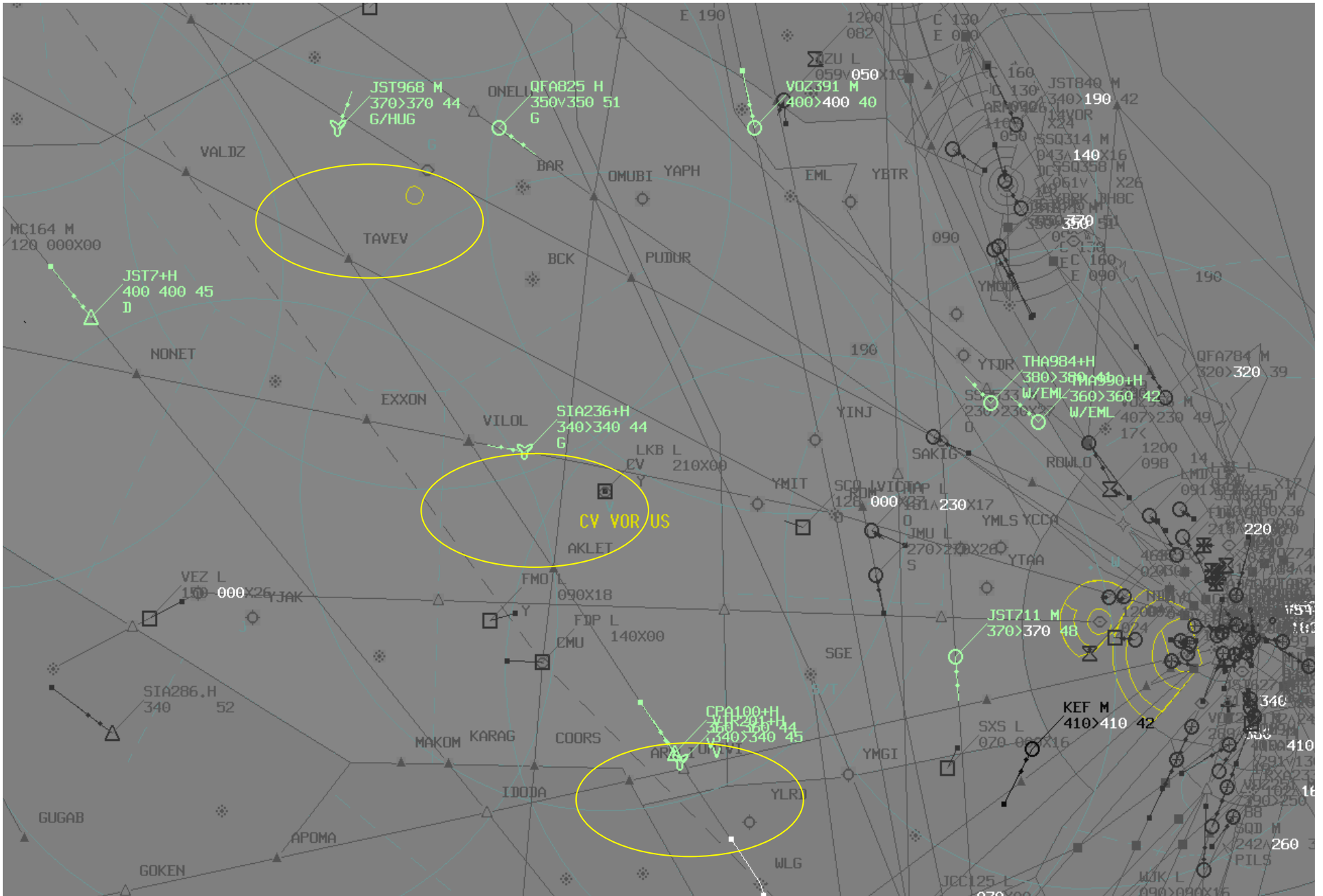


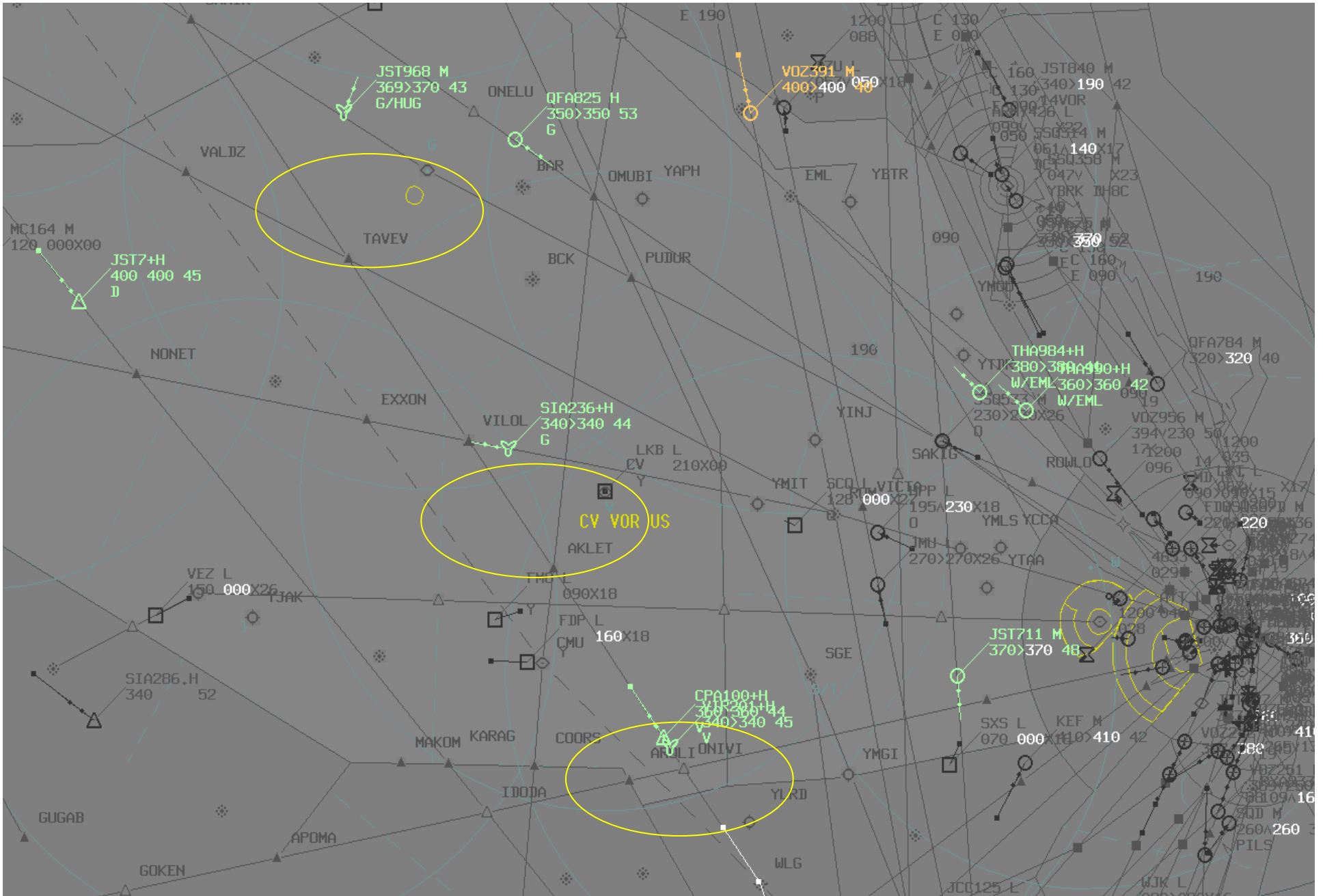


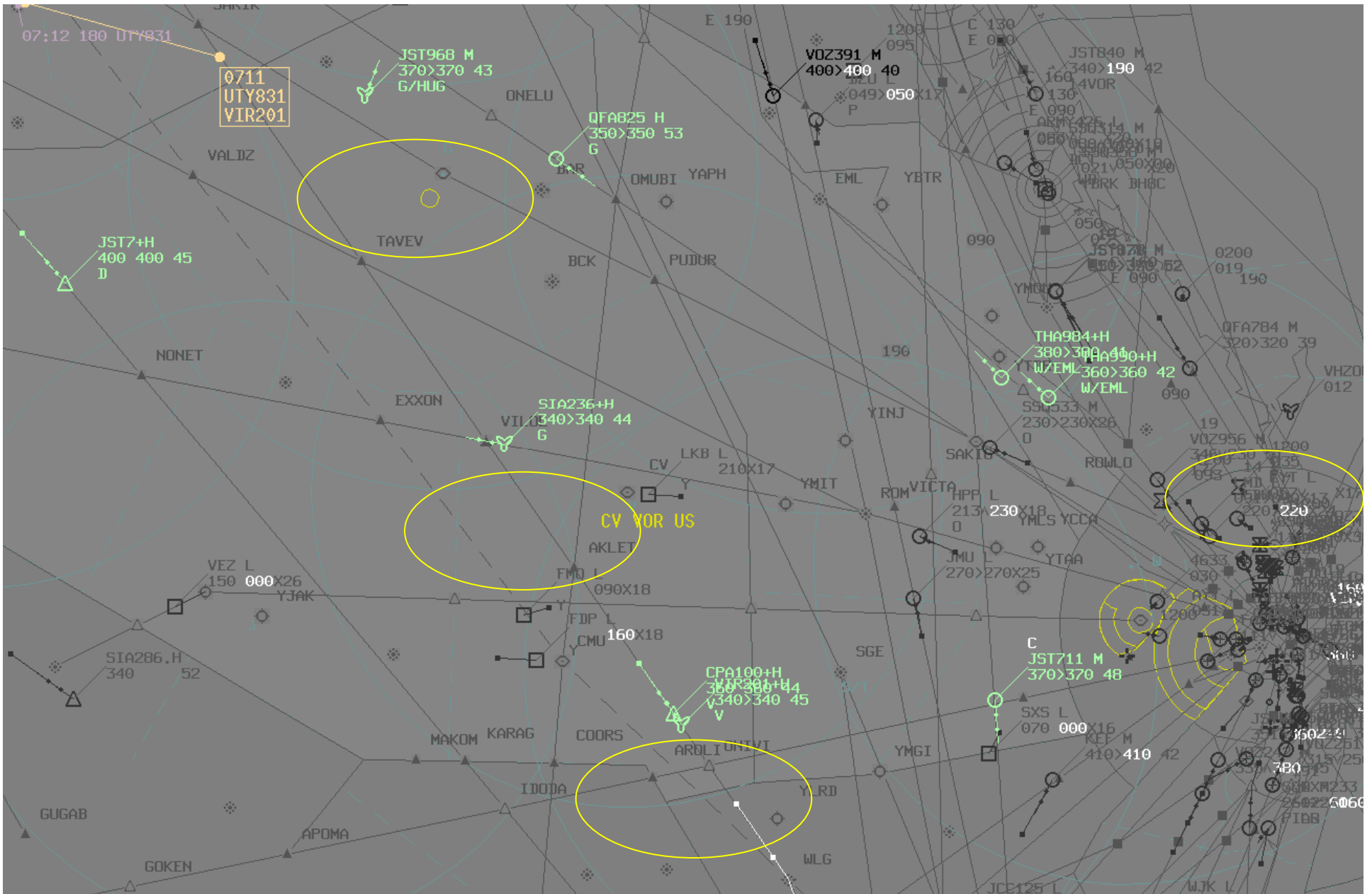












Conclusion

- Airservices Australia is the first ATC in the world to deploy ADS-B for operational use
- ADS-B implementation is more than simply installing ADS-B receivers
- ADS-B data must be fully integrated into ATCO HMI displays alongside radar, ADS-C and flight plan tracks
- Safety Cases and aircraft certification issues must be addressed
- SITA and Airservices Australia ADS-B Alliance could support ANSPs to develop implementation plans for operational ADS-B



Thanks!
For further details please contact
adriana.mattos@sitaaero.com

***Some of slides presented are partially or totally based on Australia
Airservices and Thales Eurocat system for Australian ATC Centers***

