



GLU-2100

Resilient Navigation



Collins Aerospace
An **RTX** Business

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Title: GNSS Resilience

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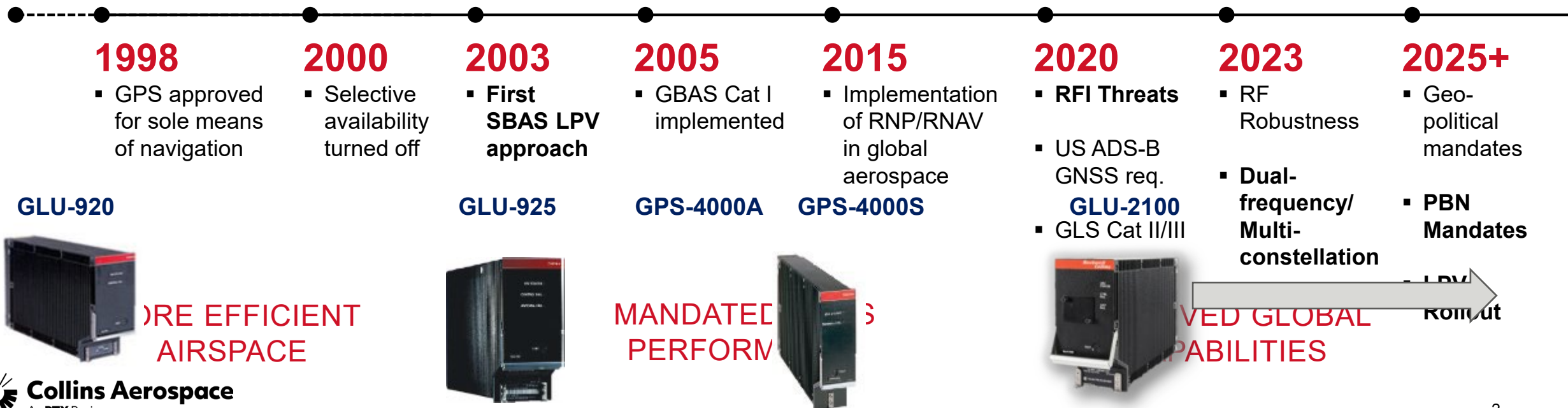
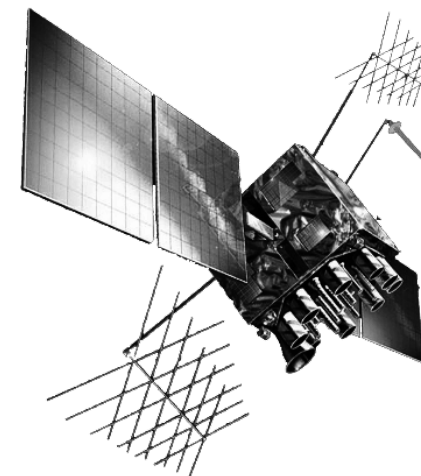
EVOLUTION OF GNSS NAVIGATION

ENHANCED NAVIGATION PERFORMANCE



July 1977

First GNSS signal received and decoded in Cedar Rapids, at Collins

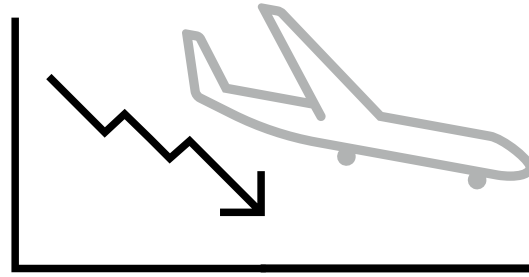


Navigation Challenges Being Faced



Evolving Airspace

- The challenges being solved today are different than what we'll face tomorrow



Aging Ground Infrastructure and Regional Changes

- Legacy solutions are aging and being phased out in favor of PBN requirements



Increased Jamming & Spoofing

- Intentional RFI has expanded at exponential rates in recent years

Landing globally is non-optional

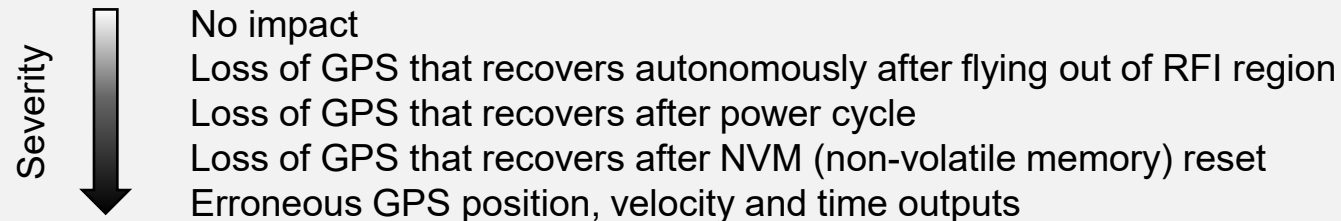
GNSS threats

70% of Commercial Air customers experience Radio Frequency Interference (RFI) on a weekly basis

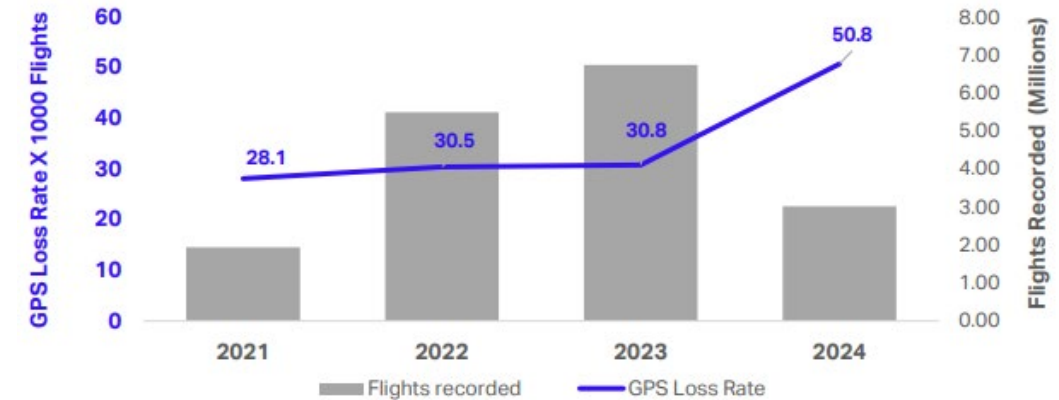
RFI reports from the Field in the last 2 years:

- Loss of GNSS for over 2 hours on flights over the Middle East
- Time jumps on flights over the Syria/Iraqi Airspace
- Corruption of GPS almanac on flights near the Baghdad airport
- Repeater based attacks on flights in Chinese Airspace
- GPS interference observed in the Dallas Area
- Spoofer attacks in the Baltic Region

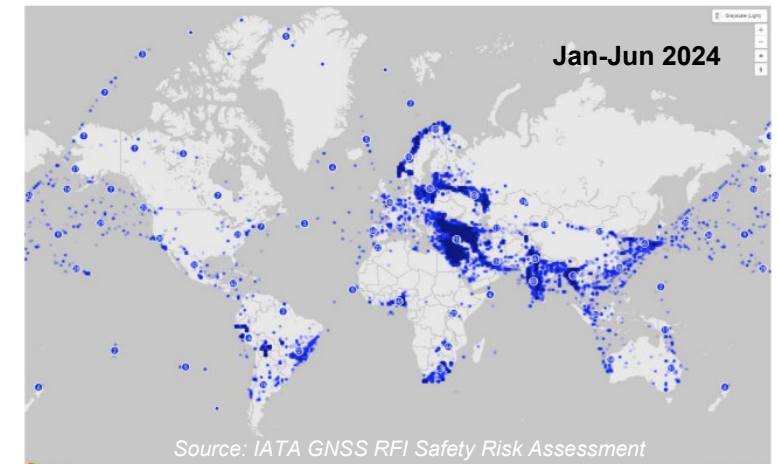
Impacts of RFI:



GPS loss is becoming more prevalent on commercial flights

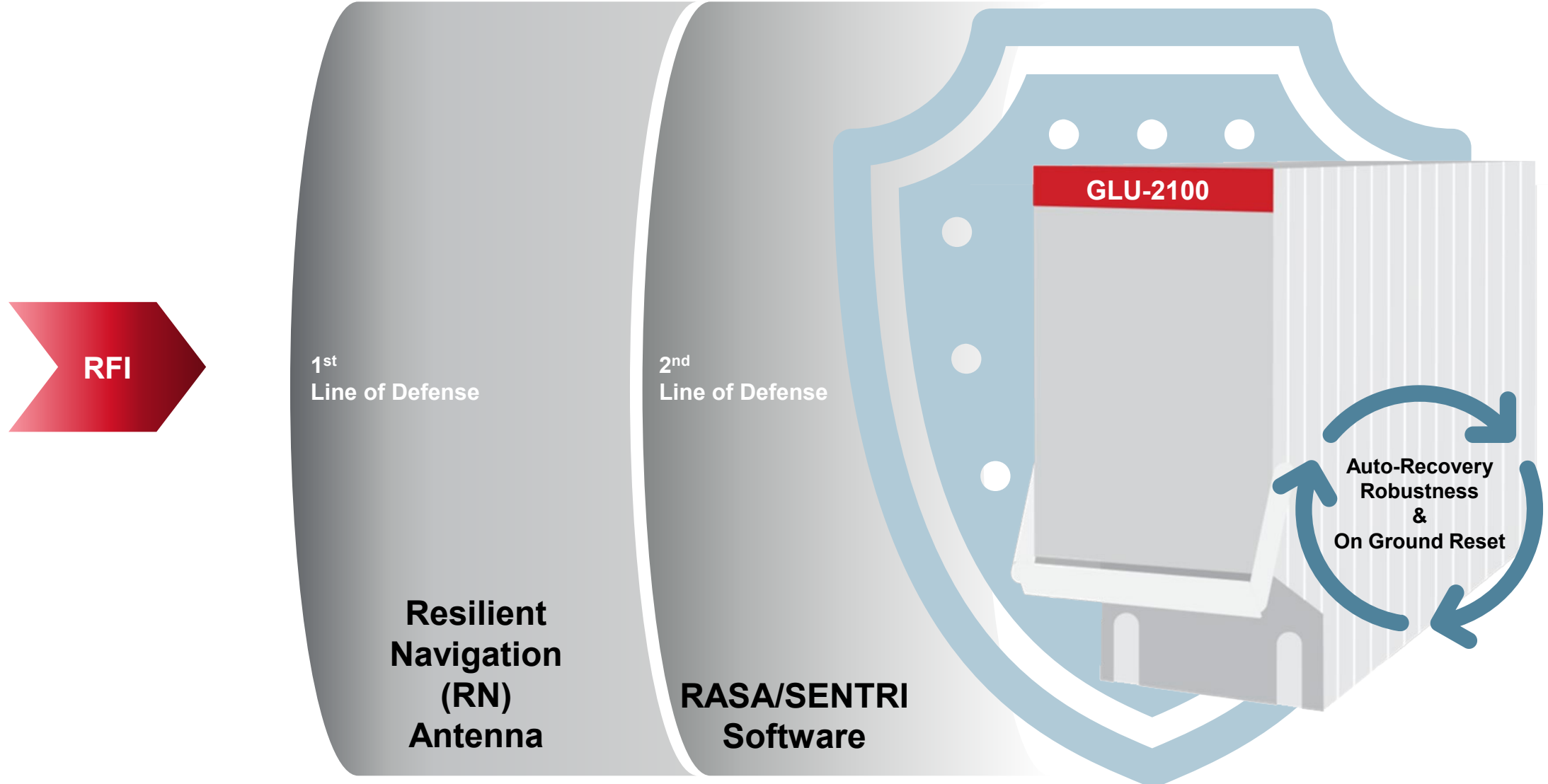


RFI is increasingly a worldwide concern



Jamming and Spoofing are real world issues demanding real solutions

Layered Approach



Collins GLU-2100 Multi-Mode Receiver (MMR)



- Growth Focused
 - Field-loadable, software-configurable packages
 - Adaptable to meet today and future needs: SBAS, LPV/SLS, RFI, DFMC, etc.
 - Future Development Capability Proven
 - Flew on [B777 Eco Demonstrator](#)
 - GLAD [Global ARAIM for Dual Constellation](#)
 - MUGG [Multi-Mode GPS and Galileo Project](#)
- Drop-in replacement for most existing MMRs
- Robust, DAL A hardware
- Reduced size, weight, & power requirements

Built for today – designed for tomorrow

GLU Software Capability Progression

			Current Software		
	GLU-925	GLU-2100 Initial Version	GLU-2100 V2.6 (Boeing) L4.2 (Airbus)	GLU-2100 Next SW With Optional Detection and Mitigation feature	GLU-2100 Planned Future SW
Field Loadable SW	No	Yes	Yes	Yes	Yes
SBAS	A350 GLU-925S Only	Yes*	Yes*	Yes*	Yes*
GLS CAT 1	Yes	Option Enabled	Option Enabled	Option Enabled	Option Enabled
VOR and Marker Beacon	No	Yes*	Yes*	Yes*	Yes*
GLS CAT 2/3	No	No	Option Supported*	Option Supported*	Option Supported*
LPV	A350 GLU-925S Only	No	Option Enabled	Option Enabled	Option Enabled
DO-229E	No	No	Yes	Yes	Yes
RFI Improvement Robustness Improvements	No	No	Good	Better	Best
RFI Detection and Mitigation SENTRI & RASA	No	No	No	Option Enabled	Option Enabled
DFMC	No	No	No	No	Option Enabled

*Options may vary by OEM and platform

An evolving software solution for evolving needs

Resilient GNSS Technology

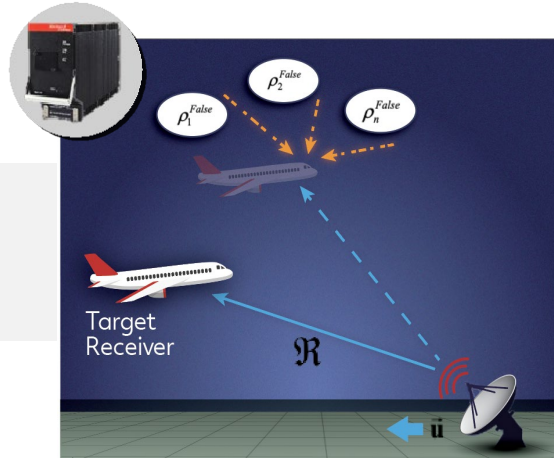
Current solutions for Commercial Aviation



GLU-2100 MMR

Multi-Mode Receiver

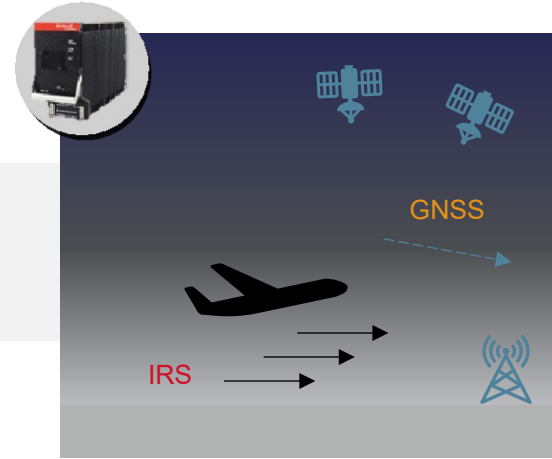
- Software-defined GNSS receiver
- Supports Satellite-Based Augmentation System (SBAS)
- Supports Ground-Based Augmentation System (GBAS)



RASA

Receiver Autonomous Signal Authentication

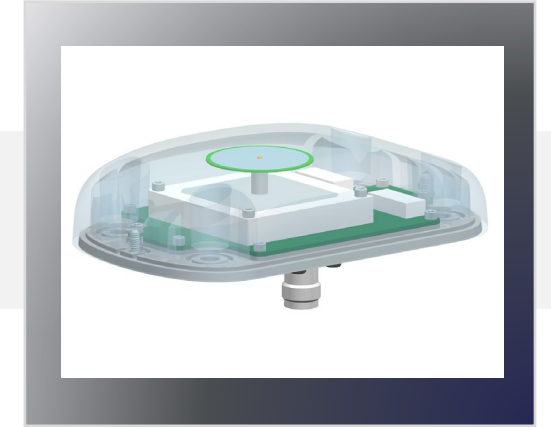
- Monitors receiver clock stability to detect spoofers



SENTRI

Staggered Examination Of Non-trusted Receiver Information

- Uses nav-grade Inertial Reference System (IRS) units on the aircraft together with GNSS data to detect spoofing



- ### Concentric CRPA
- #### 2-Element Controlled Reception Pattern Antenna
- Meets ARINC 743 footprint and connectivity
 - Retrofit compatible
 - Power Compatible
 - I/O to report Nulling Status
 - Field loadable

Addresses jamming and spoofing challenges in commercial aviation



RFI Detection and Mitigation Software In Development

UPCOMING SOFTWARE UPGRADE PACKAGE

- RFI Detection and Mitigation features introduced via field-loadable software update
- Utilizes the following techniques:
 - SENTRI (IRS-Aided Spoofer Detection)
 - RASA (Effect of Spoofer on receiver clock estimate)
 - Miscellaneous robustness improvements that handle corrupted time, ephemeris and almanac.
- Position error bounds (integrity levels) computed during coasting and when protecting against Spoofers
- Fine control of RFI detection and mitigation features using the OSS
- An antenna change is not required

Next Software Package Introduces RFI Detection and Mitigation capability



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Prototyping: RFI First Line of Defense

Resilient Navigation (RN) Antenna Solution

- Resilient Navigation antenna prototype underway at Collins
 - Prototypes are being tested for effectiveness in spoofing and jamming scenarios
 - Viability currently being determined
 - Navfest 2025 – positive results
 - Jammertest 2025 – positive results
 - Operator installing prototypes – performance data expected by early 2026
- Expected to be a drop-in replacement of existing GPS antenna
 - Dependent on regulatory and OEM design requirements



More information + timeline coming soon

Two-Fold Approach: Strong Defense



Defenders: RN Antenna



Goalie: RASA/SENTRI

- Will keep RFI (jamming & spoofing) from reaching the receiver most of the time
 - No anti-jam or CRPA antenna is foolproof

- Last defense to defend the receiver from a spoofed signal
 - Prevents corrupt PVT from being used and distributed to the flight deck

Need both for a solid defense against RFI



MULTI mode GPS and Galileo project MUGG



GLU-2100 Future Potential Options

Evaluating & Prototyping

- Dual Frequency / Multi-Constellation Option (DFMC)
 - Upgradable via software and dual-frequency antenna
 - Additional navigation modes
 - Further RFI improvements
- MUGG Project
 - Extensive DFMC work being done by Collins in support of the European Global Navigation Satellite System Agency (GSA)

Exploration

- Alternate Position Navigation and Timing (APNT)
 - Use of non-GNSS APNT sources
 - Dependent on industry alignment, regulatory acceptance, and OEM Integration

GLU-2100 designed to grow for continued future flexibility

MUGG Project: GLU-2100 → DFMC Prototype

- The MUGG DFMC Prototype is built from Collins GLU-2100 Product and includes:
 - New navigation modes: DFMC SBAS PA/NPA, DFMC H-ARAIM, L5 H-ARAIM
 - Implementation of ED-259A MOPS acquisition and tracking requirements
 - Optimizations to DSP functions and resource re-allocations
 - Specific forced modes for test purposes...
- Why DFMC?
 - GPS L1/L5 and Galileo E1/E5a
 - Integrity of the GNSS solution is increased, meaning more trust can be placed in the accuracy of the PVT
 - Accuracy is improved thanks to less noisy measurements and the ability to remove some error sources such as ionospheric delay
 - Specifically in aviation, there is the possibility to operate at more airports in locations with limited or no ground-based landing systems or SBAS coverage
 - Increased resilience in case of an L1/E1 outage



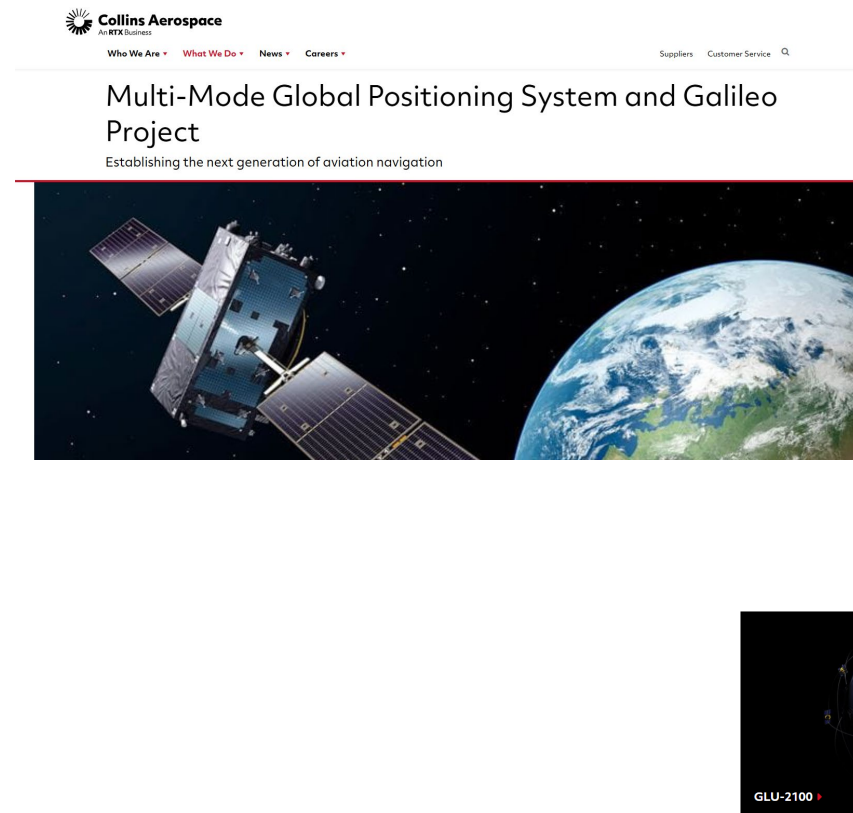
Project main achievements

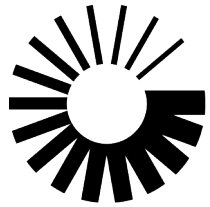
- HARAIM
 - For the first time on the certified platform GLU-2100, H-ARAIM developed in the scope of MUGG have been demonstrated in a representative operational conditions
 - With improved Pconst for the Galileo constellation, a significant improvement for the Protection Levels performance would be achieved: down to 20 meters
- SBAS DFMC
 - MUGG project demonstrated the implementation of DFMC SBAS capability on an Avionics certified hardware platform
 - Comparison of L1 SBAS, GPS L1L5 SBAS and DFMC SBAS shows significant improvement for LPV and CAT1 coverage
- Implementation of MOPS in a representative avionics receiver is key to mature/consolidate MOPS requirements

For further information...

- MUGG project website:

[Multi-Mode Global Positioning System and Galileo Project | Collins Aerospace](#)





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Thank You!