

The Free Route Airspace Implementation Workshop / 2

Bangkok, Thailand

13th Nov 2024

This event is jointly organised with





ICAO

FREE ROUTE OPERATION (FRT0) TRAINING FOR ATC

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EVP of ANS Planning & Development – AirNav Indonesia

FREE ROUTE OPERATION ≠ FREE FLIGHT



Technically all flights continue under controlled by ATC

FREE ROUTE OPERATION

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IMPACT ON ATC

AIRSPACE
ORGANISATION

CONFLICT
MANAGEMENT

ATC PROCEDURES

COORDINATION
PROCEDURES

WORKING METHOD

TRAINING NEEDS

FRT0 CONCEPT

AIRSPACE
MANAGEMENT IN FRT0

PBN FOR ATC

ATC PROCEDURES

FLIGHT PLANNING

COORDINATION
PROCEDURES

ATMAS - HUMAN
MACHINE INTERFACE

CONFLICT DETECTION
TOOLS

AIR SITUATION DISPLAY

TOWARDS TRAJECTORY
BASED OPERATION

ATC PROCEDURES

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- Separation Minima
- Phraseology
- Contingency procedures
- Human Machine Interface (HMI)
- FPL

Implementation
of FRT0
**DOES NOT
CHANGE
CURRENT
APPLICABLE
ATC
procedures!**

ATCO need to familiar with the COMPLEXITIES of FRT0 CONCEPT, increase SITUATIONAL AWARENESS, and optimizing ATM Automation System (ATMAS) tools & features

FRT0
CONCEPT

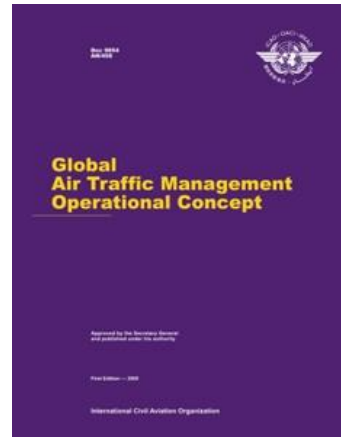
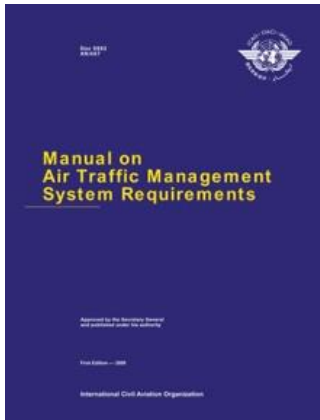
REFRESH
TRAINING

SIMULATION

FRT0 CONCEPT

DEFINITION: FRA, FRT0, UPR

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FRA

A specific airspace within which airspace users may freely PLAN a route between a defined entry point and a defined exit point with the possibility to route via intermediate way points without referring to the ATS route network.

FRT0

An airspace design concept where aircraft can plan their routes freely within a specified airspace, without being constrained by fixed airways

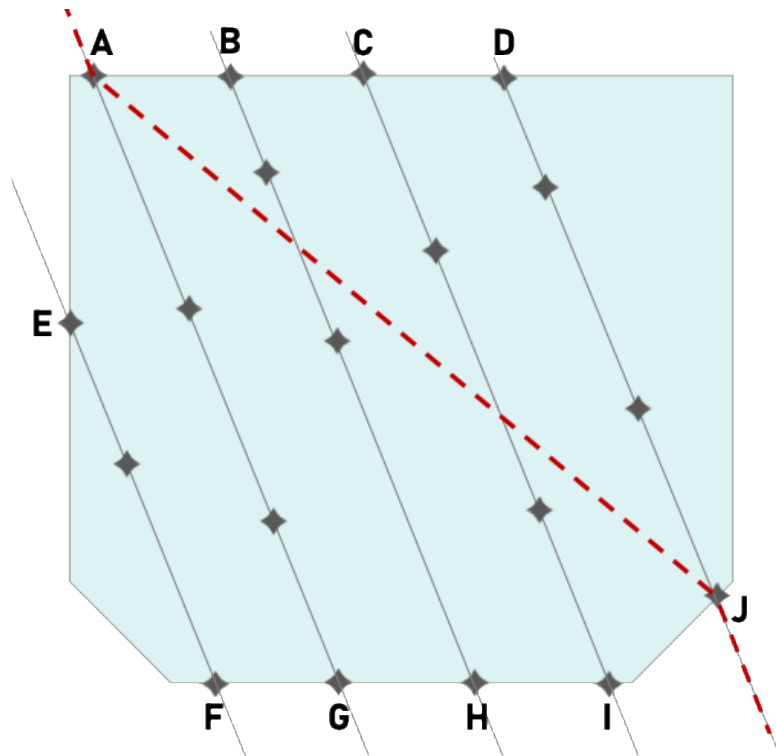
UPR

A flight path chosen by an aircraft operator based on operational preferences, typically for efficiency, time savings, or fuel optimization, while still adhering to airspace constraints and ATC requirements.

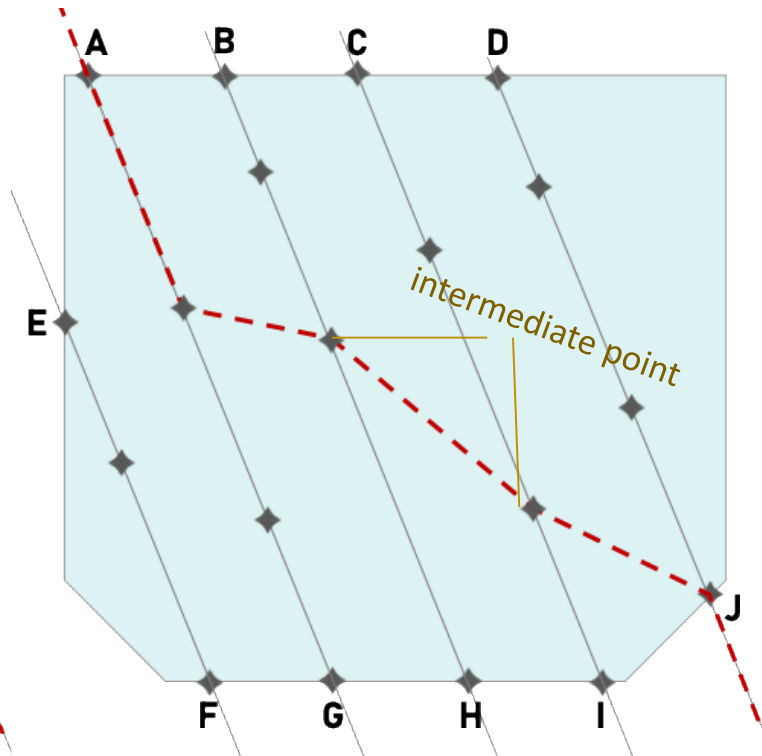
TYPES OF FRTO

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DIRECT ROUTE OPERATION (DRO)

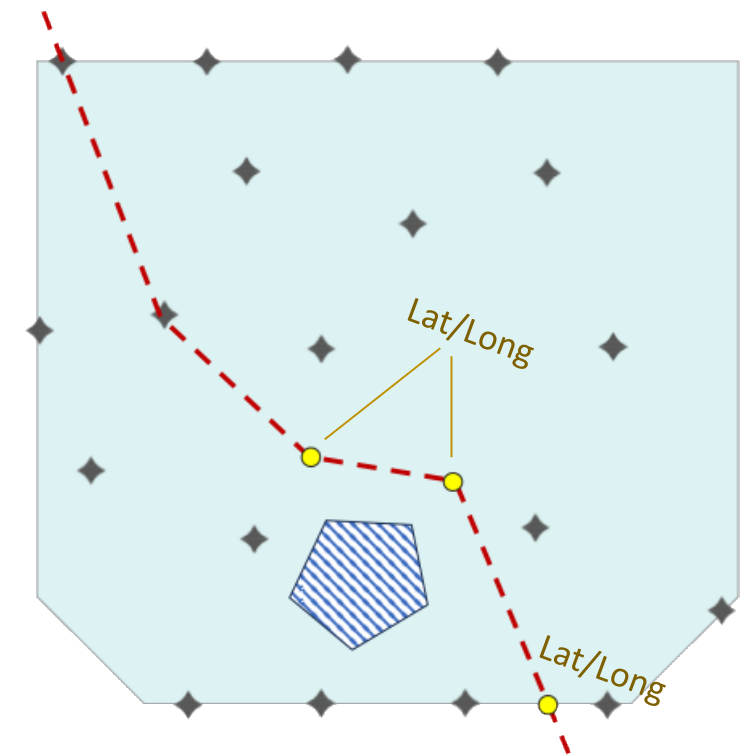


Direct ENTRY to EXIT



Direct via Intermediate Point

FREE ROUTE OPERATION (FRTO)



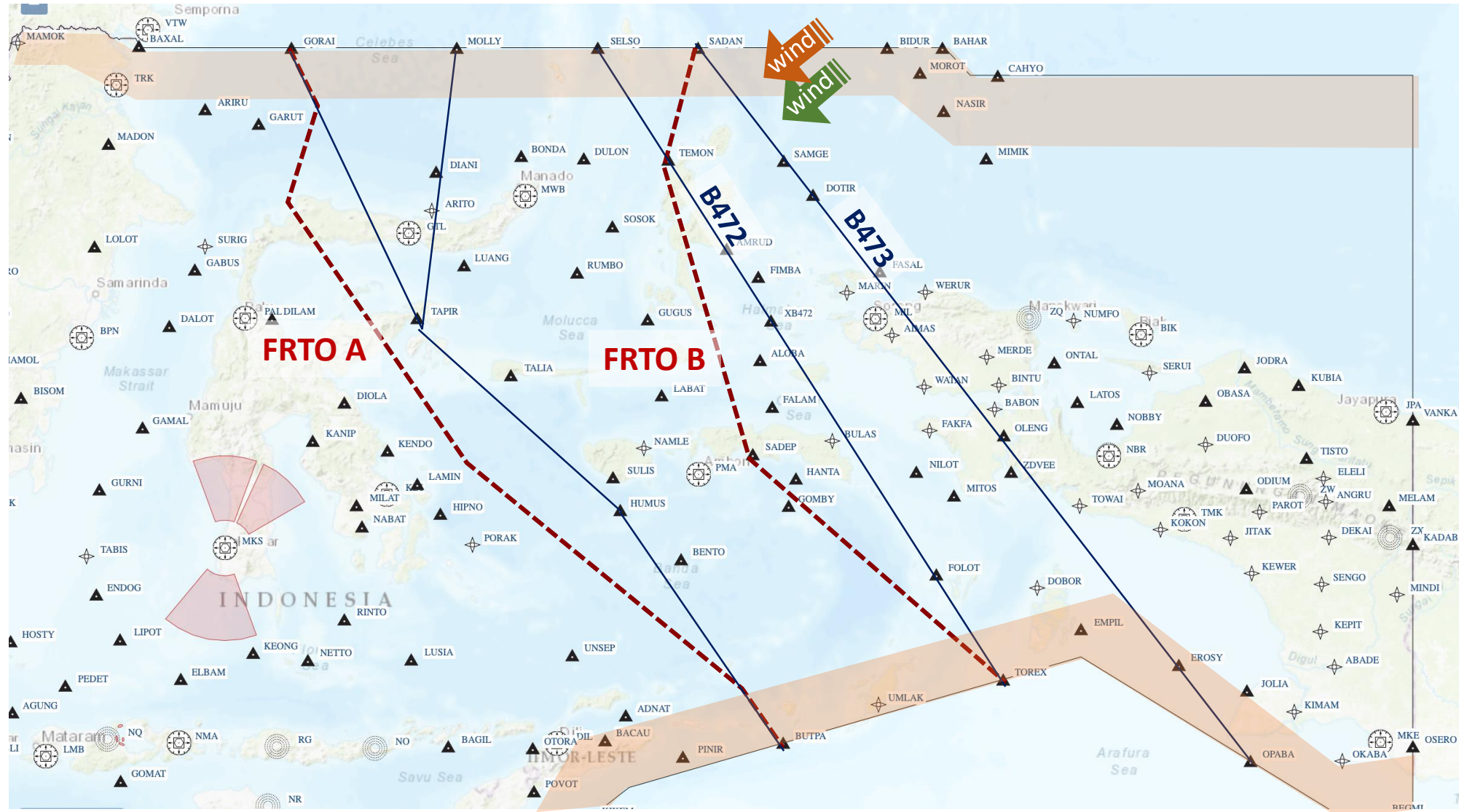
Free Route using LAT/LONG

UNDERSTANDING FRT0 RULES

AIRSPACE MANAGEMENT	TRAJECTORY CONSTRUCTION RULES	TYPE OF FLIGHT	FUA
Vertical Limit	FRT0 types	Domestic	Avoid PRD
Horizontal Limit	Duration without point	International	Conditional routes
Near boundary ops	Lat/long at boundary	Overflying	
Cross border	Lat/long at designated		

EXAMPLE OF FRTO TRAJECTORY

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FRA - Bringing the World Together

CONFLICT MANAGEMENT

[illegible]

 **Dynamic hot spot**

- ## FRA - Bringing the World Together

SEPARATION APPLICATION

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SURVEILLANCE ENVIRONMENT



- Apply standard surveillance separation minima: 5NM or 10NM or as applicable
- Control technique: Vectoring

PROCEDURAL ENVIRONMENT

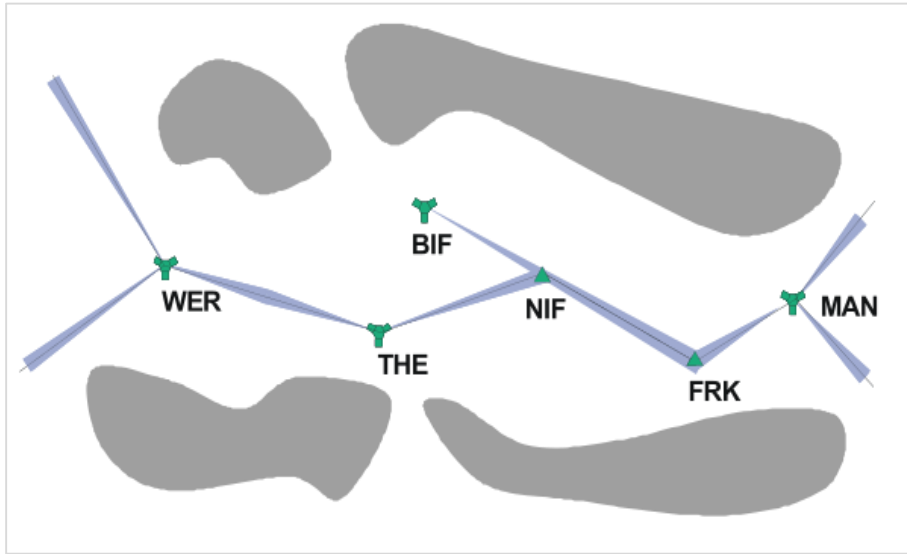


- ❑ Apply procedural and PBN (+ PBCS) separation
 - ❑ Lateral separation
 - ❑ Longitudinal
- ❑ Control technique
 - ❑ Time restriction
 - ❑ Distance reporting

PBN FOR ATC

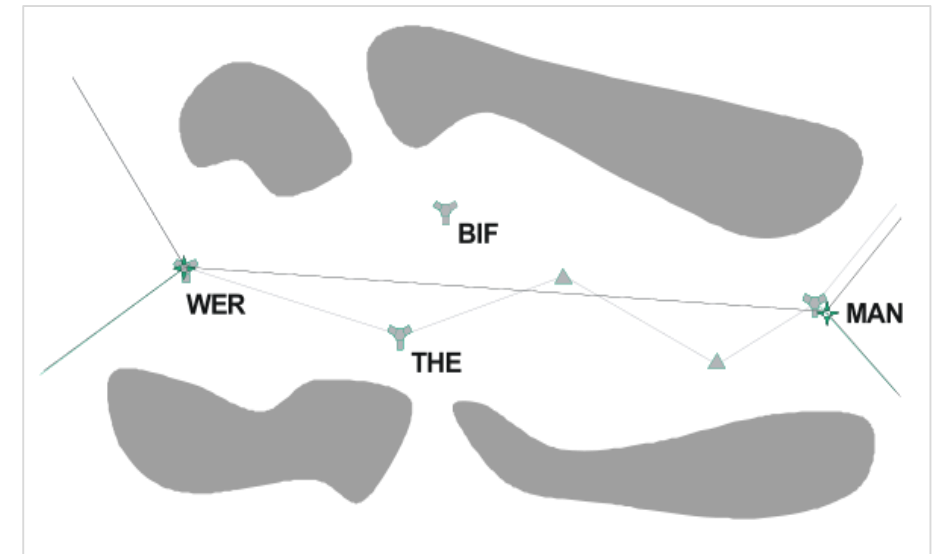
PBN AS FRT0 ENABLER

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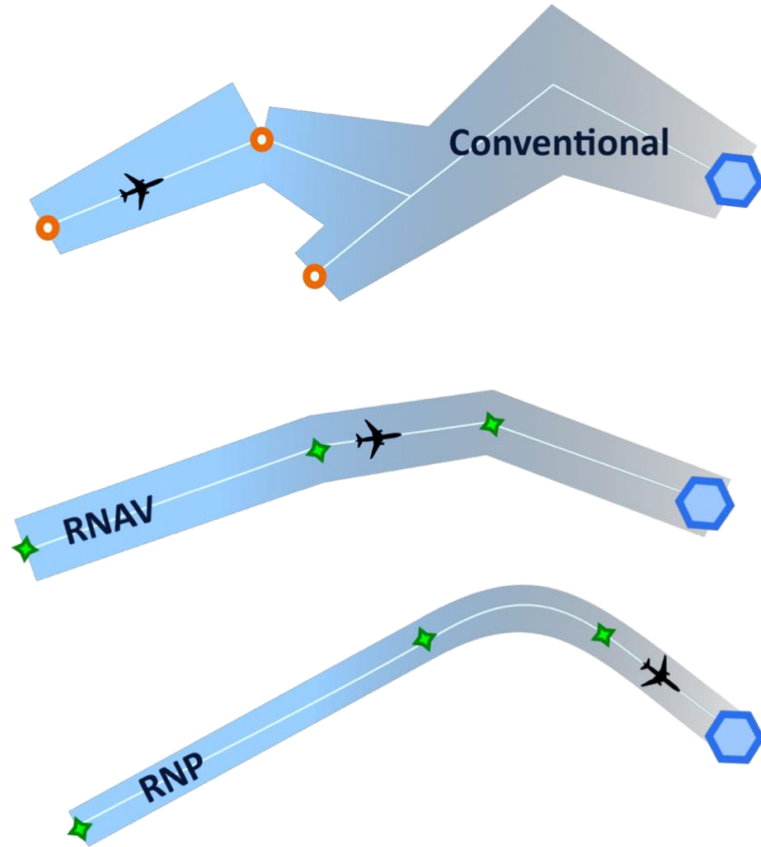
Performance Based Navigation (PBN) is an area navigation based on performance requirements for aircraft operating along an ATS route, on an instrument approach procedure or in a designated airspace.

Area navigation principles permit aircraft operation on any desired flight path within the coverage of ground or space based navigation aids or within the limits of the avionics onboard the aircraft, or a combination of these



PBN FOR ATC TRAINING

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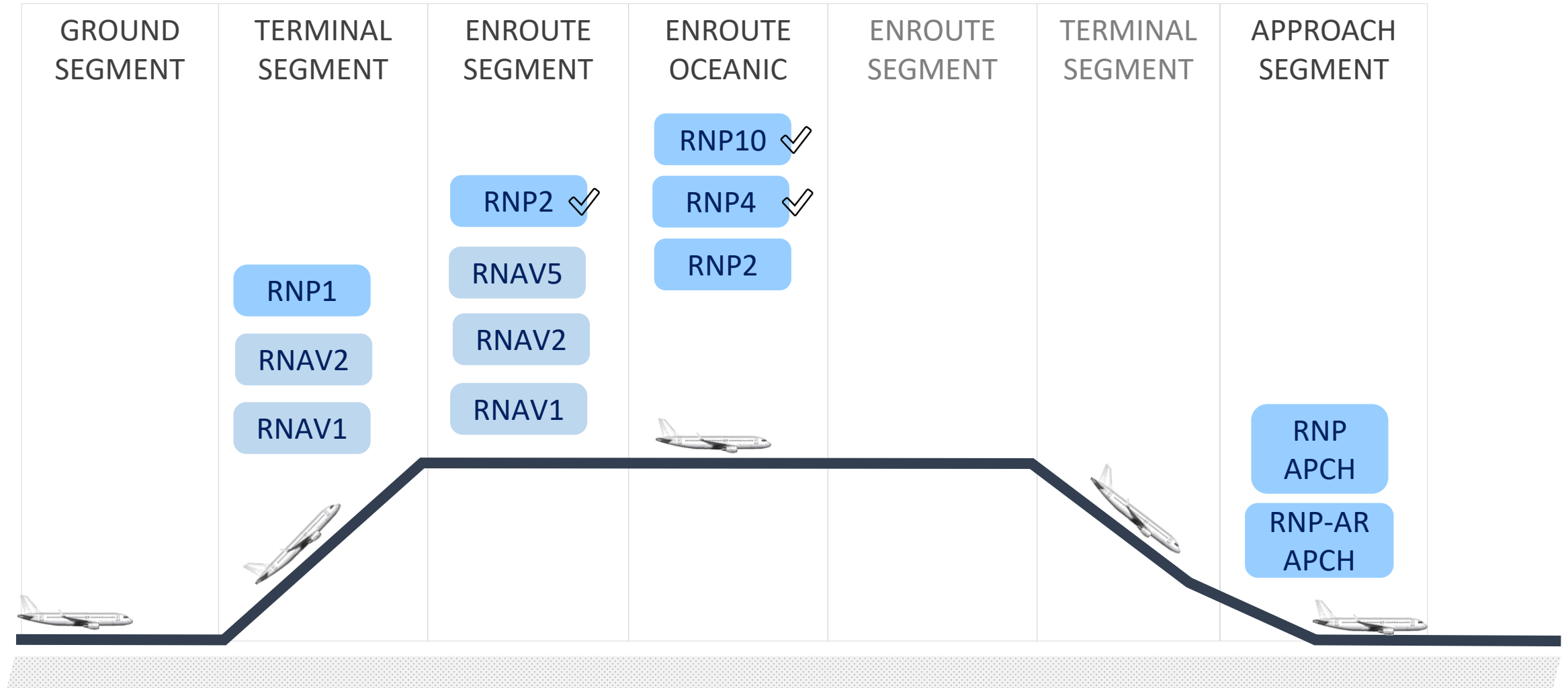


- Based on ICAO PBN Document 9613 Volume II Part B and Part C section x.2.6, PBN training for ATC consist of:
 - Core Training
 - Navigation Specification training

CORE TRAINING	NAVSPEC TRAINING
<ol style="list-style-type: none">1. How area navigation system works in this area2. Flight plan requirements3. ATC procedures<ol style="list-style-type: none">a. ATC Contingency proceduresb. Separation minimac. Mixed equipped environmentd. Transition between different operating environmente. Phraseology	<i>[depends on the PBN navigation specification implemented in your airspace]</i>

NAVIGATION SPECIFICATION APPLICATION

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✓ Implemented = specific training needs

SPECIFIC NAVIGATION SPECIFICATION TRAINING

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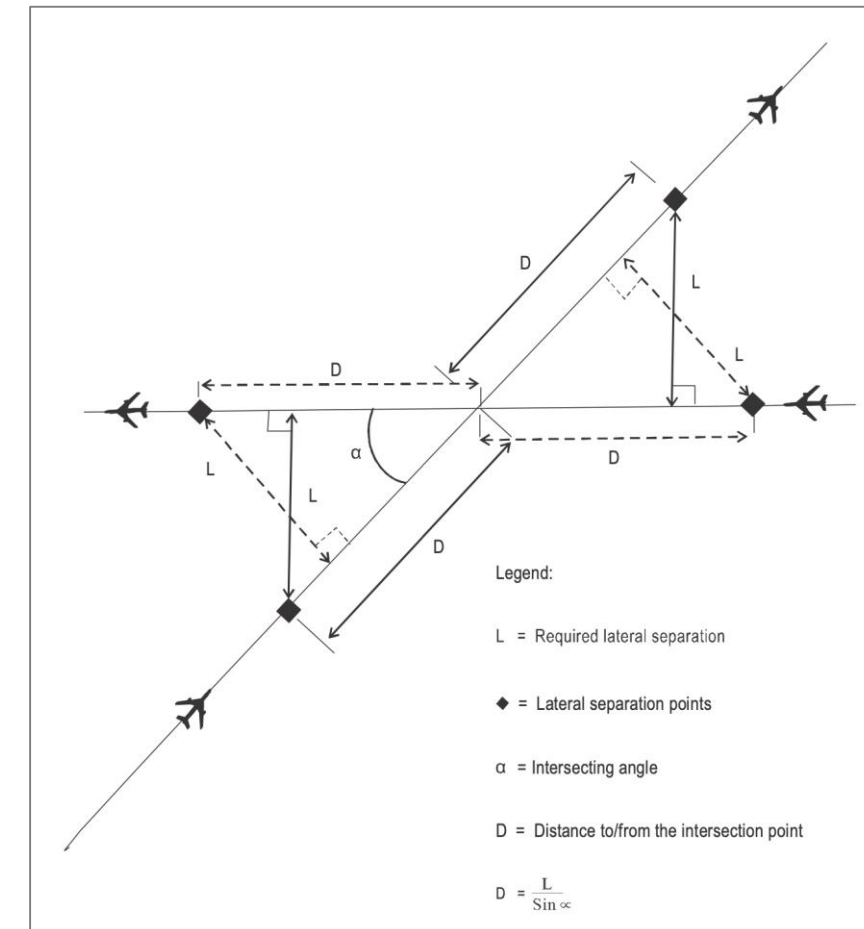
RNP/RNAV 10	RNAV2 (ENROUTE)	RNP4
<ol style="list-style-type: none">1. Functional capabilities and limitation of RNP/RNAV 102. Accuracy, integrity, availability & continuity3. GPS receiver, RAIM, fault detection and exclusion (FDE) and integrity alerts4. Reporting of gross navigation error	<ol style="list-style-type: none">1. Functional capabilities and limitation of RNAV 22. Accuracy, integrity, availability & continuity3. GPS receiver, RAIM, FDE and integrity alerts4. Waypoint fly-by versus fly-over concept (and differences in turn performance)	<ol style="list-style-type: none">1. Functional capabilities & limitation of RNP 42. Accuracy, integrity, availability and continuity including on-board performance monitoring and alerting3. GPS receiver, RAIM, FDE and integrity alerts4. Waypoint fly-by versus fly-over5. For application 30/30 separation minima<ol style="list-style-type: none">a. CPDLC communicationb. ADS-C system and simulation trainingc. Effect of periodic reporting delay/failure on longitudinal separation.

PBN SEPARATION

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ICAO Doc 4444 PANS-ATM 16th Edition, Chapter V (separation) ICAO introduce application of **PBN separation minima** which are not sensor based (like VOR, VOR/DME) but **performance requirement based** (RNP, RCP, RSP).

- Lateral separation between aircraft operating on intersecting tracks or ATS routes shall be established in accordance with the following.
 - an aircraft converging with the track of another aircraft is laterally separated until it reaches a lateral separation point that is located a specified distance measured perpendicularly from the track of the other aircraft; and
 - an aircraft diverging from the track of another aircraft is laterally separated after passing a lateral separation point that is located a specified distance measured perpendicularly from the track of the other aircraft.



Navigation	Separation
RNAV 10 (RNP 10)	93 km (50 NM)
RNP 4	42.6 km (23 NM)
RNP 2	27.8 km (15 NM)

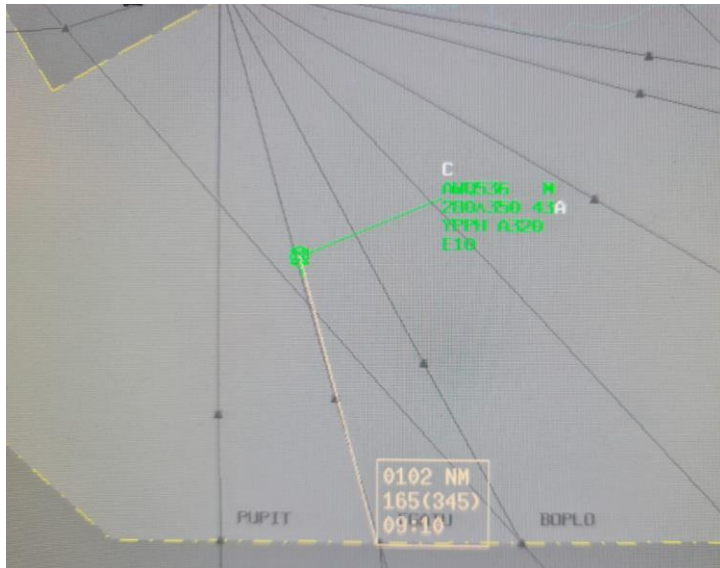
ATMAS FEATURE

BRL & FPCP

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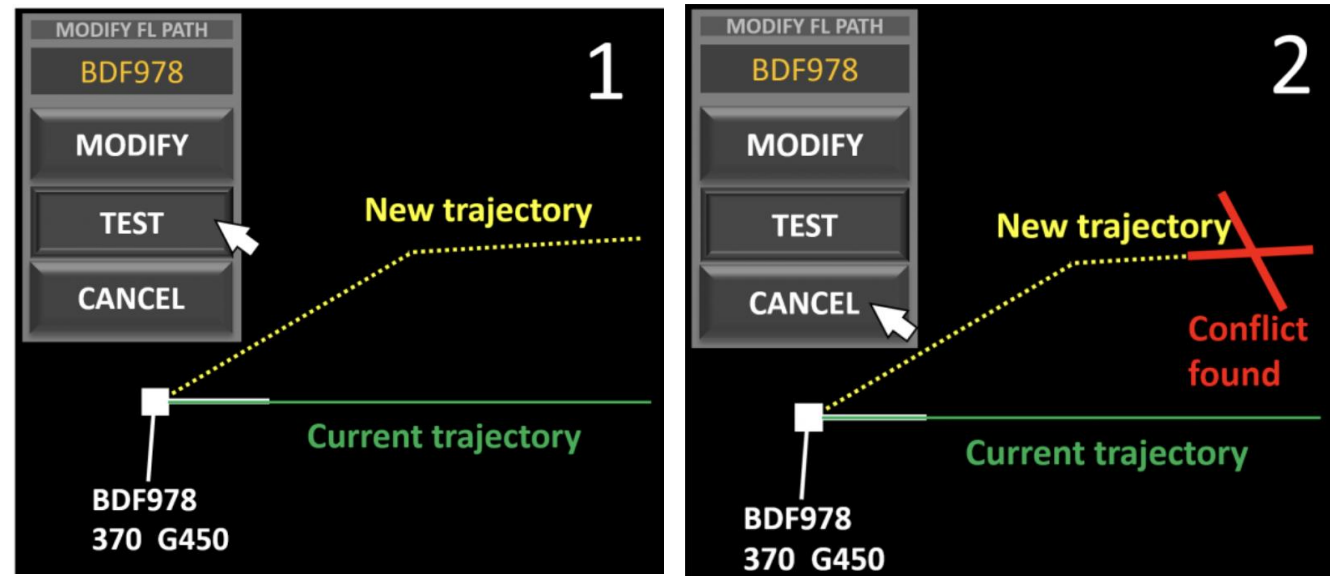
BEARING AND RANGE LINE (BRL)

It provides a means of measuring the bearing (direction) and distance between map locations and aircraft. It also provides a time estimate for an aircraft at a point.



FLIGHT PLAN CONFLICT PROBE (FPCP)

It provides data for a display to air traffic controllers whenever any two aircraft are predicted to approach each other within certain separation criteria in the horizontal and vertical dimensions

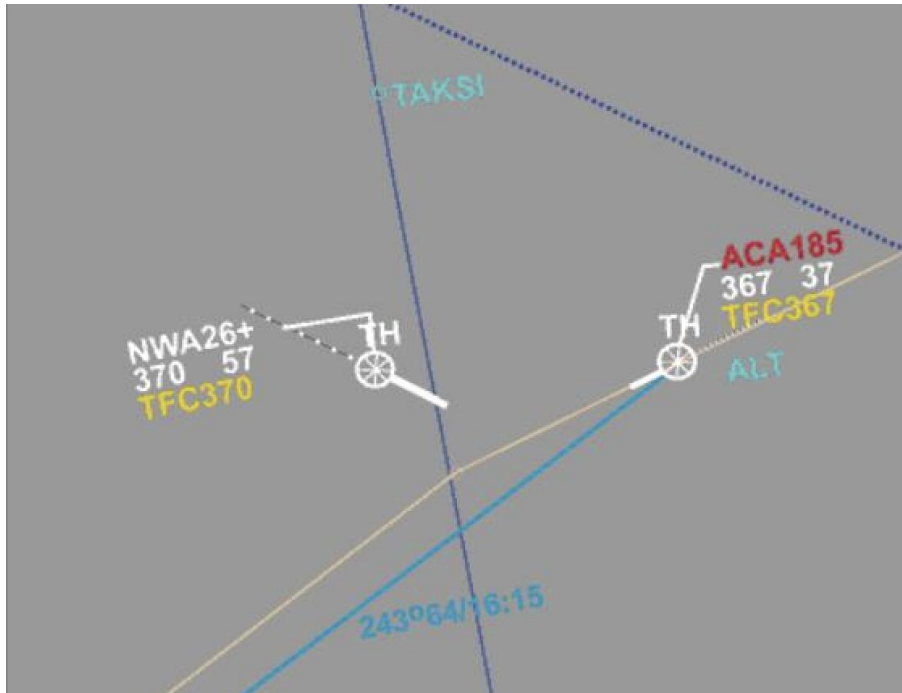


MTCD & TCT

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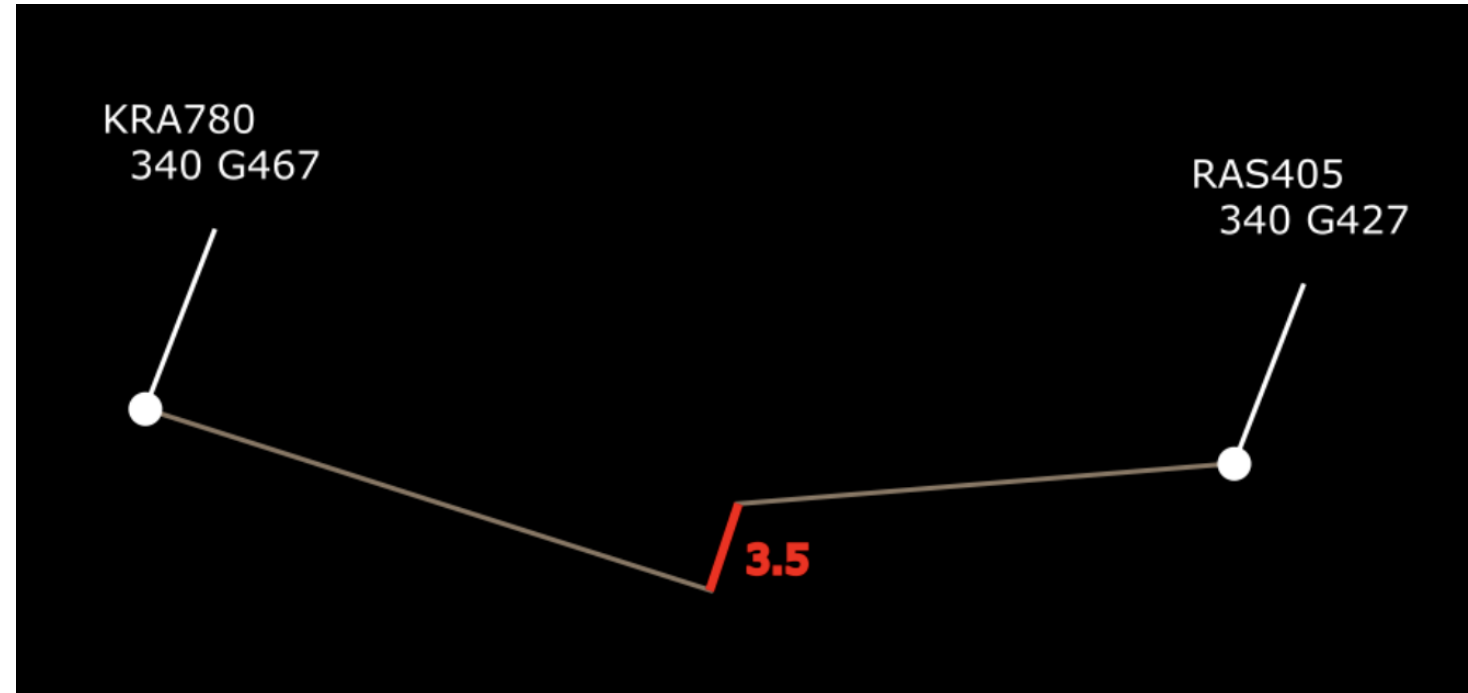
MEDIUM TERM CONFLICT DETECTION (MTCD)

MTCD is a flight data processing system added functionality designed to warn the controller of potential conflict between flights in his area of responsibility in a time horizon extending up to 20 minutes ahead.



TACTICAL CONTROLLER TOOL (TCT)

TCT warns the executive (tactical) controller of potential conflicts within the sector. To do this it usually combines current aircraft tracks with an accurate tactical trajectory that reflects the aircraft's current behaviour.

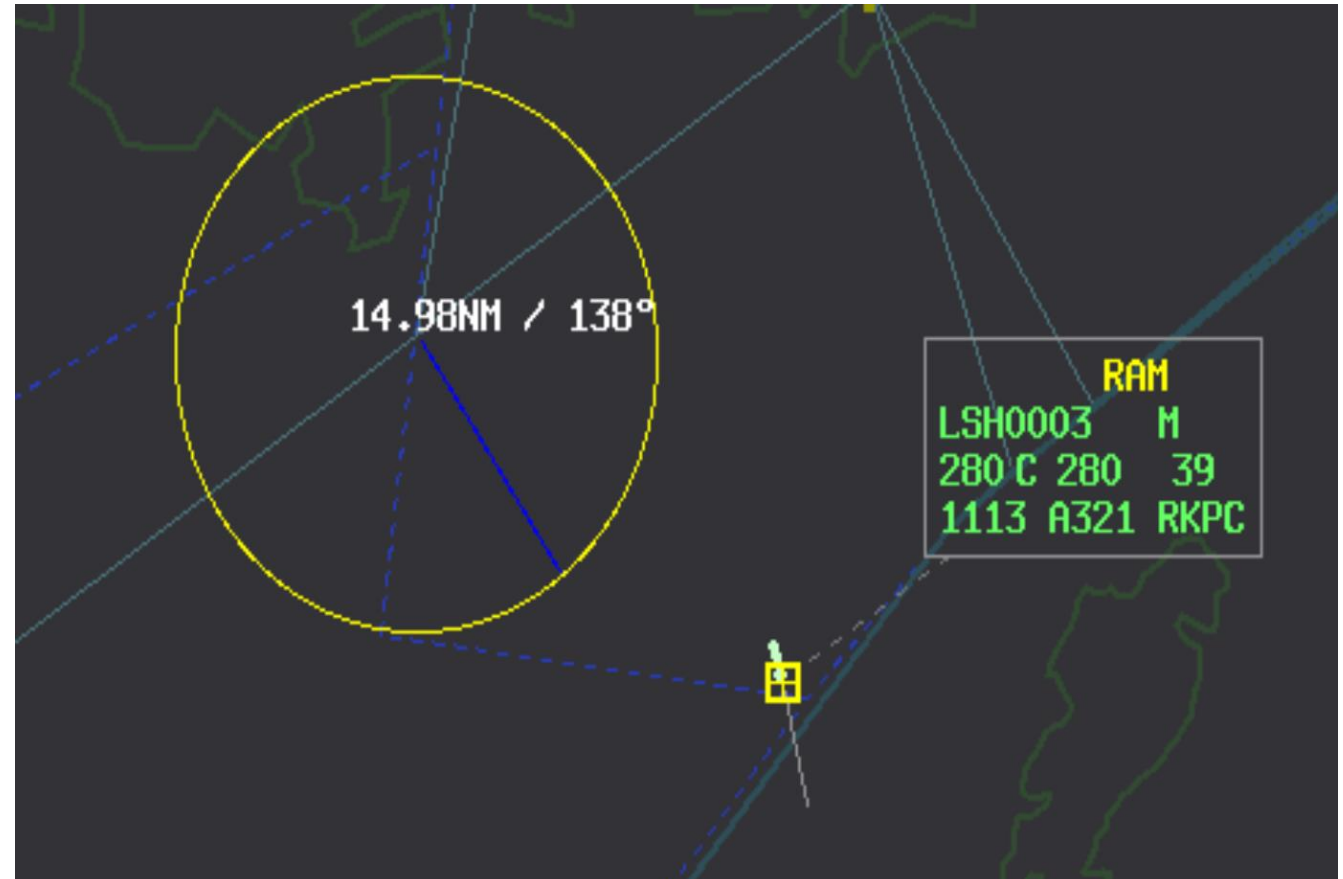


SAFETY NET: ROUTE ADHERENCE MONITORING

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Route Adherence Monitoring (RAM) is a controller advisory tool designed to assist in the early identification of a variation between the actual and the expected trajectory.).

In FRT0 where the trajectory of aircraft may not align with ATS route, RAM provides advance warning for controllers, in case of lateral deviation which COULD LEAD TO LOSS OF SEPARATION (the aircraft turns towards another one) or AIRSPACE INFRINGEMENT (the aircraft turns towards an area reservation or a volume of controlled airspace).



FLIGHT PLANNING

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FLIGHT PLAN PLAN DE VOL			
PRIORITY Priorité FF		ADDRESSEE(S) Destinataire(s)	
FILING TIME Heure de dépôt		ORIGINATOR Expéditeur	
SPECIFIC IDENTIFICATION OF ADDRESSEE(S) AND/OR ORIGINATOR Identification précise du(des) destinataire(s) et/ou de l'expéditeur			
3 MESSAGE TYPE Type de message (FPL)	7 AIRCRAFT IDENTIFICATION Identification de l'aéronef	8 FLIGHT RULES Règles de vol	TYPE OF FLIGHT Type de vol
9 NUMBER Nombre	TYPE OF AIRCRAFT Type d'aéronef	WAKE TURBULENCE CAT. Cat. de turbulence de sillage	10 EQUIPMENT Équipement
13 DEPARTURE AERODROME Aérodrome de départ	TIME Heure		
15 CRUISING SPEED Vitesse croisière	LEVEL Niveau	ROUTE Route	
16 DESTINATION AERODROME Aérodrome de destination		TOTAL EET Durée totale estimée HR MIN	2ND ALTN AERODROME 2 ^e aérodrome de dégagement
18 OTHER INFORMATION Renseignements divers			

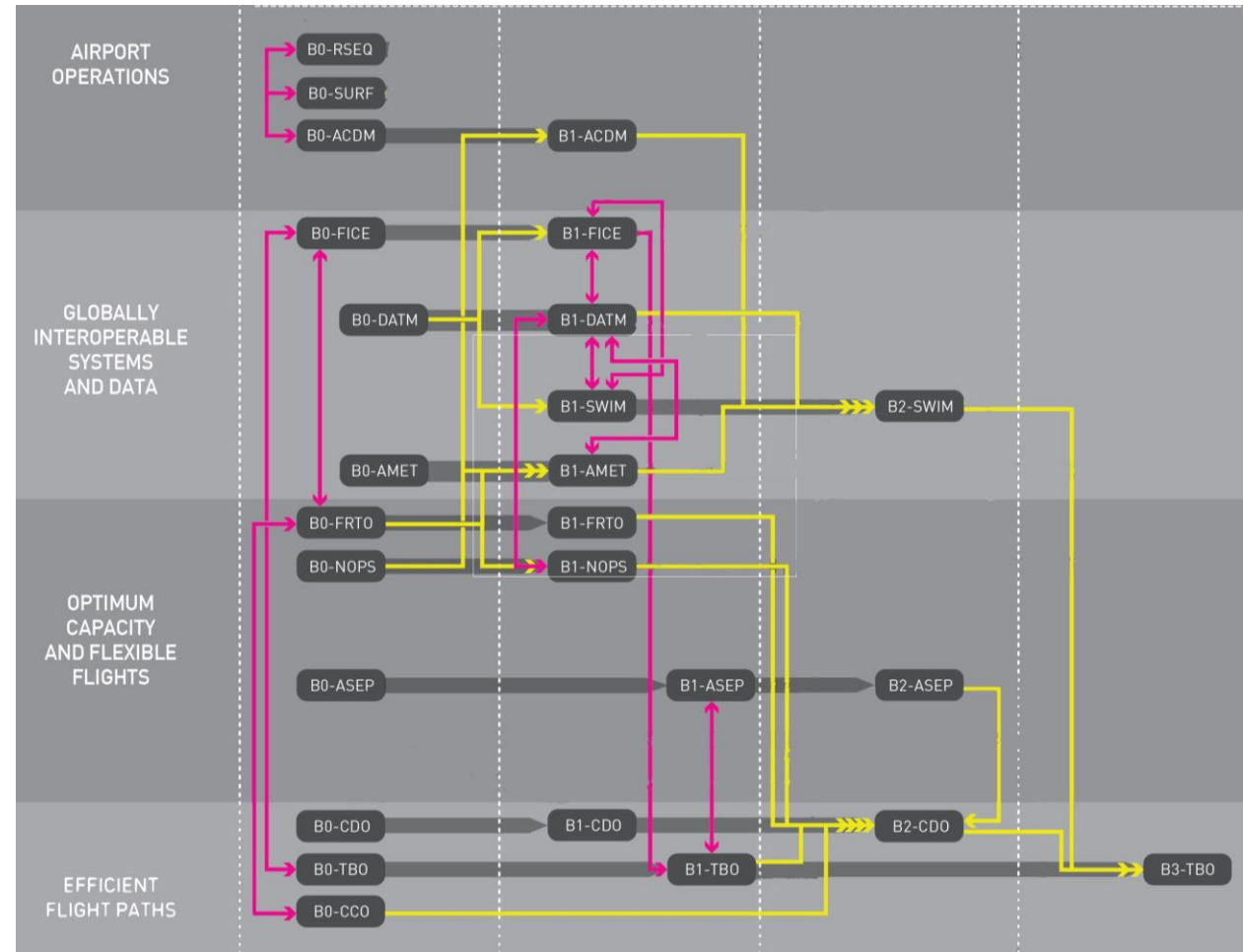
Flight planning check item depending on the FRT0 Rules & Requirement:

- Equipment: item 10
 - PBN, ADS-C, CPDLC, etc.
- Trajectory rules: item 15
 - Entry/Exit point
 - Intermediate point
 - Designated point
- Identifying FRT0 flights
 - Remark for flying FRT0 (item 18), example: RMK/UPRINA

TOWARDS TRAJECTORY-BASED OPERATION

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- FRT0 directly supports Trajectory Based Operation (TBO) by giving aircraft more flexibility to plan their own optimal routes, which, in turn, supports collaborative trajectory negotiation.
- Trajectory Based Operation (TBO) represents a paradigm shift in air traffic management by focusing on the management of aircraft trajectories in four dimensions: latitude, longitude, altitude, and time.
- This is achieved through the use of advanced data exchange systems, predictive algorithms, and real-time communication between aircraft and ground systems



ASBU Dependencies (ICAO Doc. 9750 V.5 2016)

KEY TAKEAWAYS

- Free Route is not a free flight. (Currently), aircraft flying FRT0 is still controlled by ATC
- FRT0 implementation does not change most ATC related procedure, however it needs to adapt to FRT0 rules;
- Build training syllabus including simulator exercise that fit with FRT0 rules which are implemented
- Optimize ATM automation system features to support ATC operation managing FRT0
- Introduce simple rules, gradually to more complex FRT0 rules



Thank You