

CELEBRATING 70 YEARS OF THE CHICAGO CONVENTION

PANS-OPS Flight Procedure Design Training for CAAs

23 August – 03 September 2021



CELEBRATING 70 YEARS OF THE CHICAGO CONVENTION

14 – PBN departures (Doc. 8168, Vol. 2, Part I, Section 3, Part III, Sections 1 & 3)





- 1. General
- 2. Straight departure
- 3. Turning departures
- 4. Design methodology
- 5. Protection





General criteria apply as amplified or modified here; What is remaining?

TOER;

Area1;

15° max change of track for straight departure;

Bank angle : 15°;

Bank angle delay (if needed) : 3s;

Pilot reaction : 3s;

Climb gradien;

𝐨MOC;

Average flight path for nominal trajectory;

Turn at an altitude;







What is new (specific to PBN departure)?

- Minimum distances;
- Turn at FB WP;
- Turn at FO WP;
- Use of wind spiral for all turn protections;
- Max turn angle :120° (except for DF);
- No bank angle delay for a fly-by WP;
- Protection deals with max TAS and low TAS.
- PBN applications:
 - RNP 1, RNAV 1, RNAV 2;
 - Amended RF turn protection
 - Minimum turn angle: 5° (except where free turn back to waypoint (DF leg used)





Criteria for initial departure:

IS NM ARP.

Criteria for terminal departure:

Within less than 30 NM around ARP;WHICHEVER the sensor.

Criteria for SID :

For part of the track outside 30 NM from ARP;Whichever the sensor.

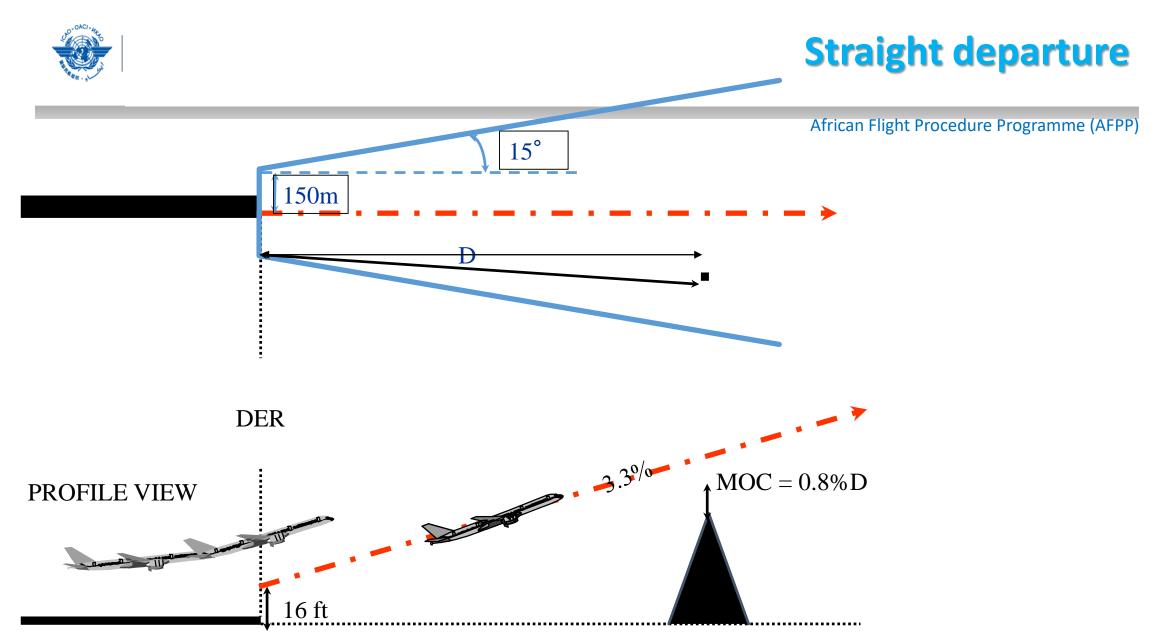
□ Merging Areas.





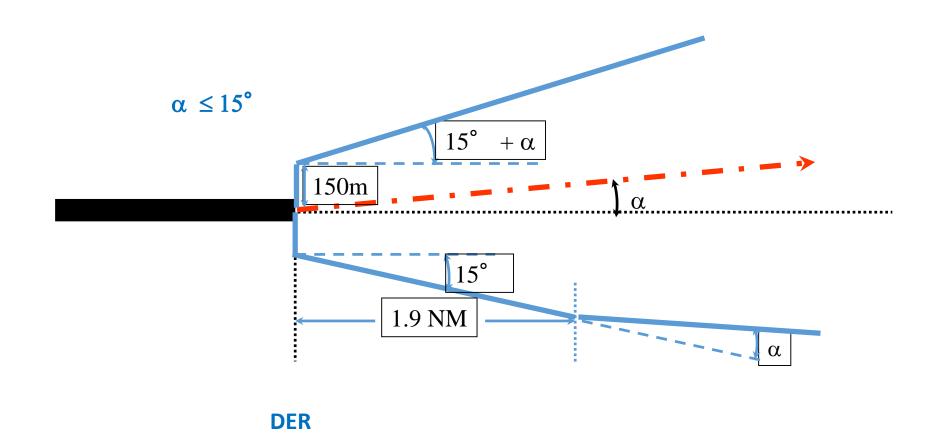
Two types of departures:

- Straight departure:
 - Initial track offset $\leq 15^{\circ}$.
- Turning departure:
 - Turn at an altitude;
 - Turn at a TP.

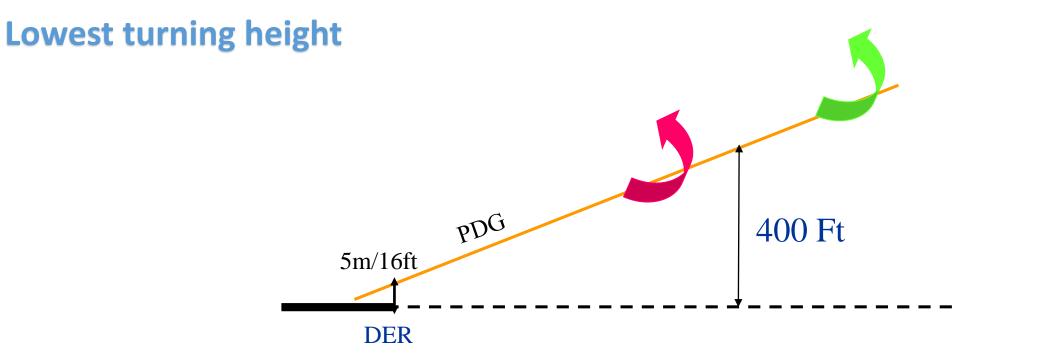


Straight departure









According to ICAO : NO TURN BELOW 400 FT / 120 m

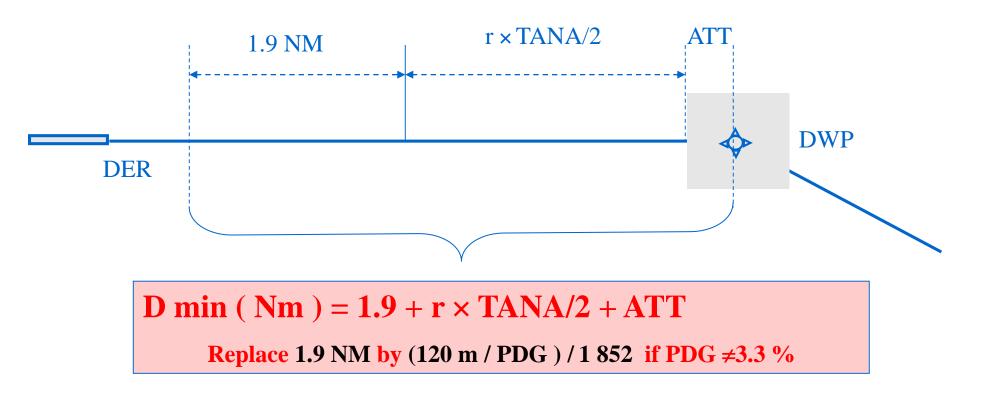
Operationally: NO TURN BELOW 500 FT



Turning departures

African Flight Procedure Programme (AFPP)

Turn at TP: minimum length with a FB waypoint

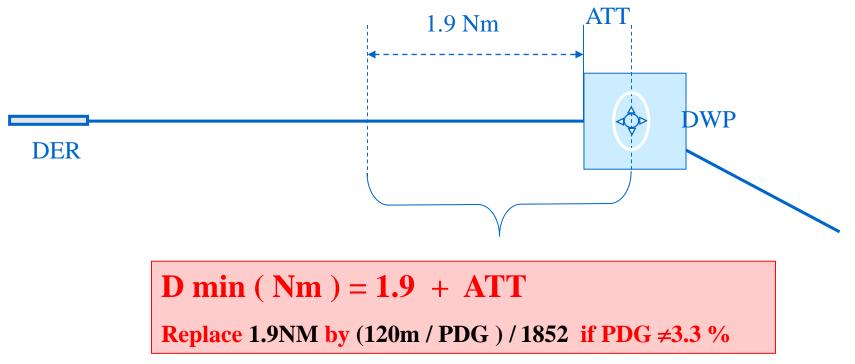




Turning departures

African Flight Procedure Programme (AFPP)

Turn at TP: minimum length with a FO waypoint





Design methodology

- According to airspace concept, select the appropriate navigation application (e.g. RNP1, RNAV1, RNAV 2);
- According to terrain constraint, noise abatement and operational issues, define the nominal path:
 - **For cat C and D aircraft use average flight path.**
- **Locate the first waypoint:**
 - The check minimum length of the first leg [DER-WP] according to the type of WP.
- **Draw the straight departure protection area;**
- □ Assess the obstacles (define OIS if needed) and deduce climb gradient.



Design methodology

African Flight Procedure Programme (AFPP)

Assess close obstacles after turn (validate climb gradient and turn;

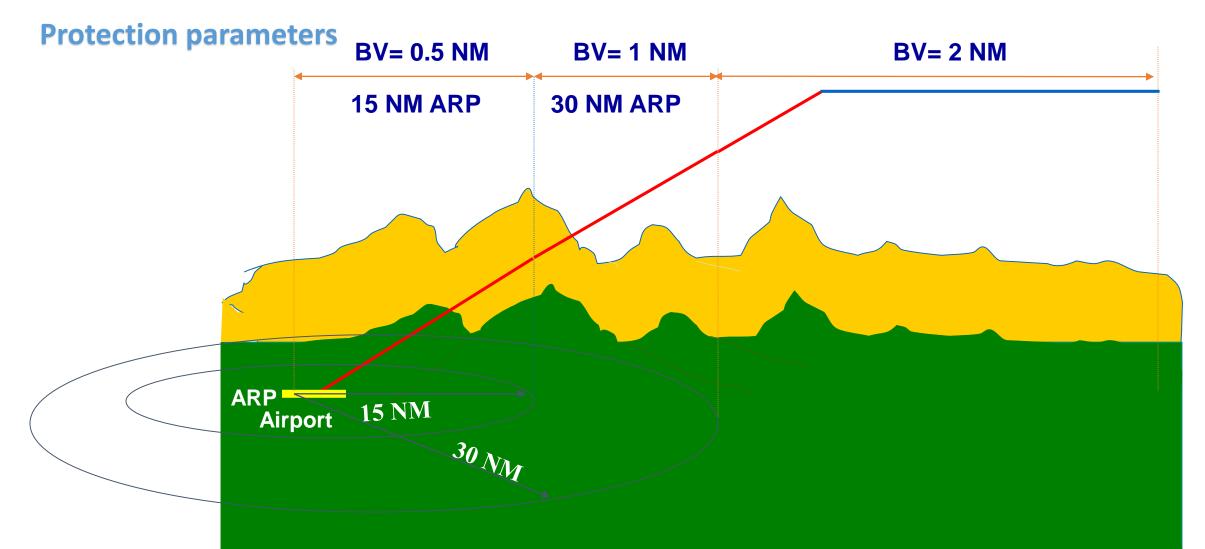
Draw the straight protection area of the next leg:
Check minimum length of the leg according to the type of WP.

Draw the turn protection area according to the type of WP and connect to the straight area;

Assess obstacles and validate climb gradient, altitude at WPs and connection to en-route structure.









Protection

African Flight Procedure Programme (AFPP)

Protection parameters

Phase of Flight	BV (NM) for CAT A-E	BV (NM) for CAT H
En-route : greater than 30 NM from departure ARP	2	1
Terminal within 30 NM of the ARP but more than 15 NM from ARP	1	0.7
SIDs within 15 NM of the ARP	0.5	0.35



Protection

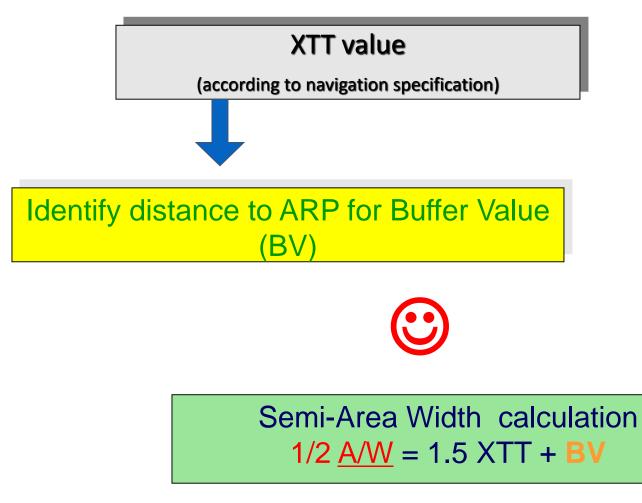
African Flight Procedure Programme (AFPP)

Protection parameters

Phase of Flight	FTE (95%) Specific to required navigation specification
En-route (GREATER THAN 56 km (30 NM) from ARP	RNAV 2 – 1.9 km (1 NM) RNAV 1 – 926 m (0.5 NM) RNP 2 – 1.9 km (1 NM) RNP 1 – 926 m (0.5 NM)
Terminal WITHIN 56 km (30 NM) of the ARP	RNAV 2 – 1.9 km (1 NM) RNAV 1 – 926 m (0.5 NM) RNP 1 – 926 m (0.5 NM)











Protection parameters (NM)

Navigati	on specification	RNP	FTE	IMAL	ATT	XTT	BV	^{1/2} AW
RNP 1	> 30 NM ARP	1	0.5		0.8	1	2	3.5
	Terminal	1	0.5		0.8	1	1	2.5
	SID <15 NM ARP	1	0.5		0.8	1	0.5	2
RNAV 2	> 30 NM ARP		1	2	1.6	2	2	5
	Terminal		1	1	0.8	1	1	2.5
	SID <15 NM ARP		1	1	0.8	1	0.5	2
RNAV 1	> 30 Nm ARP		0.5	2	1.6	2	2	5
	Terminal		0.5	1	0.8	1	1	2.5
	SID <15 NM ARP		0.5	1	0.8	1	0.5	2



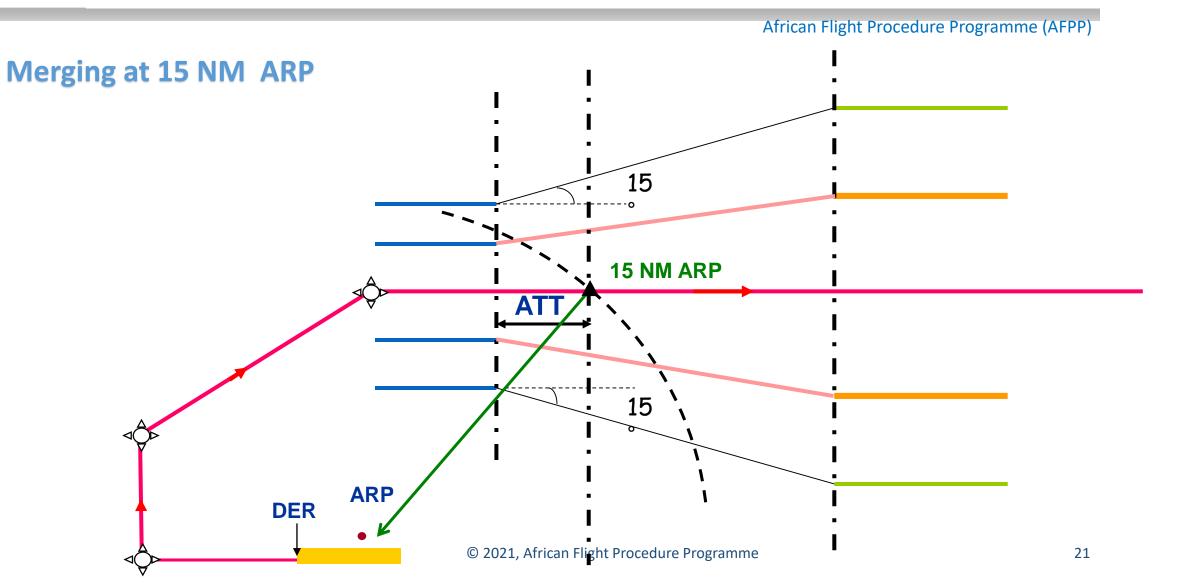


Merging methodology

- Area width of the subsequent segment is always equal or larger than the preceding one;
- **When larger : SPLAY with 15° from the EARLIEST ATT;**
- For RNP application and for RNAV application based on GNSS sensor, it occurs at 15 NM ARP and 30 NM ARP;
- Even if no waypoint is located at 15 NM DER, nor at 30 NM.

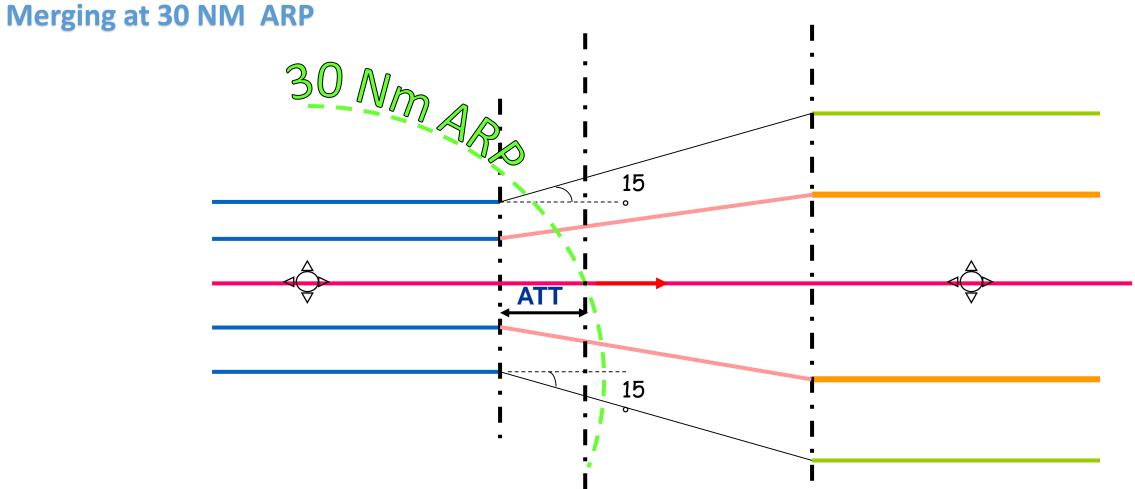








Protection







Merging at 15 & 30 NM ARP

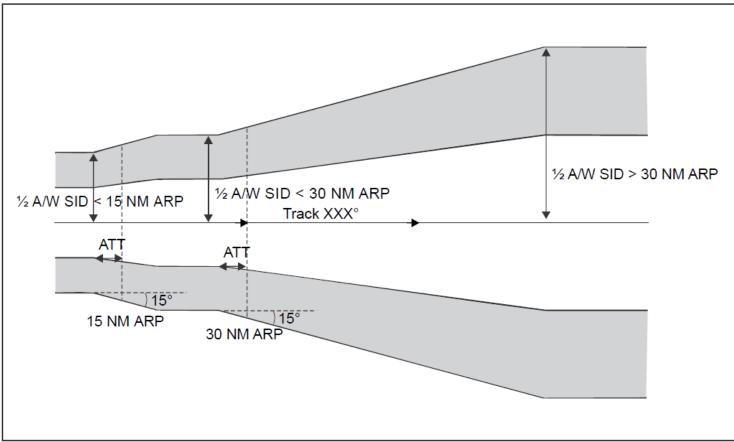


Figure III-1-1-3. Merging at phase-of-flight interfaces — departures





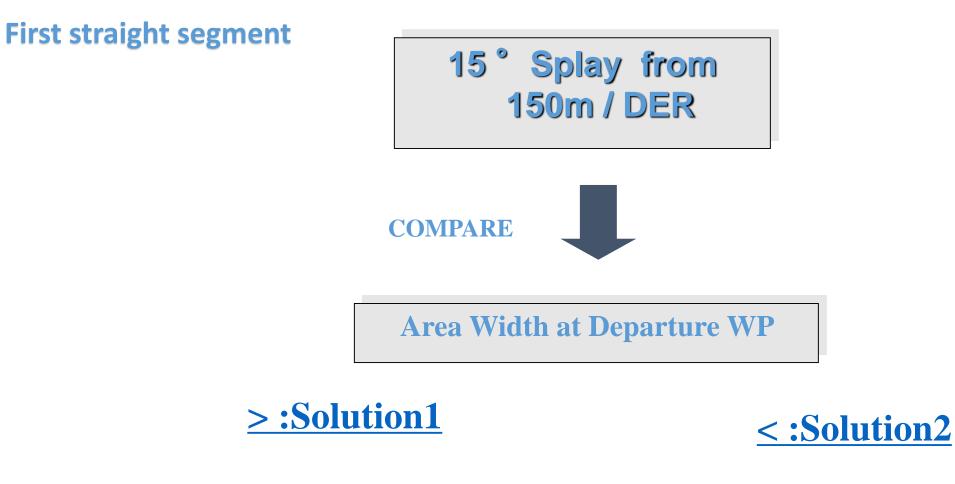
First straight segment

Find the value of ½ area width for the fictitious WP in the table part III section3 chapter 1 table III-3-1-1:
2 NM for RNP 1;
2 NM for RNAV 1;

Calculate XTT and ½ AW for the first WP;

Draw the straight segment area between the DER and the first WP.

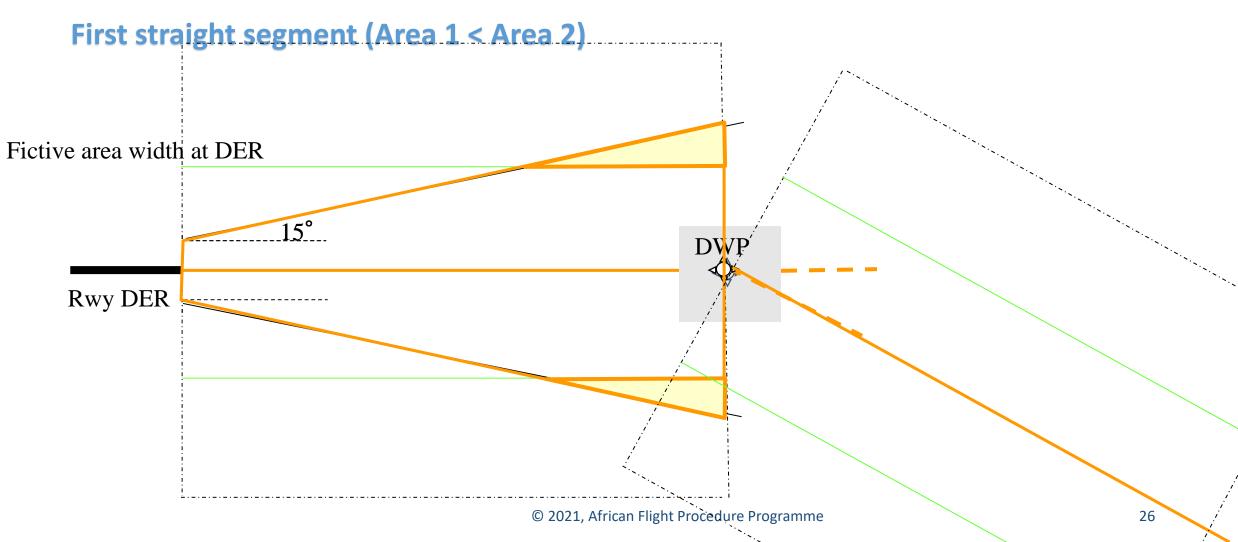








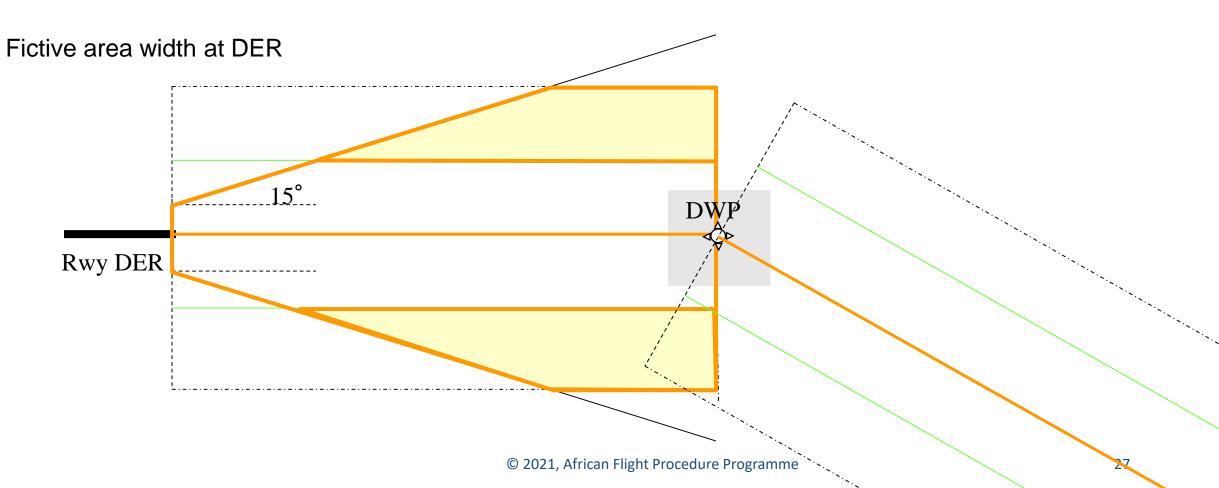






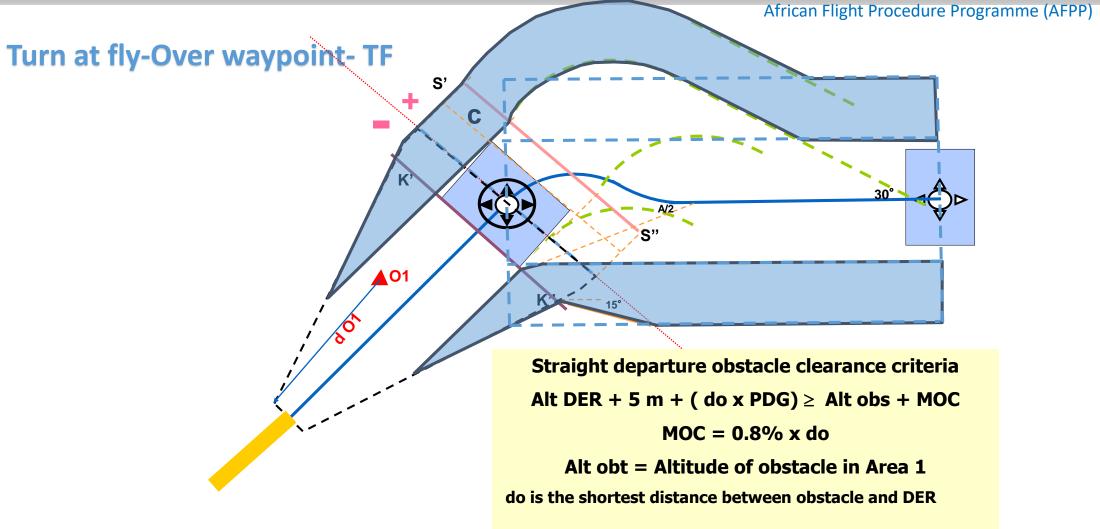


First straight segment (Area 1 > Area 2)



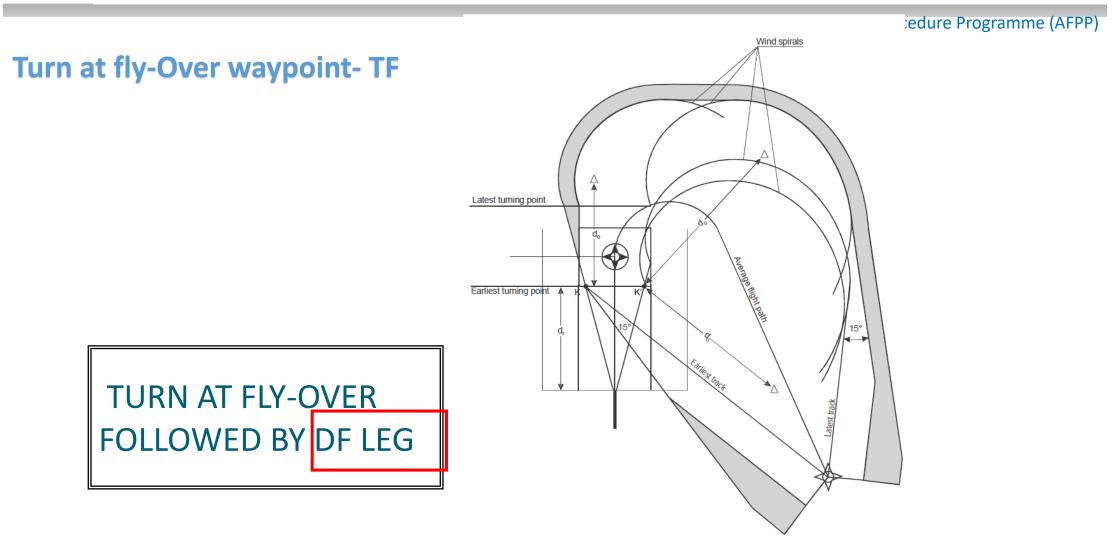








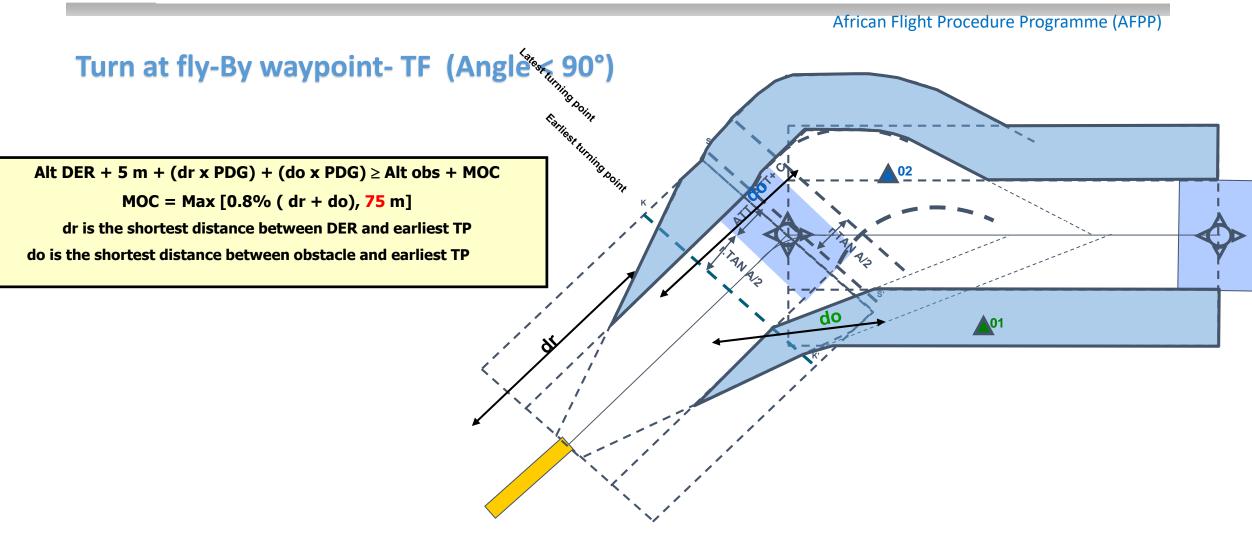




Protection

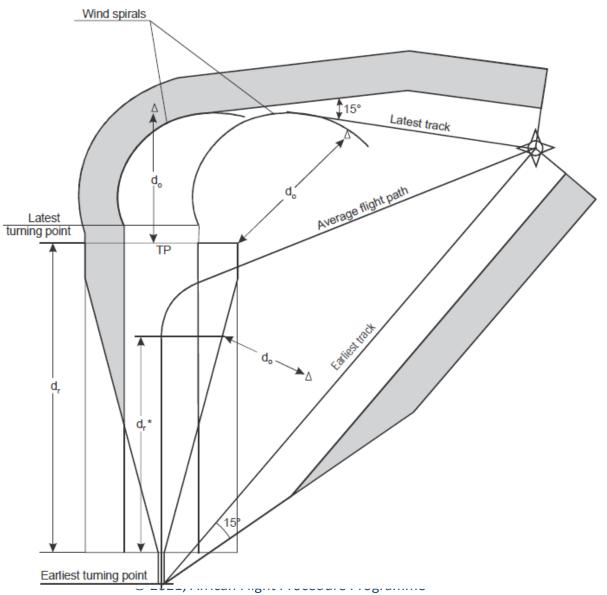








Turn at altitude with DF



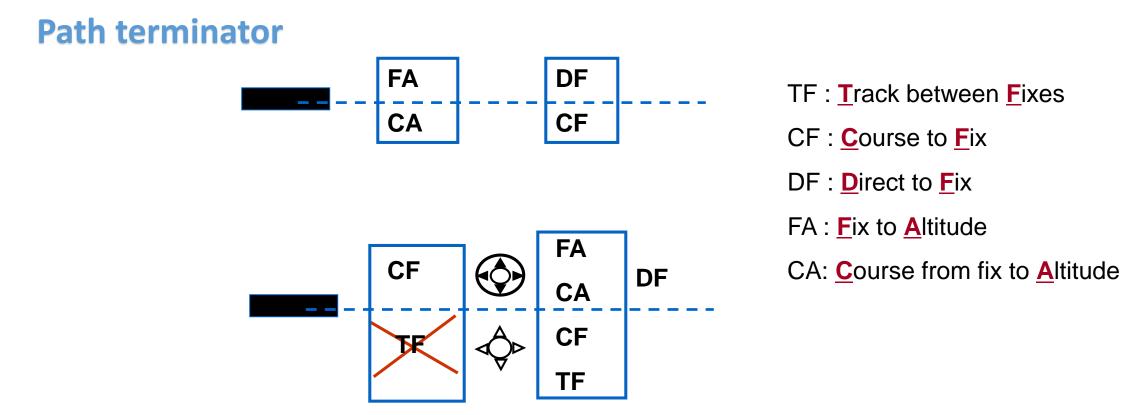
Protection

Programme (AFPP)



Protection

African Flight Procedure Programme (AFPP)



After the first WP, the standard sequencing rule is applicable

